

**UNIVAC
9200**

**SPECIAL CONTROL ROUTINES
ESCR**

SYS. S/N 2230

UNIT S/N _____

BOOK /
OF /

SPERRY RAND

UNIVAC
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**SERVICING
DOCUMENT
MANUAL INDEX**

MANUAL INDEX NO.

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SYSTEM NO. 92/9300		SERIAL NO. 2230	

MANUAL TITLE

SPECIAL CONTROL ROUTINES (ESCR)

9/4/69

CONTENTS

TAB DIVIDER NO.	SECTION INDEX TITLE	REQ'D.	TYPE NUMBER VARIATIONS	SD SECTION INDEX NUMBER		INDEX REVISION
				TYPE NO.	IND. VAR.	
1	Scope, Applicable Documents & Routines	X	All	Document SHO4479	Sec. 1	
2	Preset Locations - Halt Display Stops-Address Assignments	X	All	"	Sec. 2	See Above
3	Input/Out Control	X	All	"	Sec. 3	"
4	Selector Channel Control	X	All	"	Sec. 4	"
5	Internal Card Reader Control	X	All	"	Sec. 5	"
6	Internal Card Punch Control	X	All	"	Sec. 6	"
7	Internal Printer Control	X	All	"	Sec. 7	"
8	Disc File Control (8410)	X	All	"	Sec. 8	"
9	Row Punch Subsystem	X	All	"	Sec. 9	"
10	Card Controller	X	All	"	Sec.10	"
11	Uniservo Control - VIC	X	All	"	Sec.11	"
12	ICCU Control	X	All	"	Sec.12	"
13	Drum Printer & Control	X	All	"	Sec.13	"
14	Perforated Tape Subsystem	X	All	"	Sec.14	"
15	Data Communications Subsystem	X	All	"	Sec.15	"
16	Uniservo Control Unit (5017)	X	All	"	Sec.16	"
17	Disc File Control (5024)	X	All	"	Sec.17	"
18	Reader and Control	X	All	"	Sec.18	"
19	Code Edit (ESCR)	X	All	Document 3841246-00		

TITLE

NCF 9200 and/or 9300 INPUT/OUTPUT
Special Control Routine
ESCR

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SHEET INDEX

SHEET	1-1a	1-1b	1-1c	1-1d	1-2	1-3	1-4	1-5	1-6	1-7	1-8	1-9	1-10	1-11
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—
SHEET	1-12	1-13	1-14	1-15	1-16	1-17	1-18	2-1	2-2	2-3	2-4	2-5	2-6	2-7
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—
SHEET	2-8	3-1	3-2	3-3	3-4	3-5	3-6	4-1	4-2	4-3	5-1	5-2	6-1	6-2
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—

THE AUTHORIZED ISSUE OF THIS SPECIFICATION CONSISTS OF THE SHEET REVISIONS SHOWN IN THE SHEET INDEX SECTION ON THE LATEST ISSUE OF THIS APPROVAL SHEET. ("—" IN REVISION SPACE DENOTES ORIGINAL ISSUE)

ORIGINAL ISSUE				MONTH	DAY	YEAR	UNIVAC
WRITTEN BY	<i>B. M. Archer</i> B. M. Archer	11	5	68	SPECIFICATION TYPE		
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APPROVAL	A. A. Pizzirani <i>AA Pizzirani</i>	12	12	68			
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SHEET INDEX

SHEET	6-3	7-1	7-2	7-3	7-4	8-1	8-2	8-3	8-4	8-5	8-6	8-7	8-8	8-9
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—
SHEET	9-1	9-2	9-3	9-4	9-5	9-6	10-1	10-2	10-3	10-4	10-5	11-1	11-2	11-3
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—
SHEET	11-4	11-5	11-6	11-7	11-8	11-9	11-10	11-11	11-12	11-13	11-14	11-15	11-16	11-17
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—

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SHEET INDEX

SHEET	11-18	12-1	12-2	12-3	12-4	12-5	13-1	13-2	13-3	13-4	13-5	13-6	13-7	14-1
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—
SHEET	14-2	14-3	14-4	15-1	15-2	15-3	15-4	15-5	15-6	15-7	15-8	15-9	15-10	15-11
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—
SHEET	16-1	16-2	16-3	16-4	16-5	16-6	16-7	16-8	16-9	16-10	16-11	16-12	16-13	16-14
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—

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SHEET INDEX

SHEET	16-15	16-16	16-17	16-18	16-19	16-20	16-21	16-22	16-23	16-24	16-25	17-1	17-2	17-3
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—

SHEET	17-4	17-5	17-6	17-7	17-8	17-9	17-10	17-11	17-12	17-13	17-14	17-15	17-16	17-17
REV.	—	—	—	—	—	—	—	—	—	—	—	—	—	—

SHEET	17-18	17-19	17-20	18-1	18-2	18-3	18-4	18-5	18-6	19				
REV.	—	—	—	—	—	—	—	—	—	—				

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SPECIFICATION SYMBOL SH04479

CONTENTS

<u>PARAGRAPH</u>	<u>TITLE</u>	<u>SECTION</u>	<u>SHEET</u>
1.	Scope	1	1-1
2.	Applicable Documents	1	1-1
3.	Routine ESCR	1	1-4
3.1	Purpose	1	1-4
3.2	Equipment Configuration Requirements	1	1-5
3.3	Description	1	1-5
3.4	Operating Instructions	1	1-10
3.5	Printed Messages	1	1-16
3.6	Program Stops	1	1-18
Table I	Preset Locations	2	2-1
Table II	Halt-Display Stops	2	2-2
Table III	9200/9300 Device Address Assignments	2	2-7
Appendix I	Reference Documentation For Controlling Specific 9200/9300 Input/Output Devices		
	Multiplexer Channel	3	3-1
	Selector Channel	4	4-1
	Internal Card Reader Control	5	5-1
	Internal Card Punch Control	6	6-1
	Internal Printer Control	7	7-1
	8410 Disc File Control	8	8-1
	9000 Series Row Punch	9	9-1
	9000 Series 1001 Card Controller	10	20-1
	6-C Control Unit No. 0858	11	11-1
	ICCU 418/1108-9300	12	12-1
	9000 Series 900/1000 LPM Drum Printer	13	13-1
	9000 Series Punch Paper Tape	14	14-1
	DCS1, 4 Data Communications Subsystems	15	15-1
	Uniservo 12/16 Control Unit No. 5017	16	16-1
	Disc File Control No. 5024	17	17-1
	9000 Series 600 CPM Reader	18	18-1

1. SCOPE

ESCR is a generalized, input/output control routine designed to minimize and facilitate the operations necessary to issue commands to any kind of device on the multiplexer and/or selector channels of NCF 9200 and 9300 computer systems. Subsequent termination status indications are analyzed for successful completion and error situations are indicated by coded halt-displays and optionally selected printouts of pertinent control information.

The controls necessary to run ESCR are simplified so that even relatively inexperienced personnel can use it. However, expandability features provide program controls limited only by the software experience of the user and memory restrictions.

2. APPLICABLE DOCUMENTS

- | | | |
|------|---|---|
| 2.1. | Computer and channel product descriptions | |
| | P.D. P-10044, Rev. D | 9200 System |
| | P.D. P-10055, Rev. B | 9300 System |
| | S.U. 00039 | 9000 Series I/O Interface, 8-bit Compatible |
| 2.2 | Readers | |
| | C.S. 1955 | Card Readers, Internal |
| | P.D. P-10072 | 600 CPM Reader and Control Unit |
| | P.D. P-10078 | 1000 CPM Reader and Control Unit |
| | P.D. P-10050 | 1001 Card Controller |
| 2.3 | Printers | |
| | P.D. P-20077 | Bar Printer Family |
| | P.D. P-10066 | 900/1100 LPM Drum Printer and Control Unit |
| 2.4 | Punches | |
| | P.D. P-20066 | Standard 75 CPM Punch |
| | P.D. P-10056 | 9000 Series Row Punch |
| 2.5 | Tapes | |
| | P.D. P-10052 | 9000 Series 6-C Subsystem |
| | P.D. P-10054 | U12/U16 Magnetic Tape Subsystem |
| | P.D. P-20041 | Uniservo 6-C |
| | P.D. P-20040 | Uniservo 8-C |
| | P.D. P-20102 | Uniservo 12 |
| | P.D. P-20103 | Uniservo 16 |
| 2.6 | Discs | |
| | P.D. P-10068 | 8410 Disc File Control Unit |
| | P.D. P-20112 | 8410 Disc File |
| | P.D. P-10076 | 5024 Disc File Control Unit |
| | P.D. P-21108 | 5024 Disc File |

2.7 Punch Paper Tape
P.D. P-22128 9000 Series Punch Paper Tape Subsystem

2.8 Data Communications
S 90037 DCS 1,4 Data Communications Subsystems
SA 00798 DCS 1,4 Data Communications Subsystems

2.9 Other Devices
P.D. P-10073 ICCU

3. ROUTINE ESCR

3.1 Purpose

3.1.1 On-line input/output subsystem checkout requires software facilities to handle the following general hardware considerations.

A. Both Multiplexer and Selector Channel controls and data transfer rates.

B. "Test-facility" features, such as

device simulation

monitor mode

data-turn-around test mode

C. Control Unit and/or Device optional hardware features providing selection of

recording methods

recording densities

odd and even parity generation

data conversion

data translation

D. A convenient method for data generation.

E. Any arbitrary command selection and handling of associated termination status indications.

F. An optional command selection sequence to be used when errors are detected and a "repositioning" of the device is necessary.

G. No interrupt, one interrupt, two interrupt and "unsolicited" interrupt situations.

H. Command chaining.

3.1.2 The purpose of this control routine is to easily and conveniently provide these requirements. To simplify the operating procedures, as much automatic control was built into the routine as possible.

3.2 Equipment Configuration Requirements

The primary equipment requirements for Routine ESCR are

- A. Central Processor, 9200 or 9300 16K, or larger, memory size, for normal operation, 8K requires address changes outlined in Operating Instructions, Section 3.4.
- B. General Purpose Channel, Feature SH03602
or
Dual Input-Output Channel, Feature F1104
- C. 80 Column Card Reader or 1001 Card Controller for loading the object deck.
- D. High Speed Printer (Internal), Feature F0864
132 print positions, 63 characters
- printouts are optionally selected, so this device is required only when printing is desired.

Table III lists the input-output devices which can be operated by using Routine ESCR.

3.3 Description

3.3.1 Routine ESCR executes in consecutive order, three arbitrarily selected commands, referred to hereafter as C1, C2, and C3. These commands will be issued to three optionally selected device addresses, DA1, DA2, and DA3, such that C1 will be issued to DA1, C2 to DA2, and C3 to DA3. The three device addresses may refer to the same or different devices, in any combination, using either or both types of channels.

3.3.1.2 If using a dual channel configuration, the routine will automatically detect selector channel device addresses and load the corresponding selector channel address word (CAW) into locations 78 and 79₍₁₆₎. This address points to the location of the selector channel command word (CCW). If multiplexing, the address of the first byte of the four-byte buffer control word for the corresponding DA must be indicated.

Refer to Appendix I for detailed descriptions of selector and multiplexor channel control words; device commands, status, and sense indicators; and general operating procedures for controlling input-output devices.

- 3.3.2 The selector channel control words (CCW1, CCW2, CCW3) and the multiplexer channel buffer control words (BCW1, BCW2, BCW3) can be arbitrarily set by the operator and must conform to the requirements dictated by the associated command, the device, and the memory configuration limits of the CPU, if data transfers are involved.
- 3.3.3 All error and control locations in memory are preset to specific values before the execution of each of the three commands, to facilitate manual verification of changes. These preset locations are itemized in Table I.
- 3.3.4 After each of the three commands are initially executed, a halt-display of the following format occurs:
- OOCX(16)
- where X = 1, 2, or 3 — the command number.
- These halts are bypassed on all successive execution cycles of the three commands, and their basic purpose is to allow manual verification of termination indications. A secondary purpose of the halt and reset-halt instructions is to provide memory space for "operator key-ins". These key-ins could transfer to "operator subroutines" which would perform specific testing functions or data comparison functions on the data associated with the command just terminated.
- 3.3.5 All errors on command execution detected by ESCR result in a halt-display (of the address of the halt-display instruction itself), followed by two branch (47) instructions. The first branch goes to the "general recovery" procedure set up for that halt and the second is designated as a "recovery switch".
- 3.3.5.1 The address displayed by the error halt instruction performs two functions.
1. If continuous operation is desired, all error-halts are easily ignored by one general procedure. Set up in the address switches of the control console the error-displayed address, display the contents of this address to verify the A9 operation code of the halt instruction*, and manually alter the A9 to a 47 (no-operation, branch conditional instruction). No reference to write-ups or codedits is necessary.
 2. On initial use of the routine, this displayed address should be used to reference the codedit location of the halt-display instruction or Table II, where explanations for the halts are given and recovery procedures indicated. Since error checking is generalized, the number of error stops is small. Thus, error address displays and meanings usually are readily memorized.
- 3.3.5.2 The error halt instruction plus the two branch conditional instructions following it may be used for "operator-keyed" recovery procedures or tests. If this is not done, the first branch conditional transfers control to a subroutine which resets the program controls necessary to proceed with the execution of

*This display step may be omitted.

the next command. If the error halt is bypassed, continuous operation is accomplished and scoping facilitated.

3.3.5.3 In addition to the normal halt-displays on error, a printout of pertinent information concerning the command-in-error termination status can be obtained by selecting an option bit.

It is also possible to optionally select printouts of this same information after successful completion of each command. Selection of both options results in printing the same relevant information for both successful completion and error termination of the commands. Thus, a "hard copy" of the command sequence and termination indications is available. (Refer to Operating Instructions, Section 3.4).

The formats for printouts are given in Section 3.5 along with explanations of the heading abbreviations and fields.

3.3.6 The detection of unsuccessful completion of a command is made by the following comparisons:

3.3.6.1 CASE 1 XIOF issued in Processor Mode with command termination signaled by interrupts.

Type 1 One interrupt per command accepted (CC = 00)

The contents of locations 40, 41, 42, 43₍₁₆₎ are compared to the following hexadecimal values:

CPU INTERRUPT INDICATORS*				Channel Type	Device Type
40	41	42	43		
FF	FF	00/04	DA	Multiplexor	Internal
FF	FF	0C	DA	Multiplexor	External
DA	SS	0C	DA	Selector	External

Type 2 Two interrupts per command accepted (CC = 00)

The contents of locations 40, 41, 42, 43₍₁₆₎ are compared after each interrupt, as indicated,

	CPU INTERRUPT INDICATORS*				Channel Type	Device Type
	40	41	42	43		
Interrupt 1	FF	FF	08	DA	Multiplexor Selector	External External
	DA	SS	08	DA		
Interrupt 2	FF	FF	04	DA	Multiplexor Selector	External External
	DA	SS	04	DA		

3.3.6.2 CASE 2 XIOF issued in Input/Output Mode with command termination determined by TIO instructions.

Type 1 One end-status presentation per command accepted (CC = 00)

The contents of the end-status stored by the TIO instruction is compared to the expected value, as indicated.

TAG DS CONTENTS OF LOCATION 08CA*	CHANNEL TYPE	DEVICE TYPE
00/04	Multiplexer	Internal
OC	Multiplexer	External
OC	Selector	External

Type 2 Two end status presentations per command accepted (CC = 00)

The contents of the end-status stored by each of two TIO instructions is compared, as indicated,

	TAG DS CONTENTS OF LOCATION 08CA*	TAG DS + 1 CONTENTS OF LOCATION 08CB*	CHANNEL TYPE	DEVICE TYPE
TIO1	08 08	-- --	Multiplexer Selector	External External
TIO2	-- --	04 04	Multiplexer Selector	External External

*Indicator definitions (hexadecimal)

FF = Preset value

00/04 = Successful completion status for internal devices only

OC = CHANNEL END, DEVICE END

Successful completion status for external devices

DA = Device Address

SS = Selector Channel Error Indicators. Compared to 00 for no error.

08 = CHANNEL END status

04 = DEVICE END status

3.3.7 Routine ESCR expects interrupts for each XIOF issued in processor mode that has set the respective condition code to an acceptance state (CC = 00). On interrupt, end-status is tested for the ATTENTION bit, if successful completion status has not been received. If set, an unsolicited interrupt printout occurs and any outstanding expected interrupts associated with the XIOF will still be anticipated.

- 3.3.7.1 All other interrupts for which the processor mode PSCW indicates an address range outside of that defined by the XIOF and its associated BC instructions are considered as unsolicited, regardless of the contents of the stored status. This includes the so-called "soft-interrupt" which is generated on certain devices to indicate that a command has been issued to the device when it is in a "stop" state. The command itself is rejected and an associated interrupt generated which serves the purpose of alerting the processor to the rejection. The command-rejection-halt must be followed by hitting START to allow the "soft-interrupt" to be accepted by the processor.
- 3.3.7.2 When operating in I-O mode, in order to accept status presented by devices not addressed in the TIO instructions (considered unsolicited status), the following procedures may be taken. When the command-rejection-halt occurs because the Control Unit is in a pending status state, set the recovery branch conditional to address 0666 where an LPSC sets up the I-O PSCW to analyze interrupts and gives control to processor mode for one instruction time.
- 3.3.7.3 If loading ESCR from cards, unsolicited interrupts are handled if they occur after the first instruction (LPSC) within ESCR is executed. If initial loading from tape, the interrupt generated by the operator-initial-loading is indicated as unsolicited, as well as all interrupts which are not routine initiated by the acceptance of an XIOF instruction (CC = 00).
- 3.3.8 The number of end-status indications expected by ESCR is determined by testing a mask constant against the command byte of the accepted XIOF just issued. If this test mask sets CC = 11, two end-status states will be anticipated, CHANNEL END alone, followed by DEVICE END alone. Otherwise, one end-status indication of CHANNEL END and DEVICE END is expected.
- 3.3.8.1 Three mask constants must be set (TM1, TM2, and TM3) such that TM1 relates to C1, TM2 to C2, and TM3 to C3. If C1, C2, and C3 are all associated with the same device, the 3 test masks should have identical values based upon the Control Unit logic which makes this same determination in the hardware. For most purposes, mask bytes set to 07 are sufficient for designating "control-type" commands resulting in two end-status conditions.
- 3.3.9 Two data generators are optionally selectable in ESCR. The first is based on the need for a relatively small amount of data and is selected by designating bit 6 of the option selection byte. Eight bytes of data pattern are set in location 0230 → 0237, tagged DATA, at the initial-load halt-display of 00EE. Before any commands are executed, this 8-byte data pattern is repeated for a total of 256 bytes in each of the 3 normal data areas beginning at locations 1000, 2000, and 3000₍₁₆₎. These data patterns will remain set until GENERAL CLEAR, START reinitializes the routine. If the patterns in DATA are changed after GENERAL CLEAR, the new data pattern will be generated on START.
- 3.3.9.1 The second data pattern generator is based upon the need for large amounts of data generation and has a basic 16-byte repeat cycle. Bits 6 and 4 of the option selection byte must be set to designate this data generator. A 16-byte data pattern is entered in locations 0230 → 23F. This pattern is repeated for a total of 8192 bytes beginning in data area 1000 before C1 is executed and will not be regenerated until GENERAL CLEAR, START reinitializes the beginning of the routine, at which time it can be altered.

3.4 Operating Instructions

3.4.1 Load Procedures

3.4.1.1 Card Deck Versions

Initial-load routine by placing the standard 4-card loaders in front of the object deck and following normal card load procedures. Halt-display OOEE indicates successful loading of deck.

3.4.1.2 Tape Version

Three identical blocks (Blocks 2, 3, and 4) containing 4000₍₁₀₎ bytes of object coded data for ESCR are written (800 BPI density, NRZI recording mode) after the first locator block (Block 1) or each 9300 Test Program Master Tape. If Block 2 cannot be loaded without error, loading of Blocks 3 or 4 can be attempted or a second tape servo utilized.

Step 0: Set Control Unit to On-Line State

Step 1: Mount Master Tape.

Step 2: Set Device Address of servo in data entry switches.

Step 3: Set LOAD switch to ON position.

Step 4: GENERAL CLEAR, START loads Block 1. Repeat Step 4 once. Block 2 is loaded.

Step 5: Successful load is verified by no light bit for the UNIT CHECK indicator in the Control Unit.

Step 6: If Block 2 is loaded without error, Reset Load switch. START* or GENERAL CLEAR, START results in OOEE display.

*If GENERAL CLEAR does not clear the pending initial load interrupt, an unsolicited printout will give the pertinent information associated with this interrupt.

Step 7: If block loaded is in error, repeat Steps 3 and 4 until the 3rd or 4th block is read successfully.

Step 8: If Step 7 fails, repeat Steps 1→7 on a different servo.

3.4.1.3 Operation

The uses of this routine are determined by the operator and it is to be considered a software tool. To encompass the wide variety of hardware and software experience of users, a set of examples follow which illustrate basic operational characteristics. Following the examples, is a detailed and comprehensive reference for users extending the routine to their own particular needs, the Option Parameter Chart.

- 3.4.1.3.1 This program executes three XIOF instructions and handles all contingencies of status and sense. It provides a printout of each one at its successful or unsuccessful completions. The operators basic responsibility is to supply Device Address, Commands to be executed, addresses and contents of Buffer Control Words and/or Channel Command Words.
- 3.4.1.3.2 The data needed for these key-ins (locations 01FC → 0204 and 0206 → 023F) is found in Sections 2. to 18. Location 0205 is the Option Selection Byte. The contents of locations 0206 - 0211 is Buffer Control Word information which is dependent on the associated I-O command. If the machine used does not have all the devices called out in the examples, substitutions should be made to accommodate the configuration, as long as rules for that device are followed.
- 3.4.1.3.3 A quick method to try the routine would be to run one device only. All three Commands must be used since the program executes all three. In the case of one device only, the same starting BCW address should be keyed-in to 01FC, 01FD, 01FE; the same Device Address into 01FF, 0200, 0201; the three commands in 0202, 0203, 0204 and the associated BCW's in 0206 → 9, 020A → D, 020E → 0211. Each of the three XIOF's will be executed; therefore, it is very important that some valid command to some valid device be designated.

EXAMPLE OPERATION 1Purpose: Read a card thru on-line reader, print on bar printer and reproduce card on serial punch.

Loc.	Data	Reason
01FC	44	Starting address of reader BCW (BCW for XIOF ₁)
01FD	50	Starting address of bar printer BCW (BCW for XIOF ₂)
01FE	4C	Starting address of serial punch BCW (BCW for XIOF ₃)
01FF	01	Readers device address (DA for XIOF ₁)
0200	03	Printers device address (DA for XIOF ₂)
0201	02	Punch device address (DA for XIOF ₃)
0202	02	Reader Command (Read) (XF for XIOF ₁)
0203	01	Printer Command (Print & Space) (XF for XIOF ₂)
0204	01	Punch Command (Punch) (XF for XIOF ₃)

OPTION BYTE

0205	44	Stop before XIOF (Bit 1) Print on error (Bit 5) (See OPT for other options possible)
0206-9	00500080	BCW data for reader (load 80-col. into mem. beginning at loc. 80).
020A-D	01XXXXXX	BCW data for printer (mem. loc. 50 is the only one loadable -- for line space).
020E-11	00500080	BCW data for punch (punch 80-col. from mem. loc. 0080).

These are the only data insertions necessary for the above purpose.

3.4.1.3.3 continued . . .

EXAMPLE: OPERATION 2Purpose: Read card from reader put it on tape and punch it on row punch

<u>LOC.</u>	<u>DATA</u>	<u>REASON</u>
01FC	44	Starting address of reader BCW (BCW for XIOF ₁)
01FD	60	Starting Address of channel 8's tape BCW (BCW for XIOF ₂)
01FE	58	Starting address of row punch (BCW for XIOF ₃)
01FF	01	Reader device address (DA for XIOF ₁)
0200	C0	Channel 8 device address tape 0 (DA for XIOF ₂)
0201	06	Row punch device address (DA for XIOF ₃)
0202	02	Reader command (Read -- XF for XIOF ₁)
0203	01	Tape command (Write -- XF for XIOF ₂)
0204	11	Row punch command (punch & feed - XF for XIOF ₃)

OPTION BYTE

0205	C5	Set NRZI (Bit 0) - Sense & Monitor bits edited & printed out Stop before XIOF (Bit 1) Print on error (Bit 5) Print on successful term (Bit 7) (see OPT for other options possible).
0206-9	05001000	BCW data for reader (load 80-col. into memory beginning at loc. 1000)
020A-D	80501000	BCW data for tape (write 80 bytes on tape from memory beginning at loc. 1000).
020E-11	80501000	BCW data for punch (punch 80 bytes on row punch from memory beginning at loc. 1000)

Special changes needed for this example because of peripheral mode of operation.

0339	03	A valid mode set command for VIC tape which is needed to execute bit 0 of 0205 option byte (see sec. 11 for further definition)
01FB	11	Change test mask formate to accommodate row punches interrupt seq. where channel end and device end are returned separate (see for further definition)

3.4.2 Option Selection and Parameter Entry

After OOE display, set option selection byte and control parameters as indicated. START initializes routine. (Superscripts refer to notes at end of this chart).

ADDRESS*	TAG REFERENCE	PRESET CONTENTS*	DESCRIPTION
01F9 ⁽¹⁾	TM1	07	Test Mask constant for determining if CX, if accepted, will initiate 2 end-status presentations. X = 1
01FA ⁽¹⁾	TM2	07	Same as TM1 except X = 2.
01FB ⁽¹⁾	TM3	07	Same as TM1 except X = 3.
01FC ^(2,3,4,5)	MBC1**	70	Address of <u>first</u> byte of the 4-byte buffer control word area for CX, DAX. X = 1.
01FD ^(2,3,4,5)	MBC2**	70	Same as MBC1 except X = 2.
01FE ^(2,3,4,5)	MBC3**	70	Same as MBC1 except X = 3.
01FF	DA00**	E0	Device Address for C1
0200	DA01**	E0	Device Address for C2
0201	DA02**	E0	Device Address for C3
0202	C123	01	Command 1 (C1) - Standard Write
0203	C123	27	Command 2 (C2) - Standard Control (Backspace block)
0204	C123	02	Command 3 (C3) - Standard read
0205	OPT	00	Option Selection Byte
Bit 0 ^(6,7)		0	Do not execute MODE SET 2 command at routine initialization before C1
		1	Execute this MODE SET 2 command.
Bit 1		0	Do not HALT-DISPLAY before XIOF execution.
		1	HALT-DISPLAY before XIOF execution to enable cycling.
Bit 2		0	Execute XIOF in Processor Mode. Do not stack status.
		1	Execute XIOF in Input/Output Mode. Stack status.
Bit 3 ^(6,7)		0	Do not execute MODE SET 1 command at routine initialization before C1.
		1	Execute MODE SET 1 command.
Bit 4 ⁽⁸⁾		0	Execute C1, C2, and C3 sequentially.
		1	Execute C1. Execute C2 & C3 only on error.
Bit 5		0	Do not print on error.
		1	Print on error.
Bit 6		0	Do not utilize 256 byte data generator
		1	Utilize 256 byte data generator if bit 4 is not set.
			Utilize 8192 data generator if bit 4 is set.

3.4.2 continued . . .

ADDRESS*	TAG REFERENCE	PRESET CONTENTS*	DESCRIPTION
continued ... 0205 Bit 7	OPT	0 1	Do not print on successful XIOF termination. Print on successful termination.
0206 → 0209 ⁽⁹⁾	BCW1***	80401000	Buffer Control Word (BCW1) for C1, DA1
020A → 020D ^(9,10)	BCW2***	80402000	Buffer Control Word (BCW2) for C2, DA2
020E → 0211 ^(9,10)	BCW3***	00403000	Buffer Control Word (BCW3) for C3, DA3
0212, 0213 ^(1,11,12)	CCW1 ⁺	021A	Selector Channel Address Word pointer for C1
0214, 0215 ^(1,11,12)	CCW2 ⁺	0222	Selector Channel Address Word pointer for C2
0216, 0217 ^(1,11,12)	CCW3 ⁺	022A	Selector Channel Address Word pointer for C3
0218 → 021F ^(1,12,13)	CW1 ⁺	01001000 10000040	Selector Channel Command Word for C1, DA1
0220 → 0227 ^(1,10,12,13)	CW2 ⁺	01002000 10000040	Selector Channel Command Word for C2, DA2
0228 → 022F ^(1,10,12)	CW3 ⁺	01003000 10000040	Selector Channel Command Word for C3, DA3
0230 → 023F ^(14,15)	DATA	--	Area for Data Patterns

*Value is designated in hexadecimal
 **Reference - Table III - Section 2
 ***Reference - Section 3
 +Reference - Section 4

- Note 1) This parameter is not set if the associated device address is for an internal device. The constant 07 is sufficient for most control units for external devices. However, exceptions exist and this constant should be changed accordingly. Refer to Section 1, paragraph 3.3.8.
- Note 2) These bytes are not set for Selector Channel devices.
- Note 3) For communications devices utilizing buffer control word areas beginning in address 0200, this byte should refer to the least significant byte of the first address of the 4-byte BCW area. In addition, the MVC instruction byte for the corresponding command should be changed as follows:

COMMAND	ADDRESS	INITIAL VALUE	CHANGE TO
C1	04C4	00	02
C2	04D4	00	02
C3	04E4	00	02

3.4.2 continued . . .

- Note 4) For internal devices where only 1 byte of the BCW is actually used, only this byte of the BCW need be designated in BCWX (X=1,2, or 3) but all 4 bytes will be moved to the area designated by this address.
- Note 5) For a single Multiplexor Channel system, BCW addresses 0078 and 007C require location 03A5 to be changed from 7A to 80. On dual channel configurations, these addresses are restricted to selector devices only and are preset by ESCR to the Selector Channel Address Word.
- Note 6) MODE SET 1 command byte is located in 030F preset to 4B.
MODE SET 2 command byte is located in 0339 preset to CB.
For tape control units 0858 and 5017, command byte 4B sets device simulation mode and command byte CB sets 800 BPI, 9-track, NRZI (5017 only) recording mode. If printing options in location 0205 and tapes are designated by DAX (X=1,2, or 3) being set to C0→CF, E0→EF or 60→6F SENSE and MONITOR SENSE modes are automatically handled to obtain sense data. MODE SET 1 will also be reissued to set Device Simulation Mode which gets reset by the MONITOR MODE operations. For external devices other than tapes, only a SENSE command is issued to obtain sense data. For internal devices, no sense data is available.
- Note 7) MODE SET 1 and MODE SET 2 command bytes are issued only to DA1. Therefore, devices requiring such control are required to be associated with DA1, C1.
- Note 8) C2 and C3 are usually Control and Recovery type commands. They should be previously tested to assure execution without error, for the basic purpose of this option is to have an "error-free" output.
- Note 9) To be set only if device is on Multiplexor channel.
- Note 10) On 8K memory configurations byte counts and data address locations should be altered to reflect the smaller memory.
- Note 11) These addresses can be altered to designate operator-keyed chained command lists. These lists, however, should have the last command agree with the first command in the list with respect to the number of end-status indicators to be expected on completion of the chain.
- Note 12) These parameters are set only if the corresponding designates a Selector channel device.
- Note 13) These commands can designate chaining if the restrictions of Note 11) are met.
- Note 14) The 16 data bytes are preset to
 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16
 FF|A9|FF|81|D7|A9|FF|A9|44|12|44|3A|6C|12|44|12
- Note 15) To be considered only if data generation is designated in 0205, Refer to Section 1, paragraph 3.3.9.

3.5 Printed Messages

- 3.5.1 Two types of printed information are produced by ESCR. The first type is associated with unsolicited interrupts and will print one line of the following information:

UNSOLICITED INTERRUPT ** AABCCDD EE

AA = Selector Channel Device Address

= 00, if unsolicited MX interrupt occurred before routine presets this location

= FF, if unsolicited MX interrupt occurred after routine presets this value

BB = Selector Channel Error Status

= 00

= FF same as AA

CC = Device Status

DD = Device Address

EE = 00

= FF same as AA

This printout is not optionally selectable in location 0205. However, it maybe bypassed by altering 062A, B from a 45C0 to 4700.

- 3.5.2 The second type of printout is associated with initial and termination control indicators for the XIOF currently accepted and is optionally selected by setting bits 5 and/or 7 of 0205. Bit 5 maybe set at any time to control error printouts. Bit 7 should be set at initial load to print on successful completion of the XIOF.
- 3.5.2.1 This printout consists of one header line printout, a data line for each XIOF (in error or successfully completed, depending on the options selected). If the device is a tape unit (refer to Section 1, Paragraph 3.4.2 Note 6), one or more lines of additional information will decode in 4 alpha-numeric-character-notations each bit set in the SENSE and MONITOR SENSE bytes (refer to Section 11, Page 112 for Control Unit 0858 or Section 16, Page 16-3 for Control Unit 5017).
- 3.5.2.2 Since the 6-C Control Unit is permanently assigned to channels 8 and 9, the SENSE byte decode associated with this unit requires NRZI (bit 0 of 0205) recording to be indicated and the MODE SET 2 command designated as a valid command for this unit (CB is invalid for 6-C). Refer to Section 11, Paragraph 1.18.
- 3.5.2.2 If a 5017 Control Unit is put on channels 8 and 9, the proper SENSE byte bit decode is obtained by altering 07C9 from 80 to F0.
- 3.5.3 The header and data fields for the second printout are indicated below.

3.5.3 continued . . .

FIELD NO.	DATA TYPE	HEADER DESIGNATION - DATA CONTENTS	DESCRIPTION
1		ESCR	Routine name
	1		Data field is blank
2		DENSITY	Mode Set 2 indicator
	1	PHASE	Bit 0 of 0205 = 0
	2	NRZI CB	Bit 0 of 0205 = 1 - 5017 CU
	3	NRZI $\Delta\Delta$	Bit 0 of 0205 = 1 - 0858 CU
3		INSTRUCTION	XIOF instruction
	1	AABBCCDD	AA = XIOF operation code (A4) BB = Device Address CC = 00 DD = Command Code
4		40414243	Processor Mode Interrupt Indicators
	1	AABBCCAA	AA = Device Address - SEL CHAN = 00 - if not yet preset, - MX CHAN = FF - if preset, MX CHAN BB = 00 - normal SEL CHAN indication = 80 - error SEL CHAN indicator = 40 - length error SEL CHAN indicator = 00 - if not yet preset - MX CHAN = FF - if preset, MX CHAN CC = Stored Status for Device
5		DS	Status Stored by TIO
	1	AA	AA = 00 if not yet preset & I-O set = FF if preset & PM set = XX - termination status
6		78797A7B7C7D7E7F	SEL CHAN termination CAW
	1	AAAABBBBCCCCDDDD	AAAA = Address pointer to CAW BBBB = Termination Data Address CCCC = Termination Byte Count DDDD = Error indicators
	2	-	This area is blank, if multiplexing

3.5.3 continued . . .

FIELD NO.	DATA TYPE	HEADER DESIGNATION - DATA CONTENTS	DESCRIPTION
7		COMDBADRFLAGBCNT	SEL CHAN CCW
	1	AA00BBBBECCO0DDDD	AA = Command Byte OO = Always zero BBBB = Initial Data Address CC = Chaining, Termination, Length, Indicators DDDD = Initial Byte Count
	2	-	This area is blank, if multiplexing.
8		TERM-BCW	MX CHAN termination Buffer Control Word
	1	ABBCCCC	A = Data direction, Data Address Increment/Decrement, and termination Indicators. Also MS bit of byte count. BBB = Termination Byte Count CCCC = Termination Data Address
	2	--	This area is blank if selecting.
9		INIT-BCW	MX CHAN initial Buffer Control Word
	1	ABBCCCC	Indicators are identical to Field 8 above except they reflect initial rather than termination values.
	2	--	This area is blank if selecting.
10		SOS1S2S3S4	Five Sense Byte Indicators
	1	AABBCCDDEE	AA = Sense Byte 1, hexadecimal BB = Sense Byte 2, hexadecimal CC = Sense Byte 3, hexadecimal DD = Sense Byte 4, hexadecimal EE = Sense Byte 5, hexadecimal
	2	FFFFFFFF	This field is preset to FF if no Sense data is available
11		MOM1M2M3M4	Five monitor Sense Byte Indicators
	1	AABBCCDDEE	AA = Monitor Sense Byte 1, hexadecimal BB = Monitor Sense Byte 2, hexadecimal CC = Monitor Sense Byte 3, hexadecimal DD = Monitor Sense Byte 4, hexadecimal EE = Monitor Sense Byte 5, hexadecimal
	2	AAFFFFFFFF	AA = Device Address base FF = Preset value - no Monitor Sense Data
12		SIM	MODE SET 1 indicator
	1	N	Bit 3 of 0205 = 0
	2	Y	Bit 3 of 0205 = 1

3.6 Program Stops

3.6.1 All program stops are listed in Table II of Section 2. They are divided into 2 types: TYPE I - coded halt displays; TYPE II - address-display-halts

3.6.2 Explanations and Recovery Procedures for each stop are given.

TABLE I
PRESET LOCATIONS

Reference Tag	Hexadecimal Location	Preset Hexadecimal Value	Description
NSNS	→ 0268 → 026C	5 bytes set to FF	Five bytes of normal sense information.
MSNS	→ 026D → 0271	5 bytes set to FF	Five bytes of monitor sense information.
STATUS	→ 0040 → 0043	4 bytes set to FF	Channel and device status-address interrupt locations.
DS	08CA	1 byte set to FF	Device status set by a TIO instruction.
	→ 007A → 007F	6 bytes set to FF	Selector channel command termination control words.
	→ 001D → 001F	3 bytes	Multiplexor channel error termination status indicators and device address.

TABLE II

TYPE I — HALT-DISPLAY STOPS

ROUTINE CONTROL TYPE, CODED-HALT-DISPLAYS

Hexadecimal Display	Explanation	Recovery Procedure
00EE	Successful-initial-load	Key-in option selections and parameters. START initializes routine.
00CX X=1,2, or 3	Command X (CX) has been completed. This halt normally occurs once, after initial execution of CX.	Manually check termination indicators for CX. START initializes next command.
3ESS ⁽¹⁾	Printer error. SS = printer status	Correct error. START resumes printing. (NOTE: ESCR should be run without printer-loop-control to avoid 3E06 error stop.)
3AAA ⁽¹⁾	Printer abnormal.	Check and correct abnormal condition. START resumes printing.
3EEE ⁽¹⁾	Printing has been attempted resulting in an unrecoverable indication ⁽²⁾ .	I. START reissues 3EEE halt-display. II. Set location 093B from F0 (16) to 00(16). START reissues print command.

(1) These displays occur only if printing has been attempted. The first character of the display indicates the printer channel number, 3.

(2) This stop is considered unrecoverable by the routine for normal operation. Recovery must be operator controlled as indicated.

TABLE IITYPE II - HALT-DISPLAY STOPSADDRESS-DISPLAY TYPE

HEXADECIMAL DISPLAY	EXPLANATION	RECOVERY PROCEDURE
053A ⁽³⁾	Bit 2 of Option-Selection-Byte (location 0205) is set to 1. (Halt-before-command-execution option).	I. 1) Manually verify initial command control indicators 2) START initiates the command II. 1) Same as I. 1) 2) Set INST switch to STEP position 3) START staticizes the XIOF about to be executed in locations 6,7,8,9 ⁽⁴⁾ 4) Set CYCLE switch to cycle through the execution of this XIOF 5) Set any desired Test Mode Switches during cycling 6) On completion of the XIOF, reset INST switch to RUN position. START resumes routine.
0546 ⁽³⁾	XIOF instruction ⁽⁴⁾ has been rejected with Condition Code set to 01, 10, or 11.	I. 1) Verify Condition Code setting in location 0000 if in PM ⁽⁵⁾ or location 0010 if in IO ⁽⁶⁾ 2) Correct rejection condition 3) Set the address of the branch instruction following this halt to transfer control to an "operator-keyed" recovery <u>or</u> 4) If the rejected command is to be reissued (i.e., device was BUSY), set this address to 053E. 5) START executes the recovery step in 3) or 4)

TABLE II
 TYPE II - HALT-DISPLAY STOPS
 ADDRESS-DISPLAY TYPE
 continued . . .

HEXADECIMAL DISPLAY	EXPLANATION	RECOVERY PROCEDURE
058C	XIOF instruction ^(4,5) has been accepted and end-status interrupt indicates other than OC-CHANNEL END, DEVICE END.	General Recovery 1, 2, or 3.
05AA	XIOF instruction ^(4,5) has been accepted and end-status for a two interrupt command does not indicate CHANNEL END on the first interrupt.	General Recovery 1, 2, or 3.
05CC	Same as 05AA except this time the second interrupt is expected containing DEVICE END.	General Recovery 1, 2, or 3.
0644	An unanticipated transfer to I-0 mode has occurred. An UNSOLICITED INTERRUPT printout indicates pertinent information.	General Recovery 4.
066A	Previous LPSC did not work. A pending interrupt should have given control to location 0556 tagged INT.	I. 1) Manually verify interrupt indications. 2) START attempts to set PM. II. 1) Same as I. 1) 2) Set following branch instruction to go to operator keyed recovery. 3) START transfers control to this coding. III. General Recovery 3
068A	Previous LPSC did not transfer control to location 0390 in I-0. Probably CPU malfunction. No automatic routine recovery is provided.	I. 1) Analyze appropriate error indicators. 2) Set recovery branch instruction to transfer control to operator keyed recovery III. General Recovery 3

TABLE II
TYPE II - HALT-DISPLAY STOPS
ADDRESS-DISPLAY TYPE

continued . . .

HEXADECIMAL DISPLAY	EXPLANATION	RECOVERY PROCEDURE
069E	XIOF instruction ^(4,6) has been accepted. End-status stored in 08CA by a TIO indicates 00 instead of non-zero end-status.	General Recovery 1, 2, or 3
06BA	XIOF instruction ^(4,6) has been accepted. End-status stored in 08CA by a TIO does not indicate OC-CHANNEL END, DEVICE END.	General Recovery 1, 2, or 3
06D2	Same as 06BA above except CHANNEL END alone end-status is expected for first of two end-status indications.	General Recovery 1, 2, or 3
06EA	XIOF instruction ^(4,6) has been accepted and CHANNEL END status cleared. A subsequent TIO has not set CC = 01.	General Recovery 1, 2, or 3
0702	Same as 06BA above except DEVICE END alone end-status is expected for second of 2 status indications (stored in 08CB).	General Recovery 1, 2, or 3
0722	Same as 06BA except TIO has not stored 00 or 04 for end-status on an internal device.	General Recovery 1, 2, or 3
072E	An interrupt has set I-0 and control given to INT coding. The address in 2, 3 of PM PSCW should not contain a value less than 0502 Probable CPU malfunction.	General Recovery 3

NOTE ³ - Displays address of A9 halt-display instruction. This halt maybe removed by changing the A9 of the displayed address to a 47.

NOTE ⁴ - The XIOF instruction for C1, C2, or C3 is located in locations 053E, 053F, 0540, 0541.

NOTE ⁵ - PM - Processor Mode is set.

NOTE ⁶ - IO - Input/Output Mode is set.

TABLE II
TYPE II - HALT-DISPLAY STOPS
ADDRESS-DISPLAY TYPE

continued . . .

General Recovery 1

Step 1. Check appropriate command termination indicators.

 Status 40, 41, 42, 43
 TIO Stored Status 08CA, 08CB
 Buffer Control Words
 Condition Code Settings
 Selector Channel Address Words 78 → 7F
 MX Channel Error 1D, 1E 1F

Step 2. Set Print-on-error option - Bit 5 of 0205, if printing is desired and this option was not selected on initialization.

Step 3. START will print pertinent information, if printing options are set, and resume execution of next command.

General Recovery 2

Step 1. Record displayed-address

Step 2. Same as Step 1 of General Recovery 1.

Step 3. Alter the two branch conditional instructions following this halt instruction to transfer control to an operator-keyed recovery or test, or appropriate recovery coding in ESCR.

Step 4. START initializes Step 3.

General Recovery 3

Step 1. Same as Step 1 of General Recovery 1.

Step 2. Reset options and parameters, if required or desired.

Step 3. GENERAL CLEAR, START reinitializes C1.

General Recovery 4

Step 1. Same as Step 1 of General Recovery 1.

Step 2. START returns control to place at which routine was interrupted.

TABLE III
9200/9300 DEVICE ADDRESS ASSIGNMENTS

Purpose:

To define the device addresses and associated control word areas for all sub-systems that can be connected to all 9200/9300 systems.

Explanation:

There are two "BCW" areas in memory allocated for device addressing at present. The first "BCW" area is limited to eleven (11) usable sub-channels, 5₁₆ through F₁₆. The maximum number of sub-systems allowed on the channel is eight (8). A single sub-system control unit can accommodate up to eight (8) devices in a shared format. Both shared and non-shared control units can use sub-channels 5₁₆ through F₁₆. The second "BCW" area, sub-channels 40₁₆ through 4F₁₆, are limited to non-shared type device addressing only.

The following tabulation gives the complete device addressing assignments. The first six addresses (5₁₆ through 10₁₆) have been in effect for some time. Some of the unused sub-channels are in reserve for sub-systems that are to be included in the product line in the near future.

<u>Device</u>	<u>Hexadecimal Sub-channel Number</u>	<u>Hexadecimal Device Addresses</u>	<u>Hexadecimal Buffer Control Word Area</u>
Reader (Internal)	01	01	44
Read/Punch (Internal)	02	02	48
Punch (Internal)	02	02	4C
Printer (Internal)	03	03	50
8410 Disc	05	A8	54
Row Punch	06	06	58
1001 Card Controller	07	B8	5C
VI-C Tape #1	08	C0-7	60
VI-C Tape #2	09	C8-F	64
ICCU 418/1108-9300	0A	0A	68
0768 Printer	0B	0B	6C
Punch Paper Tape	0C	E0	70
DCS-4 Output #1	40	40	200
DCS-4 Input #1	41	41	204
DCS-4 Output #2	42	42	208
DCS-4 Input #2	43	43	20C
DCS-4 Output #3	44	44	210
DCS-4 Input #3	45	45	214
DCS-4 Output #4	46	46	218
DCS-4 Input #4	47	47	21C
DCS-1 Output #1	48	48	220
DCS-1 Input #1	49	49	224
DCS-1 Output #2	4A	4A	228
DCS-1 Input #2	4B	4B	22C

TABLE III

92/9300 DEVICE ADDRESS ASSIGNMENTS (cont)

<u>Device</u>	<u>Hexadecimal Sub-channel Number</u>	<u>Hexadecimal Device Addresses</u>	<u>Hexadecimal Buffer Control Word Area</u>
*U12/U16	0C Multiplexer	E0 → E7	70
	0D Multiplexer	E8 → EF	74
	-- Selector	60 → 67	78 → 7F
	-- Selector	68 → 6F	78 → 7F
*5024 Disc	-- Selector	30 → 37	78 → 7F
*600 CPM Reader	08 Multiplexor (non-shared)	08	60 → 63

*Arbitrary assignments for 9300 peripheral test-evaluation of 9400 devices.

1. INPUT/OUTPUT CONTROL

- 1.1 Various sets of memory locations are assigned to each input/output unit. Each set consists of four memory bytes, called a buffer control word, which is used for storing data storage addresses, character counts, and other details of each input/output function, if using the Multiplex Channel. Channel Command and Channel Address Words (Sect.4) are used if Selecting.
- Input/output control requires the following software steps:
- (1) Load the proper Control Word with information required by the control unit, provided the unit is not busy.
 - (2) Issue an input/output instruction which specifies the device address and the function to be performed.
 - (3) Check the condition code setting to determine if the instruction was accepted.
 - (4) Test the status of the device when the operation is completed (normally indicated by the generation of an interrupt) to determine if the operation was successful.
- 1.2 Processing continues during the execution of all I/O instructions. If the H bit is set to one, all interrupts for devices on a Multiplex Channel are inhibited. The Test I/O instruction should then be used to determine device status. An I/O interrupt can only be made at the end of a program instruction execution in the Processor Program State Control. At the end of each instruction execution, the peripheral interrupt request line is examined. If an interrupt request is present, interrupt is granted, control is shifted to the I/O Program State Control, and the device address and device status are stored in fixed locations in memory.
- 1.3 A Control Word should not be altered during the execution of an input/output operation on the peripheral device to which it is assigned. To do so can cause unpredictable results.

2. INPUT/OUTPUT INSTRUCTIONS, XIOF and TIO

2.1 The input/output instructions use the SI format. The I₂ portion specifies the I/O device. The least significant byte of the XIOF instruction specifies the command. If bit 16 of the instruction is a 1, the function is indexed before being executed.

			Operand 2			Address of Operand 1					
XIOF Op Code			Immediate Operand			Base Reg.			Displacement		
			I ₂			B ₁			D ₁		
0	A4	7	8	Device Address	15	16		19	20	Command	31

NOTES:

- The control word associated with the device specified must have been loaded with the proper control information for this device.
- If the instruction is executed with interrupt inhibited, the status or device address is never stored automatically. The procedure to be followed is the same as if I/O operations are done in I/O mode. In particular, the interrupt pending bit is set when the I/O operation is completed.
- The function specification in the OPl portion of the instruction defines the type of operation to be initiated.
- Some devices require additional information in the Control Words.
- Bit 27 (the H bit) is reserved to inhibit the generation of all interrupt requests when the operation ends. In this case, the interrupt pending bit will be set at the completion of the instruction.
- Condition Codes:
 - 0 - Function accepted
 - 2 - Function rejected
 - 3 - Function rejected - invalid device number

If a function is rejected, a TIO instruction causes the status to be stored to indicate a reason for the rejection.
- A control unit is busy from the time it accepts an I/O instruction until either an Interrupt Request is granted or until it is reset by the TIO instruction.
- When an interrupt request is granted, the indicators of the device are reset, and the status of the device is stored in memory location 42. The device address is stored in memory location 43.

2.2 Test I/O Status tests the status of the I/O unit specified by the device address in the I2 field.

Operand 2				Address of Operand 1			
TIO		Immediate Operand		Base Reg.		Displacement	
Op Code		I2		16		D1	
0	A5	7	8 Device Address	15	16	19	20 Address For Status
							31

NOTES:

1. The status of the addressed unit is stored at the address specified by OP1 regardless of the ultimate condition code setting.
2. This instruction clears the device status storage in the device if it is not busy. If the device is busy, status is not reset.
3. The interrupt request is part of the device status and is cleared by this instruction.
4. Condition Codes:
 - 0 - Zero Status - device available
 - 1 - Valid Status - interrupt was pending; device now available
 - 2 - Busy Status - device not available (also set if the reader, punch or printer is offline)
 - 3 - Zero Status - invalid device number

3. Multiplexer Channel Control

3.1 Multiplexer Channel Instructions

When Execute or Test I/O instructions are issued to devices other than the basic peripherals (Device Address 1, 2, or 3), the channel will attempt to execute the initial selection sequence or I/O command. The channel will reject the command if the addressed device is offline or does not exist. This will produce condition code 3.

3.2 Multiplexer Channel Status Byte

At the time of initial selection during an Execute I/O or Test I/O instruction and also at the end of I/O operations, peripheral units present a status byte with the following format:

- | | |
|----------------------|---------------------|
| Bit 0 - Attention | Bit 4 - Channel end |
| 1 - Status modifier | 5 - Device end |
| 2 - Control Unit end | 6 - Unit check |
| 3 - Busy | 7 - Exception |

The status byte is stored in a program specified location by a Test I/O instruction. When the channel is allowed to interrupt the program, the status byte is stored in location 66₁₀.

3.2 Multiplexer Channel Buffer Control Word

3.2.1 When a subchannel is used, the proper BCW must be loaded with the correct initial conditions before issuing an Execute I/O order to any subchannel. Each subchannel requires a four-byte buffer control word in the main memory. The buffer control words contain initial data counts and working data counts, data addresses, and control bits. Eleven buffer control words have been reserved for the multiplexer channel (memory locations 84-127₁₀). It may also use buffer control words allotted to basic I/O units if they are not present.

3.2.2 When a control unit initiates a sequence in order to request or present data or to present a status byte, the control unit presents a device address along with appropriate control signals. This address is placed in the multiplexer channel's device address register where it is used to determine the location of the proper buffer control word. The action taken by the channel depends upon the contents of this location. The normal BCW format follows:

3	13	1	15	
WMT	Byte Count (13 Bits)	0	Data Address (15 Bits)	
BC00 64 + 4N	BC01 64 + 4N + 1	BC10 64 + 4N + 2	BC11 64 + 4N + 3	Location

Basic Format: WM ≠ 11

W = Data Direction Bit

W = 1 for write (output) or "buffered" control operations

W = 0 for read (input) operations

M = Addressing Mode Bit

M = 0 for forward addressing sequence

T = Termination Bit

If T = 1, no data will be transferred, the BCW will not be modified by the channel and the Terminate response will be given to data request.

The channel will set T = 1 after the transfer of a byte of data causes the byte count to go to zero. The channel will not reset the T bit to 0.

Byte Count: This field is decremented by the channel whenever a byte of data is transferred. An initial count of zero gives a block length of 8192 bytes if $T = 0$.

A control unit may terminate an operation before the count becomes zero. Upon termination, this field indicates the difference, if any, between the initial byte count and the number of bytes actually transferred.

Data Address: This field is fetched by the channel and used as the address for the current byte of data. The address is modified in the BCW under control of the M bit in preparation for the next byte. Upon termination this field indicates where the next byte would have gone to or come from had the operation continued.

The W and M bits and the I-O command initiated via the subchannel must agree.

3.2.3 Line Terminal Format WM = 11

11TB	STATUS 4 5 6 7	K	0	DATA ADDRESS	
				8 Bits Fixed	7 Bits Variable
BC00		BC01		BC10	BC11

T - (Terminate Bit) - if $T = 1$ no data will be transferred, the Data Address will not be modified, the Channel will give the Terminate response to Data Requests. The Channel will set $T = 1$ when "Wrap-around error" occurs (see B Bit below). The channel will not erase a T bit.

B - (Buffer End Bit) - When the address modification generates a carry from the 2⁵ bit position of the Data Address (when the address is modified to an integral multiple of 64₁₀) the Channel sets the B bit to one and generates a LT Summary Interrupt Request. The B bit alerts the program that a 64-byte buffer segment has ended. The program is expected to remove the B bit when that buffer segment is again ready for use by the Channel. If the Channel finds a B bit remaining in the BCW when the End of Buffer Segment occurs again the Channel sets the T bit to one so that the data will not be overlaid. This is the "Wrap-around error" situation. The channel will not erase a B bit.

DATA ADDRESS - This field contains the address of the next data byte to be transferred. The address modification in the LT format is always $A + 1 \rightarrow A \pmod{128}$. This sequence, with the B bit, gives the effect of alternating the use of two adjacent 64-byte buffer areas.

STATUS FIELD - When a device operating in the LT mode initiates a sequence to present status, bits 4-7 of the Status Byte are merged (OR function) into this field. If the CPU allows the Interrupt, the entire status byte is also placed in the DEVICE STATUS area (see memory map) and the LT Summary Interrupt Request is reset. If the Interrupt is not allowed the LT Summary Interrupt Request is set.

SHEET 3-6

REVISION -

SPECIFICATION SYMBOL
SH04479

3.2.3 continued . . .

K Field - Address trap - If a device operating in the LT mode attempts to present status and bits 4 and 5 in the STATUS field of the BCW were previously both zero, the 8 least significant bits of the Data Address are transferred to the K field. If either bit 4 or bit 5 in the BCW was previously a one the transfer does not occur.

SELECTOR CHANNEL CONTROL

1. Selector Channel Instructions

The Selector Channel Execute or Test I/O instructions are identical to those of the Multiplex Channel and are described in Section 2. The primary difference between the two channels lies in the way control information is set up. See paragraph 3.

2. Selector Channel Status Byte

This byte is identical to that specified in Section 2, Paragraph 3.2. However, locations 40 → 43 contain vital information relative to the Command issued.

Loc 40: Device Address. Modified in Processor or I/O Mode only by Selector Channel.

Loc. 41: EL000000

E = any error, except L.
L = Incorrect length error.

Modified only by the Selector Channel.

Loc. 42: Device Status. Modified by MX. or Sel. Channel.

Loc. 43: Device Address. Modified by MX. or Sel. Channel.

Locations 41, 42, & 43 - modified only in Processor Mode.

3. Selector Channel Address Word

Locations 78 and 79 must contain the address +2 of the first byte of the 8-byte Channel Command Word and must be loaded before the XIOF is issued. On termination of the Command, locations 78 → 7F contain information related to the data transfers and error information.

MEMORY RESERVED FOR THE SELECTOR CHANNEL CAW

78	79	7A	7B	7C	7D	7E	7F
Command Add. Word		Ending Add + 1		Ending Byte Count		Error and Interface	

Loc. 78 & 79: Initially, address of 1st CCW+2.
At termination, last CCW address executed +8.

Loc. 7A & 7B: Initially, not used.
At termination, last data address +1.

Loc. 7C & 7D: Initially, not used.
At termination, number of bytes left to transfer.

Loc. 7E:

- Bit 0 Interface Error
- Bit 1 Address Error
- Bit 2 Parity Error
- Bit 3 Address Out
- Bit 4 Select Out
- Bit 5 Operational In
- Bit 6 Address In
- Bit 7 Command Out

Loc. 7F:

- Bit 0 Status In
- Bit 1 Service Out
- Bit 2 Service In
- Bit 3 Request In
- Bit 4 Suppress Out
- Bit 5 Select In
- Bit 6 Terminate F/F
- Bit 7 SJBO (always 1)

4. Channel Command Word

4.1 Channel Command Words must also be set up prior to XIOF execution. Commands may be chained, as indicated, and can reside in any appropriate 8 bytes of memory. If chained, they can be related by the Transfer In Channel (TIC) Command, which simply replaces the address field of the Address Pointer of the Channel Address Word with the Address of the TIC CCW.

4.2 The format of the Channel Command Word follows:

CHANNEL COMMAND WORD (CCW)																	
00		01		02		03		04		05		06		07			
0	7	8	15	16	23	24	31	32	39	40	47	48	55	56	63		
Command		X		Starting Address				Flags				X		*Byte Count			

Command:	Test	P	XXXX0000
	Sense	P	DDDD0100
	Write	P	DDDDDD01
	Read	P	DDDDDD10
	Read Backward	P	DDDD1100
	Control	P	DDDDDD11
	TIC	P	XXXX1000

P = Odd Parity Bit X = Ignored by CU's D = Detail Bits

Starting Address: Address of first byte

Flags: P OCTS0000

C = Command Chaining

T = Terminate

S = Suppress Incorrect Length Error

Byte Count: Exact number of bytes to be transferred
* (All zeros = maximum byte count = 64K)

NOTE: The CCW is never modified by the Selector Channel.

Card Reader Control

1.1 The card reader reads a card in either translate mode or in image mode.

1.2 Card Reader Instructions

The Execute I/O instruction for the card reader has the following format:

OP CODE A4	DA 00000001	B ₁	00000	000H	0X10
0	7 8	15 16	19 20	23 24	27 28 31

where: X ≠ 0 Read Translate Mode
X = 1 Read Image Mode
H = 1 Inhibit all interrupts

These two combinations of bits, in the direct B₁ - D₁ field or the indexed B₁ - D₁, are the only permissible combinations of reader XIOF instructions. Any other combination may cause an error.

1.3 Card Reader Buffer Control Word

The buffer control word for the card reader contains the following data:

HTS	COL.	BASE ADDRESS
0	7 8	15 16 23 24 31

where: HTS = Hardware temporary storage reserved for the reader. This byte should not be loaded by the program.

Col. = The number of columns to be read. This must always be 80. This count will be decremented to zero to signal the end of the operation.

Base Address = The address of the most significant halfword (even numbered address) of the card read area in memory. Upon completion of the operation, this address will be one greater than the address of the last byte into which information was read.

2. Card Reader Status Bytes

2.1 The status byte contains information pertaining to the result of the last issued order or the next to last issued order. Status indications are as follows:

All zeros No indicators set, function performed as specified.

Bit 5 set to 1 Interrupt request pending. This status bit is set only if the TIO function clears a pending interrupt before it is accepted. This status bit does not indicate an error.

Bit 1 set to 1 Misfeed, not ready, hopper empty or stacker full; these conditions are sampled only at initiation time of the XIOF instruction. If any one of these conditions exist, the XIOF instruction will be rejected. A Test I/O instruction will then store this indicator only if it follows an XIOF instruction which was rejected because of one of these conditions.

Bit 0 set to 1 Stacker jam, control parity or photocell check; instruction may or may not have been accepted and card may have been fed.

2.1.1 The error conditions are divided into Type I and Type II. Type I errors set bit 0 of the status register as soon as they occur. Type I errors indicate that the data read into memory in this card read may not be correct and should not be used by the program. Type II error indications are stored in intermediate error storage when they occur. When the next XIOF is executed, they will set bit 1 of the status register. Type II errors are delayed until a subsequent XIOF because the data read into memory during the card cycle in which they occurred is correct and can be used by the program.

2.1.2 All error conditions must be cleared manually. All error indications except Control Parity Error can be reset by depressing the Reader CLEAR switch. The Control Parity Error indication can be cleared by depressing the processor CLEAR switch. In addition, the Hopper Empty-Stacker Full (HESF) indicator can be reset by depressing the OFF-LN switch. The HESF indicator can be cleared in this way without error even if the processor is running the issuing XIOF's to the reader.

2.1.3 Offline does not set the status register but will make the reader appear busy to the processor. Any order in progress when OFF-LN is depressed will be allowed to continue to completion.

Card Punch Control

1.1 The card punch discussed below will include the controls required for the card reader option that may be incorporated to form a card read/punch.

1.2 Card Punch Instructions

The Execute I/O instruction for the card punch and reader option has the following format:

OP CODE A4	DA 00000010	B ₁	000	000H	SXRP
0	7 8	15 16	19 20	23 24	27 28 31

where: H = 1 Inhibit all Interrupts
 P = 1 Punch a card
 R = 1 Read a card
 X = 0 Read and/or Punch a card in compressed mode
 X = 1 Read and/or Punch a card in image mode
 S = 1 Select Stacker. Effective only if the program stacker select feature is installed. Otherwise, this specification is ignored.

Either the R or P bit must be 1. All other bits shown as 0's must be 0's, or an error may result.

1.2.1 Feeding with no reading or punching can be done by specifying the punching of two blank columns.

The second punch stacker is an error stacker and is selected on punch errors. This stacker is program selectable. However, errors will always cause this stacker to be selected regardless of program choice. Stacker selection is given for the card in the punch wait station in the same instruction that causes it to be punched.

1.3 Card Punch Buffer Control Word

The buffer control word for the card punch contains the following data:

HTS	COL.	BASE ADDRESS
0	7 8	15 16 23 24 31

where: **HTS** = Hardware temporary storage reserved for the punch. This byte should not be loaded by the program.

Col. = The number of columns to be punched. This must always be an even non-zero number. At the end of a card operation this count will be decremented to zero.

Base Address = The address of the most significant halfword (even numbered address) of the card punch area in memory. Upon completion of the operation, this address will be one greater than the address of the last byte that was punched.

1.3.1 The buffer control word for the punch reader option contains the following data:

HTS		COL.		BASE ADDRESS	
0	7	8	15	16	23 24
					31

where: **HTS** = Hardware temporary storage reserved for the reader. This byte should not be loaded by the program.

Col. = The number of columns to be read. This must always be 80. At the end of a card operation this count will be decremented to zero.

Base Address = The address of the most significant halfword (even numbered address) of the card read area in memory. Upon completion of the operation, this address will be one greater than the address of the last byte into which information was read.

2. Card Punch Status Bytes

The status byte contains information pertaining to the result of the last issued order or to the next-to-last issued order. The status indications are as follows:

- 2.1 All zeros No indicators set; function performed as specified.
- 2.2 Bit 6 set to 1 Hopper empty or stacker full; when this status bit is set the last XIOF function was terminated before it was executed. To recover from this early termination, the XIOF order must be reinitiated after the condition has been corrected.
- 2.3 Bit 5 set to 1 Interrupt request pending. This status bit is set only if the TIO function clears a pending interrupt before it is accepted. It does not indicate an error.

SHEET 6-3

REVISION -

SPECIFICATION SYMBOL
SH04479

- 2.4 Bit 4 set to 1 Photocell check error; this is a check on the read photocells as well as possible indication of a card jam. This error indication will be registered by status bit at the end of an XIOF. The last XIOF function should be assumed in error.
- 2.5 Bit 3 set to 1 Data parity or control parity error; card at read station or card at punch station may be in error. An immediate interrupt occurs upon recognition of error and the XIOF is terminated. The card passing through the punch station will automatically go to the error stacker. This status bit indicates that the last XIOF instruction was probably terminated before completion.
- 2.6 Bit 2 set to 1 Punch check error; interrupt after card has been punched. Card being punched will automatically go to the error stacker. The status bit being set indicates that the last card punched was in error.
- 2.7 Bit 0 set to 1 Stacker jam, punch entry or exit check, interlocks, and any other condition that may necessitate manual intervention.

Printer Control

1.1 The printer prints first and then advances paper. To allow the maximum amount of time to prepare the next line of data and to store the data in the specified print area, interrupt is generated before the paper advance operation is completed. Thus, the functions overlap since the next XIOF instruction can be issued before the paper advance is completed for the last print instruction. If the interrupt were not generated until after the paper advance, a bar cycle would be skipped after double spacing. Printing starts when the print bar is in either the extreme left or right position. Printing then requires one complete cycle of bar movement, back and forth. An advance of as many as two lines can then be made without missing a print bar cycle.

1.2 Printer Instructions

1.2.1 Print and control are the only valid print instructions. The bar selection modifies these codes and is effective only if the Bar Printer option has been included as part of the system. Print may be given with or without paper advance. Control is used for paper feeding without printing.

The Execute I/O instruction follows:

OP CODE A4	DA 00000011	B ₁	0000	BNOH	00X1
0	7 8	15 16	19 20	23 24	27 28 31

where: X = 0 for a Print instruction
 X = 1 for a Control instruction
 B = 0 Standard 63-Character Bar
 B = 1 Optional 48-Character Bar
 N = 1 Print Numeric if 48-Character Bar option is activated
 H = 1 Inhibit interrupt

B must equal N (defined below).
 N = 1 Print numeric if 16-character bar is installed
 H = 1 Inhibit interrupt
 Note: In a control XIOF, B and N are not significant

1.2.2 On a system that has a printer with less than 132 print positions per line, data can be stored in the positions of the print image area for which there are no print hammers (locations 224 through 259, for a 96-position printer; or locations 248 through 259, for a 120-position printer). Such data is not altered by, nor does it affect, the operation of the printer.

1.3 Printer Buffer Control Word

1.3.1 The buffer control word for the printer contains the following data:

FC 0000LXXX	BA	STC	CR
0	7 8	15 16	19 20 31

where: BA = Base Address
 STC = Starting Code
 CR = Code Register
 FC = Forms Control

CR, STC, and BA are under complete hardware control. If they are inadvertently changed by a program, a loss of printer control will probably result.

1.3.2 The forms control byte is loaded by the program once a TIO or an interrupt determines it is permissible. The forms control byte is not changed by the execution of a printer function. The four bits which designate the desired forms action follow:

L X X X

0 0 0 0 Space 0 lines

0 0 0 1 Space 1 line

0 0 1 0 Space 2 lines

1 X X X Select any of 7 paper loop channel controls by matching holes in the paper loop to the 1 bits in the X positions.

1.3.3 There are two paper loop conventions:

X X X

1 1 1 for home paper

0 0 1 for form overflow

If a hole combination is sought under paper loop control that is not punched on the tape, a runaway paper condition results.

1.4 Issue and Execute

1.4.1 "Issue" refers to the time that an XIOF is decoded by the processor and the command information is forwarded to the printer control. This is also the time at which the condition code (CC) is generated and made available to the program. "Execute" refers to the time that the printer controls respond to the command information forwarded by the processor. In some instances, "execute" may follow "issue" by a considerable period of time.

1.5 Status Register

1.5.1 The print controls contain a status register which stores the various error indications until they are transferred to memory by a TIO or by an interrupt request acceptance by the processor. When an XIOF is in progress, the setting of any bit in the status register will terminate the operation and generate an interrupt request.

1.5.1 The error conditions are divided into Type I and Type II. Type I errors set the status register directly when they occur. Type II error indications are stored in an intermediate error storage when they occur. The next time an XIOF is executed they are transferred to the status register.

1.5.2.1 Type I errors are as follows:

- Bar Check
- Memory Overload
- Parity
- Abnormal

1.5.2.2 Type II errors are as follows:

- Paper Low
- Forms Overflow
- Paper Runaway

1.5.2.3 Bar Check occurs after an XIOF is executed, but before printing begins. Memory Overload occurs during printing.

Parity occurs after an XIOF is executed but before paper advances.

Type II errors occur during paper advance.

Abnormal can occur any time.

When an offline error occurs, the status register is not set, but the reader appears to be busy to the processor. Any order in progress when the offline (OFF-LN) switch is depressed will be allowed to continue to completion.

1.6 Interrupt Requests

1.6.1 Interrupt requests occur at the following times:

End of print before associated paper feed is started.

Immediately following an accepted paper feed order before paper advancing has begun, unless a previously initiated paper feed order is in progress. In the latter case the interrupt is delayed until the previously initiated paper feed order has been completed.

Upon abortion of an order due to detection of paper low, forms overflow, or forms runaway as a result of a preceding order.

Upon termination of an operation due to any other error condition.

2. Printer Status Bytes

The status byte (in location 66) contains information pertaining to the result of the last issued order or the next to last issued order. The status indications are as follows:

- 2.1 All zeros No indicators set; function performed as specified.
- 2.2 Bit 7 set to 1 Paper Low* as a result of paper spacing. Until the paper condition is corrected, this indicator will occur for each XIOF. Paper low will be indicated when the bottom edge of the form is 15 1/3" \pm 1/3" from print line.
- 2.3 Bit 6 set to 1 Form overflow*. OOI sensed at paper loop station during single or double spacing. Form overflow is set even if spacing does not stop on the OOI channel punch. Passing over the punch is sufficient.
- 2.4 Bit 5 set to 1 Interrupt request pending. This status bit is set only if the TIO function clears a pending interrupt before it is accepted. This status bit does not indicate an error.
- 2.5 Bit 4 set to 1 Instruction does not agree with bar switch setting.
- 2.6 Bit 3 set to 1 Data parity or control parity error on last XIOF instruction. Printer stops immediately.
- 2.7 Bit 2 set to 1 Memory overload occurred on last XIOF instruction. Printer stops immediately. Paper has not advanced.
- 2.8 Bit 1 set to 1 Paper Runaway*-forms control lost. Further orders will not be accepted without operator intervention, since the printer goes abnormal.
- 2.9 Bit 0 set to 1 Abnormal or not ready.

*These conditions are recognized following the normal interrupt request. Therefore, the previous function will be properly completed except in the case of paper runaway where paper has been spaced improperly. If another XIOF has been accepted, it will be aborted and an interrupt will be generated. If the next XIOF is not issued until after detection of the condition, the order will be accepted, then aborted and an interrupt request will be generated. Any error that happens before paper is advanced will void paper advancing.

UNIVAC 8410 Disc File Control

1. Command Repertoire

1.1 The following command codes may be issued to the Disc File Control by the computer. Any other codes will be rejected and cause a Unit Check status to be returned to the channel.

<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
-------------------------	----------------	----------------

P01234567	P = Odd Parity X is ignored by the Disc File Control ABCDEF = Detail Bits.
-----------	--

1.2	PXX000000	<u>Test I/O</u> : Disc File Control sends status byte to the channel and clears the status register and Status In when the channel responds that it has accepted the status byte.
-----	-----------	---

1.3	PABCDEX01	<u>Write Commands</u> : The following commands will be considered as write commands by the Disc File Control. Bits BCD will specify the state of the three output control lines sent to the Disc File to specify the command. If bit E = 1, a prep write is specified. If bit E = 0, a normal write is specified.
-----	-----------	---

1.3.1 At the completion of the Initial Selection Sequence the unit select line, along with the output control lines and output request, will be presented to the Disc File interface to transfer the command. The Control Unit will request the first byte from the Channel Interface and when this character has been received, the Control Unit will bring up Output Request. The Output Strobe will then be brought up to allow the output data to be sampled by the Disc File. The Control Unit will request bytes of data until COMMAND OUT response is given by the channel.

1.3.2 When the Disc File has accepted a command, the Disc File busy indication will be presented to the Control Unit. This line will remain up until the completion of the command (other than Seek Track) or until the Disc File detects an error and terminates the operation. In order to sample the status of the Abnormal and Interrupt lines from the Disc File, the Unit Select and Input Request lines must be brought up. The Disc File will return an Input Acknowledge and clear the abnormal conditions when the Unit Select is dropped, if there are errors. If no errors have been detected, the Disc File will not return Input Acknowledge and the Control Unit must time out the dropping of Unit Select.

NOTE: For normal write commands, the A bit is always zero. When the A bit is a 1 a maintenance write is specified. A maintenance write responds to the channel the same as a normal write operation. However there is no command or data transfer to the

NOTE: 8410 Disc File. Unit Select, Input and Output Requests are inhibited from being sent to the 8410 Disc File. There will be no responses received from the 8410 Disc File. All responses to the channel will be generated internally by the 8410 Disc File Control.

1.4	<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
		P01010X01	<p><u>Write and Check</u>: The Disc File Control will receive five bytes from the channel specifying the address of a record on the Disc File. The address will have the following format:</p> <p>U = Disc File unit address (from 0 to 7 in BCD).</p> <p>T_M = Most significant digit of track address (from 0 to 9 in BCD).</p> <p>U T_M T_L S_M S_L T_L = Least significant digit of track address (from 0 to 9 in BCD).</p> <p>S_M = Most significant digit of sector address (from 0 to 9 in BCD).</p> <p>S_L = Least significant digit of sector address (from 0 to 9 in BCD).</p> <p style="text-align: center;">U T_M T_L S_M S_L</p> <p style="text-align: center;">oooouuuu ooottttt ooottttt oooossss oooossss</p> <p>Bit 01234567 01234567 01234567 01234567 01234567</p>

1.4.1 Bit 3 of the most significant track address byte T_M will specify if a head on the movable arm or the fixed fastband head is being addressed. A zero in this bit position indicates a head on the movable arm, while a one in this bit position indicates the fixed fastband head.

1.4.2 The five bytes of address will be followed by the data that is to be written in the specified sector.* Upon completion of the data transfer, the Disc File will read the address of the track on which the specified arm is positioned and compare this against the track address specified in the buffer memory. If the address does not agree, the Disc File will position the arm to the correct track. The Disc File will return a busy signal to the Control until the completion of the write and check read. (Since the Disc File uses the same head for reading and writing, the check read requires 50 ms for additional revolution of the disc.)

*If more than six bytes (including the address), but less than the capacity of a sector are transferred to the Disc File, those locations not receiving data will be cleared to binary zeroes. If less than seven bytes are transferred, the remaining locations will contain data stored the last time the memory was loaded.

<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
1.5	P00010X01	<u>Write</u> : This write is the same as Write and Check except that the read check is eliminated.
1.6	P0110XX01	<u>Read</u> : The 8410 Disc File Control will receive five bytes from the channel specifying the address of a record on the Disc File.
1.6.1		The bytes specifying the address will be transferred to the Disc File buffer. The Disc File will read the address of the track on which the specified arm is positioned and compare this against the track address specified in the buffer memory. If the address does not agree, the Disc File will position the arm to the correct track. The Disc File will return a busy signal to the control until the completion of the read. Information read will be stored in the buffer. (An Unload Buffer command must be issued to transfer data to the channel.)
1.7	P0000XX01	<u>Seek Track</u> : The 8410 Disc File Control will receive five bytes from the channel specifying the address of a track on the Disc File. The address format is that specified for Writes with the exception that the sector address characters have no significance. When the Unit Select to the Disc File is dropped after transfer of the address bytes, the arm will be positioned to the track specified. The busy indication from the Disc File will be returned to the Control until the address of the track the arm is presently at is read.
1.8	P0111XX01	<u>Magnitude Search</u> : When beginning a Search High, the Disc File Control will receive five bytes from the channel specifying the address of a record. These five bytes will be followed by the key that is being searched for.
		NOTE: All data tracks, including the fastband, can be used for this search. If a data track is used, the heads must have been positioned to the correct track by a previous Seek Track Command.
1.8.1		The key will be compared against the contents of the addressed track. When the track key area is less than the desired key followed by an equal-to or greater-than key, a comparison occurs. As a result, the address of that track and sector remains in the buffer. This address can be retrieved by issuing an Unload Buffer Command.

<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
1.8.2	P0111XX01	The maximum key length that can be searched for is 160 eight-bit characters. Portions of the key may be masked by using a sentinel character to mask the beginning and ending of the key. The sentinel character is 11111111. The key search will not begin until the first non-sentinel character is recognized. The search ends when the first sentinel character occurs after the search has started.
1.9	P0011XX01	<u>Search Equal</u> : The 8410 Disc File Control will receive five bytes designating the record address from the channel, followed by the key that is to be searched for. All five bytes will be significant. Bit 3 of the most significant track address byte will specify a head on the movable arm, or the fixed fastband head. Sector addresses of 54 or less will select head 1. Sector addresses of 55 to 99 will select head 2.
1.9.1		When head 1 is selected, only the 55 sectors under it can be searched. Head 2 must be selected by another Search Equal Command to search the 45 sectors under it. The maximum key length that may be searched for is 160 eight-bit characters.
	NOTE:	No check is made to determine if the correct track is being searched. The head must have previously been positioned to the correct track. Intervention Required (bit position 1 of the Sense Byte) condition will occur.
1.10	P01011X01	<u>Prep Write Normal</u> : The Prep Write command is used to write sector addresses on a disc. One track at a time can be prepped. Before attempting this instruction, the Prep Mode Switch on the Disc File must be thrown. If this switch is not thrown the Prep Wirte will be treated as a normal write.
1.10.1		This instruction is performed the same as a Write Command. Only the address portion is significant. Addresses are of the same format as Writes.
1.10.2		When the first Prep Write command is issued, not more than 800 microseconds is permitted between successive commands. This includes Prep Write Bad Spot Commands. If sectors under head 1 are being prepped, exactly 55 valid addresses and 4 Bad Spot Commands or invalid addresses will be written. Sectors under head 2 require exactly 45 addresses and 4 Bad Spot Commands or invalid addresses to be written.

<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
1.10.3	P01011X01	In the 8410 Disc File, the Prep Write is distinguished from other write instructions by activating Input Control Line 3, in addition to the Output Control Lines being sent to the Disc File. Input Control Line 3 permits the Disc File to write the first track address after the detection of the home sprocket. This Input Control Line remains active until a command other than the prep writes or a Sense is issued from the channel. A command other than a prep write or Sense must be issued at the end of transfer of 49 or 59 addresses and bad spots. This allows the Disc File to recognize the home sprocket for the next track.
1.10.4		Before starting a Prep, it must be assured that the heads are in the home position. The Home Request switch on the Disc File must be depressed to return the heads to home. After returning home the heads are positioned to the desired track by issuing a Seek Track command. At the termination of the Seek Track the selected head will be positioned to the correct track. The Prep Write command may then be issued for that track.
		<u>NOTE:</u> Any track may be selected from the home position. Once the heads have positioned to a track, the heads may only be positioned to higher numbered tracks. To position to a track with a lower address, the heads must be repositioned to the home position.
1.10.5		Instructions other than Prep Write or Seek Track may be performed when the Prep Write Switch is thrown. However, all read or write commands must be issued for the track being prepped. If the track address issued is not the same as the one the heads are positioned to, the Equipment Check Sense Bit will be set in the control.
1.11	P00011X01	<u>Prep Write Bad Spot:</u> This command is performed the same as a Normal Prep Write. In the 8410 Disc File Subsystem ones will be written in the Sector Address. The all-ones code masks out that sector.
1.11.1		Up to four bad spotted sectors are permitted per track. These can be used to mask non-recordable areas of a track. Once a Prep Write Bad Spot Command has been issued for a sector, there is no way to address that sector.

<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
1.11.2	P00011X01	If less than 4 sectors are bad on a track an illegal address will be written in the address area of any sectors less than the track capacity. e.g. There are 45 addressable sectors under head 2 and 4 reserved. If 3 sectors have bad spots, then the fourth sector address area will be recorded with an illegal address instead of a Bad Spot.
1.12	PAXX1XX10	<u>Unload Buffer:</u> The Unload Buffer command will cause the 8410 Disc File to transfer the contents of the buffer to the Disc File Control. The first five characters transferred will be the address of the record. Input Request will be generated instead of Output Request. Input Control Line 1 will also be generated. NOTE: If bit A is a 1 a maintenance Unload Buffer is specified No data will be unloaded from the 8410 Disc File Subsystem buffer. Data returned will be the first 8 bit code transferred to the 8410 Disc File Control data register as a result of the last write command. This data byte will continually be sent as data until the channel signals terminate.
1.13	POXXX0100	<u>Sense:</u> The Disc File Control transfers sense bytes to the computer as input data. In addition to supplying pertinent information to the program, this data can be used as maintenance aids. The sense bytes provide the detail information about the unusual conditions detected in the last operation which were initially signalled to the computer in the status byte during Status In.
1.14	POX010000	<u>Set Inhibit Status:</u> This command is processed as a Test I/O Command. (If accepted, it does not generate any new status.) Status will be presented to the Channel and Inhibit Status In will be set.
1.15	POX100000	<u>Reset Inhibit Status:</u> This command is processed as a Test I/O Command. (If accepted, it does not generate any new status. Status will be presented to the Channel and Inhibit Status In will be reset.
1.15.1		The condition of the Inhibit Status In can be examined in Sense Byte 1, bit position 6. When Inhibit Status is set, the Disc File Control will not initiate sequences to present status.

<u>Bit Position</u>	<u>XF Code</u>	<u>Command</u>
1.17	POX110000	<u>Set and Reset Inhibit Status</u> : If a command is given with both the Set and Reset Inhibit bits, the command will be treated as a Test I/O and Inhibit Status In will not be affected.

2. Status Byte

2.1 The status byte provides the overall information about status and conditions detected in the last operation. The status byte will be stored in the Status Register and will be transmitted to the channel on the BUS IN during Status In, (initiated at the end of the Initial Selection Sequence, completion of the data transfers and completion of the command). The Status Register will be cleared when the channel responds to Status In with SERVICE OUT. The following defines the significance of each status bit.

<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
P	Odd Parity	Parity for status byte.
2.2	0	Attention
2.3	1	Status Modifier
2.4	2	Control Unit End
2.5	3	Busy
		Indicates that the Disc File Control cannot accept a command because one of the following conditions exists:
		a) Disc File Control is executing a previously initiated command.
		b) Disc File Control is holding pending status conditions from a previous command of the addressed unit. (Not applicable to Test I/O or Set or Reset Inhibit Status.)
		Busy can occur only during the Initial Selection Sequence.
2.6	4	Channel End
		Indicates the completion of the data transfers between the channel and the Disc File. Channel End can only occur when Device End occurs.

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
2.7	5	Device End	Indicates the completion of a command, except for Seek Track. In the case of a Seek Track, Device End indicates that motion control has begun.
2.8	6	Unit Check	Any of Bits 0, 1, 2, or 3 in Sense Byte 1 are set.
2.9	7	Unit Exception	Not Used. Bit is always 0.

3. Sense Data Byte

3.1 Sense data provide detailed information about the unusual conditions detected in the last operation and the status of the Disc File Subsystem. The Sense data will be cleared when the next command is accepted, if the command is not a Sense Command or Test I/O.

The following describes the significance of the sense data:

3.2 Sense Byte 1

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.1	P	Odd Parity	Parity for Sense Byte 1.
3.2.2	0	Command Reject	Unspecified command issued to the Disc File Control. This bit is suppressed if the command byte has bad parity (Bit 2 BUS OUT Check).
3.2.3	1	Interven- tion Required	Indicates that the interrupt line from the Disc File is active. This indicates a no find condition on a Search command, or if present with the abnormal line, a catastrophic failure.
3.2.4	2	BUS OUT Check	Parity Error. Even parity appeared on the BUS OUT from the channel during the command or data transfer. Bit 0 (Command Reject) is suppressed when Bit 2 is indicating a parity error in the command byte.
3.2.5	3	Equipment Check	Indicates that the abnormal line from the Disc File is active.
3.2.6	4	Data Check	Not Used. Bit is always 0.
3.2.7	5	Overrun	Not Used. Bit is always 0.
3.2.8	6	Inhibit Status In	Inhibit Status In.

3.2.9	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
	7	Input Control	Input Control Line No. 3 FF set. (Indicates control is in Prep Mode).

3.3 Sense Byte 2
This bytes provides the last command executed.

3.4 Sense Byte 3

<u>Bit</u>	<u>Designation (signal)</u>	<u>Normal Values</u>
0	UDATA	0
1	UACT1	1
2	UFLT (Disc File Fault)	0
3	UUSEL	0
4	UGND3	0
5	UAKN	1
6	UBUSY	0
7	UGND2	0

3.5 The abnormal line from the Disc File indicates the following conditions:

1. A Write Check error.
2. A Read error (on address or data) after three attempts to read.
3. Phase error on reading (check on demodulator).
4. Phase character error on reading data.
5. Motion Control Error.
6. Bit Count Check.
7. No data written, invalid track address.

3.6 The interrupt line from the Disc File indicates a No Find error during a Search command.

Both the abnormal and interrupt active at the same time indicate the following conditions:

1. More than a single unit selected.
2. Disc File power off.

9000 Series Row Punch Subsystem

1. COMMAND REPERTOIRE

- 1.1 The following command codes may be issued to the punch control by the Processor. Any other codes will be rejected and will return a Device check status to the Processor.

<u>Bit Position</u>	<u>Command</u>
	P01234567

Description

P = Odd Parity Bit
 X = Ignored by control unit
 ABCDEF = Detail Bits

- | | | | |
|-----|------------------------------|-----------------------|---|
| 1.2 | PXX000000
or
PXX110000 | <u>Test I0:</u> | The punch control presents a status byte to the channel. Service Out from the channel clears the status. |
| 1.3 | PAXXXXF10 | <u>Unload Buffer:</u> | (Read): Data read from the previous card to the buffer is transferred to the Channel. At the completion of the data transfer, the punch control presents Status to the channel.

F = 0 Read in the compress mode.
F = 1 Read in the image mode.

A* = 1 Unload Punch Buffer
A = 0 Unload Read Buffer

*This function is provided for Buffer Memory and Translator test. |
| 1.4 | PAXCDEX11 | <u>Control</u> | This code is used for non-data transfer operations in the punch control unit.

E = 1 Feed a card. The cards are advanced one station.

D = 1 Feed and punch a card.

C = 1 Feed a card and select stacker. The card which was punched on the previous punch order will be placed in the select stacker.

A* = 1 Post-punch read to punch buffer.

A = 0 Normal operation

*Maintenance Feature. |

COMMAND REPERTOIRE (continued)

1.4	<u>Bit Position</u>	<u>Command</u> P01234567	<u>Description</u>
			If the R/P Feature is present, the pre-read station is transferred to the buffer when a card is fed.
1.5	PAXCDEF01	<u>Load Buffer</u>	(Write): Information is transferred from the channel to the punch buffer. At the completion of the data transfer, the control unit presents Status to the channel. If the channel issues an early termination of the data transfers, the control unit will fill the remaining locations of the buffer with binary zeros. The load buffer function will normally be accompanied by the feed and punch Detail Bits. F = 0 Write in the compress mode. F = 1 Write in the image mode. Bits C thru E are specified under Control. A* =1 Load Read Buffer A =0 Load Punch Buffer *Buffer test. (A and D should not both be ones).
1.6	PXXXX0100	<u>Sense:</u>	The punch control transfers two sense bytes to the computer as input data. The first sense byte generally supplies details about any unusual conditions that occurred during the last operation. The channel can issue an early termination if the transfer of all sense bytes is not desired.
1.6.1			Prior to transmitting the sense data to the channel, the control unit will test the punch. The results of the test will modify the sense by setting additional flip-flops. The status will not be modified and no sense bits will be reset.
1.7	PXX010000	<u>Set Inhibit</u> <u>Status:</u>	This command is processed as a Test I-O Function. Status will be presented to the channel and Inhibit Status In will be set.
1.8	PXX100000	<u>Reset Inhibit</u> <u>Status:</u>	This command is processed as a Test I-O Function. Status will be presented to the channel and Inhibit Status In will be reset.

2. STATUS BYTE:

2.1 The status byte supplies information pertaining to conditions of the last operation. The status byte will be presented to the channel at the following times:

1. The end of the Initial Selection Sequence.
2. The completion of data transfers on the load or unload buffer commands.
3. The completion of card motion cycles.

The status register will be cleared when the channel responds to "Status In" with Service Out. The following list defines use of the bits in the Status Byte.

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
2.2	P	Odd Parity	Parity for Status Byte.
2.3	0	Attention	Not used. Bit always 0.
2.4	1	Status Modifier	Signaled with the busy bit to indicate that the control unit is busy either performing a previously initiated function or holding pending status on a unit other than the addressed unit
2.5	2	Control Unit End	Not Used. Bit always 0.
2.6	3	Busy	Indicates that the control unit cannot accept a command because of one of the following reasons: <ol style="list-style-type: none"> (a) Control is executing a previously initiated operation. (b) Control is holding pending status conditions from a previous operation of a unit other than the addressed unit. (c) Control is holding pending status conditions from the addressed unit.
2.6.1			Conditions (a) and (b) also present the status modifier bit. Busy can occur only during the Initial Selection Sequence. Busy will not be set if the command issued in (c) is a test I-0.
2.7	4	Channel End	If the selected device is the row punch, channel end indicates the completion of the data transfers between the buffer and the channel, or the acceptance of a control function. If Channel End is "stacked," the Control Unit will disconnect and try to present the status when the priority allows.

STATUS BYTE (continued)

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
2.7.1	4 (cont)		<p>Following is a list of conditions which will present channel end:</p> <ol style="list-style-type: none"> (1) Completion of data transfers during a punch order. (2) Acceptance of a control immediate function. (3) In an unload buffer function, channel end is presented with device end when the buffer to channel transfers are completed. (4) Channel End will be presented if a data parity error causes an early termination.
2.8	5	Device End	<p>Indicates the completion of a function initiated by the channel. In the Row Punch, Device End is presented in the following cases:</p> <ol style="list-style-type: none"> (1) At the completion of a punch command. (2) At the completion of a control immediate function. (3) Presented with Channel End when the data transfers during an unload buffer function are completed. (4) Presented when an error occurs which will not allow the completion of the punch command.
2.9	6	Unit Check	<p>One or more bits were set in Sense Byte 1 (bits 0 thru 5 or 7) when sampled by Channel End or Device End.</p>
2.9.1			<p>A parity error in the Function Byte, an Invalid Function or a Unit Abnormal when tested in the Initial Selection Sequence has been detected. In these cases, the Unit Check is sent to the channel during the Initial Selection Sequence</p>
2.9.2			<p>The punch was found to be non-ready when tested during Initial Selection. The function will be rejected and no end status will be generated. The normal sense bits will be set to indicate the type of error that occurred.</p>
2.10	7	Unit Exception	<p>If the selected device is the Row Punch, Unit Exception indicates a hole count error on the previous punch cycle. Unit Exception will be presented to the channel with Device End.</p>

3. SENSE DATA BYTES:

3.1 Sense data provides information about unusual conditions that occurred during the last operation. The sense information will be cleared when the next function is accepted, if the function is not a sense function or a test I-0. The status of various flip-flops in the control unit are transferred to these bytes. These bytes are to be used for error recovery routines or for maintenance functions in conjunction with failure finding routines.

3.2 Sense Byte 1:

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.1	P	Odd Parity	Parity bit for Sense Byte 1.
3.2.2	0	Command Reject	An unspecified command was issued by the channel. This bit is suppressed if bad parity is detected during transfer of the function code. Neither Channel End nor Device End is set in the status. The Invalid Command codes for the Row Punch are: PXXXX1X00 and PXX000X11
3.2.3	1	Intervention Required	A punch error, other than Hole Count, was detected during the previous operation. The fault may be empty hopper, stacker full, A jam, B jam, non-ready, stacker jam or full chip box. All errors with the exception of Hole Count require manual intervention.
3.2.4	2	Bus Out Check	Parity error on the function or data transfer to the control unit. If the control unit is not holding pending status, a parity error during the function transfer causes immediate termination and the suppression of Invalid Function. Neither Device End nor Channel End will be set in the Status Byte. If the control unit is holding pending status, a parity error during the function transfer will be ignored. The sequence will be handled as if the control unit was holding pending status and the function byte had good parity. Parity error during data transfer causes immediate termination. Channel End will be presented. Error status will be presented with Device End.
3.2.5	3	Card Jam	A card transport error has occurred. A jam in the pre-punch station will light the A jam indicator on the punch control panel. A jam in the post-punch station will light the B jam indicator on the punch control panel.

Sense Data Byte 1 (continued)

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.6	4	Data Check	Not used. Bit is always 0.
3.2.7	5	Data Late	The buffer has not been loaded prior to the initiation of punching.
3.2.8	6	Inhibit Status In	Inhibit Status In is set.
3.2.9	7	Non-Repeat Abnormal	Hopper Empty, Chips, Stacker Full, Stacker Jam.

3.3 Sense Data Byte 2:

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.3.1	P	Odd Parity	Parity Bit for Sense Byte 2.
3.3.2	0	Not used	
3.3.3	1	Not used	
3.3.4	2 } Punch 3 } Hole 4 } Counter	HCRPA HCRPB HCRPC	Prior to the initiation of a card cycle, these bits contain the weighted hole count of the card in the Punch Station.
3.3.5	5 } Post- Read 6 } Hole 7 } Counter	HCR2A HCR2B HCR2C	Prior to the initiation of a card cycle, these bits contain the weighted hole count of the card in the Post-Read Station.

9000 SERIES 1001 CONTROL1. COMMAND REPERTOIRE

- 1.1 The following command codes may be issued to the 1001 Control by the computer. Any other codes will be rejected and cause a Unit Check status (without Device End and Channel End) to be returned to the channel.

	<u>XF Code</u>	<u>Function</u>
Bit Position	P01234567	P = Odd Parity X is ignored by the 1001 Control. ABCDEF = Detail Bits

- 1.2 PXX000000 TEST I-0: 1001 Control sends a status byte to the channel and clears the Status Register and Status In when the channel responds that it has accepted the status byte.
or
PXX110000

- 1.3 PABCDEF10 READ: (Read Device Buffer)
Sequence for Card Controller:
The 1001 Control is in an input request mode and the Card Controller is on an output step.

Detail Bits Specified:

A = 0 Normal Operation
A = 1 Maintenance Mode. Command is executed in 1001 Control without initiating any action in the Card Controller or other device.

BCD: Not used with the Card Controller.
When Feature F0822-01 is included Bits BCD are presented to the systems slave interface on the 3 input control lines.

E = 0 Inhibit sending check character to the addressed unit.

E = 1 Send check character to the Card Controller.

F = 1 6-bit mode.
F = 0 Compress mode

COMMAND REPERTOIRE (continued)

	<u>XF Code</u>	<u>Command</u>
1.4	PABCDEX01	<p><u>WRITE</u>: (Transfer to Device Buffer) Sequence for Card Controller:</p> <p>The 1001 Control is in an output request mode and the Card Controller is on an input step. The 6 least significant bits of each 8-bit byte from the channel are transferred to the Card Controller.</p> <p><u>Detail Bits Specified</u>: Same as READ Command except "BCD" are presented to the systems slave interface in the 3 output control lines. Also, Detail Bit F is not used.</p>
	<u>XF Code</u>	<u>Command</u>
	Bit Position P01234567	
1.5	PAXXX0100	<p><u>SENSE</u>: The 1001 Control transfers the Sense byte to the computer as input data. In addition to supplying pertinent information to the program, this data can be used as maintenance aids. The sense byte provides detailed information about unusual conditions detected in the last operation which were initially signaled to the computer in the status byte during Status In. The Card Controller is tested for abnormal prior to transferring the Sense byte to the channel. This condition is indicated in Bit 1 of Sense Byte 1. Note that if abnormal is set during the execution of any function other than a TEST I-O or SENSE, the unit check (Bit 6) is also set in the status.</p> <p><u>Detail Bit Specified</u>:</p> <p>A = 0 Normal Operation A = 1 Maintenance Mode. The operation is normal except the device test is blocked.</p>
1.6	PXX010000	<p><u>Set Inhibit Status</u>: This command is processed as a TEST I-O Function. (If accepted, it does not generate any new status.) Status will be presented to the channel and Inhibit Status In will be reset.</p>
1.7	PXX100000	<p><u>Reset Inhibit Status</u>: This command is processed as a TEST I-O Function. (If accepted it does not generate any new status). Status will be presented to the channel and Inhibit Status In will be reset.</p>

COMMAND REPERTOIRE (continued)PXX100000
(cont.)Reset Inhibit Status (cont.)

The condition of the Inhibit Status In can be examined in Sense byte 1, bit position 6. When Inhibit Status is set, the 1001 Control will not initiate any sequences to present status. The Set Inhibit Status command should not be issued if the 1001 Control is connected on a selector channel.

2. STATUS BYTE

2.1 The Status byte provides the overall information about status and conditions detected in the last operation. The Status byte will be stored in the Status Register and will be transmitted to the channel on the BUS IN during the Status In. The Status In is initiated at the end of the initial selection sequence and at the completion of the data transfers. The Status Register will be cleared when the channel responds to the Status In with Service Out. The following defines the significance of each status bit.

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
2.2	P	Odd Parity	Parity for Status byte.
2.3	0	Attention	Not used. Bit is always 0.
2.4	1	Status Modifier	Present with busy bit to indicate 1001 Control is busy either executing a previously initiated operation, or is holding pending status from a previous operation of a unit other than the addressed unit.
2.5	2	Control Unit End	Not used. Bit is always 0.
2.6	3	Busy	Indicates that 1001 Control cannot accept a command because one of the following conditions exists: a) 1001 Control is executing a previously initiated operation. b) 1001 Control is holding pending status conditions from a previous operation of a unit other than the addressed unit. c) 1001 Control is holding pending status conditions from a previous operation of the addressed unit. (Not applicable to TEST I-O or Set or Reset Inhibit status). Conditions a) and b) above also present Bit 1 (status modifier). Busy can occur only during the initial selection sequence.
2.7	4	Channel End	Indicates the completion of the data transfers between the channel and the Card Controller. Note early termination if abnormal is detected.
2.8	5	Device End	Same indication as Bit 4 (Channel End).
2.9	6	Unit Check	Set simultaneously with the setting of Bit 0, 1, or 2 in Sense byte 1, except if Bit 1 of the Sense byte is set when the Card Controller is tested during a sense command.
2.10	7	Unit Exception	Not used. Bit is always 0.

3. SENSE BYTE

Sense Byte

3.1 Sense data provide detailed information about the unusual conditions detected in the last operation and the status of the Card Controller (or other unit). The Sense data will be cleared when the next command is accepted, if the command is not a SENSE command or TEST I-0. The following describes the significance of the Sense Data.

3.2 Sense Byte 1

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.1	P	Odd Parity	Parity for Sense Byte 1.
3.2.2	0	Command Reject	Unspecified command issued to 1001 Control. This bit is suppressed if the command byte has bad parity (bit 2 BUS OUT check). The following are invalid command codes: PXXXXX000, PXXXX1X00, PXXXXX11.
3.2.3	1	Intervention Required	Indicates Card Controller is stopped. (The Card Controller, while selected, signals abnormal on the System Slave Interface). The error or fault condition in the Card Controller may be misfeed, card jam, stacker full, or hopper empty. Manual intervention is required.
3.2.4	2	BUS OUT Check	Parity error. Even parity appeared on the BUS OUT from the channel during the command or data transfer. Bit 0, "Command Reject," is suppressed when Bit 2 is indicating a parity error in the command byte.
3.2.5	3	Run Off	Bit is 0 except in some cases following a Selective Reset or Interface Disconnect sequence.
3.2.6	4		Indicate the status of control logic flip-flops. Primarily intended to be used in conjunction with failure finding programs.
3.2.7	5		
3.2.8	6	Inhibit Status	Inhibit Status In is set.
3.2.9	7	Undefined	

Function Codes

6-C Control Unit No. 0858-XX

<u>COMMAND</u>	<u>BIT POSITIONS</u>							<u>HEX</u>	
	<u>0</u>	<u>1</u>	<u>2</u>	<u>3</u>	<u>4</u>	<u>5</u>	<u>6</u>		<u>7</u>
Set Inhibit Status	0	0	0	1	0	0	0	0	10
Reset Inhibit Status	0	0	1	0	0	0	0	0	20
Sense	0	0	0	0	0	1	0	0	04
Write	0	0	0	0	0	0	0	1	01
Read	0	0	0	0	0	0	1	0	02
Read Backward	0	0	0	0	1	1	0	0	0C
Control	0	0	C	C	C	1	1	1	
Rewind	0	0	0	0	0	1	1	1	07
Rewind with Interlock	0	0	0	0	1	1	1	1	0F
Erase	0	0	0	1	0	1	1	1	17
Write Tape Mark	0	0	0	1	1	1	1	1	1F
Backspace Block	0	0	1	0	0	1	1	1	27
Backspace File	0	0	1	0	1	1	1	1	2F
Forward Space Block	0	0	1	1	0	1	1	1	37
Forward Space File	0	0	1	1	1	1	1	1	3F
Mode Set	D	D	M	M	M	0	1	1	
No Operation	X	X	0	0	0	0	1	1	X3
Reset Fault-Finding Modes	0	0	0	0	1	0	1	1	0B
Set Device Simulation Mode	0	1	0	0	1	0	1	1	4B
Set Operation Monitor Mode	1	0	0	0	1	0	1	1	8B
Set Low Gain	0	1	0	1	1	0	1	1	5B

FOR 7 TRACK TAPE ONLY

								<u>200</u>	<u>556</u>	<u>800</u>	
Odd Parity, Converter On	D	D	0	1	0	0	1	1	13	53	93
Even Parity, Converter Off	D	D	1	0	0	0	1	1	23	63	A3
Odd Parity, Converter Off	D	D	1	1	0	0	1	1	33	73	B3

X = Either 1 or 0
DD = tape density as follows:

- 00 = 200 bpi
- 01 = 556 bpi
- 10 = 800 bpi
- 11 = not used

Practically all other code combinations, of which there are over 200, are invalid.

U6-C Subsystem Type 0858-XX

STATUS, SENSE DATA, MONITOR SENSE DATA, AND SENSE BYTE BIT-DECODE MNEMONICS*

	BIT	0	1	2	3	4	5	6	7
	STATUS BYTE	ATTENTION	STATUS MODIFIER	CONTROL UNIT END	BUSY	CHANNEL END	DEVICE END	UNIT CHECK	UNIT EXCEPTION
S E N S E	BYTE 0	INVALID FUNCTION *CMRJ	INTERVENTION REQUIRED *INRQ	OUTPUT BUS CHECK *BSCK	EQUIPMENT CHECK *EQCK	DATA CHECK *DAK	DATA LATE *OVRN	WORD COUNT ZERO *WDCZ	DATA CONVERTER CHECK *DCK
	BYTE 1	NOISE *NOIS	TAPE UNIT STATUS "A" *TUSA	TAPE UNIT STATUS "B" *TUSB	SEVEN TRACK *7TRK	LOAD POINT *BOT	END OF TAPE *EOT	FILE PROTECT *TUFP	"0" *TUIC
	BYTE 2	"0" *TIE0	"0" *TIE1	"0" *TIE2	"0" *TIE3	"0" *TIE4	"0" *TIE5	"1" *TIE6	"1" *TIE7
	BYTE 3	READ VERTICAL RED.CHECK *RVRC	LONGITUDINAL REDUNDANCY CHECK *LRC	SKEW *SKEW	CYCLIC REDUNDANCY CHECK *CRC	WRITE VERTICAL RED. CHECK *WVRC	"0" *TUPH	BACKWARD *BKWD	"0" *SB37
	BYTE 4	RUNAWAY *RWAY	TAPE MOTION FAULT *TMFT	"0" *SB42	"0" *SB43	"0" *SB44	STALL *STAL	TAPE FAULT *TPFT	"0" *SB47
M O N I T O R S E N S E	BYTE 0	PROGRAM COUNT Bit 0 *PC00	PROGRAM COUNT Bit 1 *PC01	PROGRAM COUNT Bit 2 *PC02	DENSITY Bit 0 *DENO	DENSITY Bit 1 *DEN1	EVEN PARITY *EPAR	DATA CONVERTER ON *DCON	FAULT FINDING MODE ON *SIM
	BYTE 1	WRITE *WRIT	READ *READ	BACKWARD *BKWD	SPACE *SPAC	FILE *FILE	REWIND *REW	WRITE TAPEMARK *WTM	ERASE *ERAS
	BYTE 2	BACKWARD/LOADPOINT *PRER	EARLY GAP WRITE *EGAP	TAPE MARK DETECTED *TMD	LOW GAIN *LOWG	EARLY TERMINATE *CTRM	INHIBIT STATUS IN *PSTA	CRC Bit 0 *CRC0	CRC Bit 1 *CRC1
	BYTE 3	CRC Bit 2 *CRC2	CRC Bit 3 *CRC3	CRC Bit 4 *CRC4	CRC Bit 5 *CRC5	CRC Bit 6 *CRC6	CRC Bit 7 *CRC7	CRC Bit P *CRCP	LPC Bit 0 *LRC0
	BYTE 4	LPC Bit 1 *LRC1	LPC Bit 2 *LRC2	LPC Bit 3 *LRC3	LPC Bit 4 *LRC4	LPC Bit 5 *LRC5	LPC Bit 6 *LRC6	LPC Bit 7 *LRC7	LPC Bit P *LRCP

SH04479
 SPECIFICATION SYMBOL

SHEET 11-2 REVISION -



SPECIFICATION SHEET

6-C TAPE CONTROL UNIT NO. 0858-XX
COMMAND REPERTOIRE

- 1.1 The command byte is transmitted by the Channel during the Initial Selection sequence. The Control Unit checks the parity and validity before accepting the Command. Invalid Commands are code combinations not described or MODE SET Commands without the corresponding features in the Control Unit.
- 1.2 TEST (X X 0 0 0 0 0 0 or X X 1 1 0 0 0 0)
- A TEST command initiates the sequence of presenting a status byte to the Channel at the end of Initial Selection sequence. The status may include the stored status of the addressed unit. When the status byte is accepted by the Channel, the STATUS IN pending state will be cleared and the status register will be cleared to binary zero. The TEST Command generates no new status and is completed at the end of the Initial Selection sequence.
- 1.3 SET INHIBIT STATUS (X X 0 1 0 0 0 0)
- This Command is performed as a TEST Command. In addition, the Command sets the Inhibit Status In condition which inhibits the Control Unit from initiating the Request In sequence to present status to the Channel. Under this condition, the status will be presented to the Channel only at the end of the Initial Selection sequence. This condition remains set until reset by a System or Selective Reset, or by a RESET INHIBIT STATUS function.
- 1.4 RESET INHIBIT STATUS (X X 1 0 0 0 0 0)
- This Command is performed as a TEST Command. In addition, the Command resets the Inhibit Status In condition.
- 1.5 SENSE (0 0 0 0 0 1 0 0)
- The SENSE Command tests and stores the current status of the selected tape unit and then proceeds to transfer the sense bytes to the Channel. The information in the sense bytes contains the current status of the tape unit and any unusual conditions detected during the last operation. The transfer rate of the sense bytes is set to approximately the same rate as the nominal data transfer rate. The status byte presented at the completion of the SENSE Command will contain the status as the results of the SENSE operation. The status byte will contain CHANNEL END bit (bit 4) and DEVICE END bit (bit 5).
- 1.6 WRITE (0 0 0 0 0 0 0 1)
- 1.6.1 The WRITE Command moves tape on the selected unit in a forward direction. Data is fetched from the Channel and is written on tape until the Channel terminates the data transfer. The end status byte will include the UNIT EXCEPTION bit (bit 7), if a WRITE operation is performed in the end-of-tape area.

WRITE (0 0 0 0 0 0 1) (cont)

1.6.2 The following description of normal termination applies for WRITE, READ and READ BACKWARD operations: The end status byte, consisting of the CHANNEL END bit (bit 4) and the DEVICE END bit (bit 5) along with other status bits—if any, will be presented to the Channel when the end-of-block is detected on the Read or Check Read. The end of block is detected when the data signal from the tape has ceased for more than 800 μ s.

1.7 READ (0 0 0 X 0 0 1 0)

1.7.1 The READ Command moves tape on the selected unit in a forward direction and reads a block of data from tape. The data is transferred to the Channel until the end-of-block occurs or the Channel terminates the transfer.

1.7.2 The end status byte will include the UNIT EXCEPTION bit (bit 7) if the block read is a Tape Mark Block. (The Tape Mark character will not be transferred to the Channel when detected as a single character Tape Mark block. However, if the Tape Mark code appears anywhere in the body of a multiple-character block, it will be transferred to the Channel as data.) 7-track Tape Mark is detected in both even and odd parity modes during "Read" and "Space" operations.

1.8 READ BACKWARD (0 0 0 X 1 1 0 0)

1.8.1 The READ BACKWARD Command moves tape on the selected unit in the backward direction and reads a block of data in the reverse order in which it was written on the tape. The data is transferred to the Channel until the end-of-block occurs or the Channel terminates the transfer. The READ BACKWARD operation will not be initiated if the tape is at load point on testing. In this case, the status byte presented to the Channel will contain the UNIT CHECK bit only.

1.8.2 Moving the tape backward into Load Point during the READ BACKWARD operation will cause the UNIT CHECK bit (bit 6) and the UNIT EXCEPTION bit (bit 7) to be set in status.

1.8.3 The READ BACKWARD operation in 7-track mode should not be attempted using tapes generated by other than UNISERVO VI-C, UNISERVO VIII-C, UNISERVO XII, UNISERVO XVI or other tape units which provide scatter correction of the LRC Frame.

1.8.4 The READ BACKWARD operation in 7-track data conversion mode should not be attempted with tapes having block length other than a multiple of four frames.

1.8.5 Sensing a Tape Mark is the same as in READ operations.

1.9 CONTROL (0 0 C C C 1 1 1)

CONTROL Commands involve no transfer of data. When the selected tape unit is tested and is in an operational state, the status byte consisting of the CHANNEL END bit (bit 4) only will be presented to the Channel. The end status byte will include the CONTROL UNIT END bit (bit 2) if the Control Unit was addressed or an unusual condition was detected and caused UNIT CHECK or UNIT EXCEPTION bits to be set while the Control Unit was busy independently of the Channel. The Control Unit is considered busy independently of the Channel during the interval between the TRANSMISSION of the status byte containing the CHANNEL END bit and GENERATION of the end status byte containing the DEVICE END bit. The particular control operation is specified by the modifier bits (C C C) of the function. The description of each is as follows:

1.10 REWIND (C C C = 0 0 0)

1.10.1 This command rewinds the tape on the selected unit to load point. The operation in the Control Unit terminates after the rewind has been initiated in the tape unit. The end status byte consisting of DEVICE END will be presented to the Channel.

The operation in the tape unit terminates when the tape is positioned at Load Point.

1.10.2 If the unit being rewound is addressed with a command other than a SENSE Command, the status of that Command will contain the UNIT CHECK bit (bit 6) only, to indicate the addressed tape unit is busy.

1.11 REWIND WITH INTERLOCK (C C C = 0 0 1)

This Command rewinds the tape on the selected unit to Unload point and sets the interlock condition in the tape unit. The operation in the Control Unit terminates after the rewind with interlock has been initiated in the tape unit. The end status byte consisting of the UNIT CHECK bit (bit 6) and the DEVICE END bit (bit 5) will be presented to the Channel. The normal end status byte will not include the CONTROL UNIT END bit (bit 2). The operation in the tape unit terminates when the tape is positioned at Unload Point. If a Unit under the interlock condition is addressed with a Command other than a SENSE Command, the status byte of that Command will contain the UNIT CHECK bit (bit 6) only, to indicate the addressed tape unit is unavailable. The interlock condition of the tape unit is removed only by manual intervention.

1.12 ERASE (C C C = 0 1 0)

1.12.1 This Command moves the tape on the selected unit forward and erases tape for approximately 3.5 inches. The end status byte consisting of the DEVICE END bit (bit 4) along with other bits, if any, will be presented to the Channel when the the Erase timing in the Control Unit has expired.

1.12.2 The end status byte will include the UNIT EXCEPTION bit (bit 7) if the ERASE operation is performed in the end-of-tape area. The check read is activated to

check for spurious pulses arising from any portion of the tape that is un-erased.

1.13 WRITE TAPE MARK (C C C = 0 1 1)

- 1.13.1 This Command moves the tape on the selected unit in a forward direction and generates an interblock gap of approximately 3.5 inches by erasing, then writes a Tape Mark.
- 1.13.2 WRITE TAPE MARK operation for a 7-track mode overrides the parity mode setting and writes the Tape Mark with even parity.
- 1.13.3 The end status byte will include the UNIT EXCEPTION bit (bit 7), if the operation is performed in the end-of-tape area.
- 1.13.4 When the end-of-block is detected on Check Read, the end status byte consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the Channel.

1.14 BACKSPACE BLOCK (C C C = 1 0 0)

- 1.14.1 This Command moves tape on the selected unit to the next interblock gap in the backward direction. When the end-of-block is detected on Read, the end status byte consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the Channel.
- 1.14.2 The operations at or into Load Point and sensing a Tape Mark are the same as in READ BACKWARD.
- 1.14.3 During 7-track BACKSPACE BLOCK or BACKSPACE FILE operations, a Tape Mark may be erroneously identified on tapes generated by other than UNISERVO VI-C, UNISERVO VIII-C, UNISERVO XII, UNISERVO XVI or other tape units which provide scatter correction of LRC character. Verification of a Tape Mark is accomplished by reading forward.

1.15 BACKSPACE FILE (C C C = 1 0 1)

- 1.15.1 This Command moves tape on the selected unit backward to the interblock gap beyond the next Tape Mark Block. If a Tape Mark is not encountered, the tape will stop at Load Point.
- 1.15.2 Moving tape backward into Load Point will cause the UNIT CHECK bit (bit 6) to be included in the end status byte.
- 1.15.3 A BACKSPACE FILE operation will not be initiated if the tape is at Load Point on testing. The Status Byte presented to the Channel will contain the UNIT CHECK bit only.

- 1.15.4 Sensing the Tape Mark will not cause the UNIT EXCEPTION bit (bit 7) to be included in the end status byte.
- 1.15.5 When the End of Tape Mark Block is detected, the end status byte consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the Channel.
- 1.16 FORWARD SPACE BLOCK (C C C = 1 1 0)
- This Command moves the tape on the selected unit forward to the next interblock gap. Sensing a Tape Mark will cause the UNIT EXCEPTION bit (bit 7) to be included in the end status byte. When the end-of-block is detected, the end status byte consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the Channel.
- 1.17 FORWARD SPACE FILE (C C C = 1 1 1)
- 1.17.1 This Command moves the tape on selected unit forward to the interblock gap beyond the next Tape Mark block. Sensing the Tape Mark will not cause the UNIT EXCEPTION bit (bit 7) to be included in the end status byte.
- 1.17.2 When the End of Tape Mark block is detected, the end status byte consisting of DEVICE END bit (bit 5) along with other bits, if any, will be presented to the Channel.
- 1.18 MODE SET (D D M M M 0 1 1)
- 1.18.1 The MODE SET Command is used to select the data transfer mode of operation. The specific mode is defined by bits 0, 1, 2, 3, and 4 of the Function. Once set, data transfer modes remain set until changed by another MODE SET Command or reset by the Channel. The reset conditions are 800 bpi and Odd Parity. If the data converter feature is installed, the reset conditions are 800 bpi, Odd Parity and Data Converter On.
- 1.18.2 The 7-track Mode Setting is active only with the 7-track Tape Unit and has no effect upon the 9-track operation. MODE SET Commands are completed during the Initial Selection sequence.
- 1.18.3 The End Status Byte consisting of the CHANNEL END bit (bit 4) and the DEVICE END bit (bit 5) will be presented to the Channel at the end of the Initial Selection sequence.
- 1.18.4 The MODE SET Command will not clear the sense bytes when accepted.
- 1.18.5 The specific MODE SET Command is defined as follows:

1.20 MODE (000)

This defines a "No Operation". No operation will be performed.

1.21 MODE (001)

This mode is used for failure-finding only. Non-diagnostic programs should not attempt to set this mode of operation.

1.22 MODE (010)

This mode defines a 7-track mode with Odd Parity, Data Converter On and a Density defined by the DD Bits.

1.23 MODE (011)

When DD = 01, this mode defines a Low Gain setting for the next "Read" or "Space" operation. The Low Gain condition will be cleared at the end of the operation following the MODE SET.

1.24 MODE (100)

This mode defines a 7-track mode with Even Parity, Data Converter Off, and a Density defined by the DD Bits.

1.25 MODE (101)

This mode is not used (invalid Command).

1.26 MODE (110)

This mode defines a 7-track mode with Odd Parity, Data converter Off, and a Density defined by the DD Bits.

1.27 MODE (111)

This mode is not used (invalid Command).

1.3 MAINTENANCE COMMANDS1.3.1 RESET FAILURE-FINDING MODES (00001011)

This command resets the Device Simulation Mode and Operation Monitor Mode, if they were set. The control unit will return to the normal state. The System Reset, or Selective Reset, will also reset these modes.

1.3.2 SET DEVICE SIMULATION MODE (01001011)

This command activates the tape unit simulation logic. The signals to the tape unit will be blocked and simulated return signals will be generated during the execution of subsequent commands. This facilitates the checkout of the control unit without a tape unit.

1.3.3 SET DEVICE SIMULATION MODE (01001011) (cont)

- 1.3.3.1 For write operation, the write data received from the Channel will be processed through the write logic, then will be fed back into the read recovery logic. The Cyclic Redundancy Check (CRC) frame will be generated, but a Longitudinal Redundancy Check (LRC) frame will not be generated. However, the content of the LRC register will be the LRC frame supposed to be written on the tape.
- 1.3.3.2 For read operation, the content of the CRC register will be used as the simulated data. The content will be shifted end-around one place from high to low order for every frame generated. The simulated data will be generated at nominal data frequency until it receives the data terminate signal from the Channel.
- 1.3.3.3 The output of CRC register will be added with the R. O. pattern (111010111) in binary addition before it is gated into the read recovery logic. The CRC register will be precleared only before a write, simulated write, or read operation.
- 1.3.3.4 To set up desired data in the CRC register for the simulated read, a write operation should be performed beforehand. The parity of the content of the CRC register depends on the number of characters written during the previous write operation. The vertical parity checker in the read recovery can be checked with the data having a wrong parity.
- 1.3.3.5 If the initial content or the shifted content of the CRC register does correspond with R. O. pattern, the generated data block will have a blank frame for every ninth frame. By this, the frame dropout checker in the read recovery can be checked.
- 1.3.3.6 For Write Tape Mark operation, the generated Tape Mark frame will be gated into the read recovery logic.
- 1.3.3.7 For space, or space file operation, one frame of the generated data from the CRC register will be gated into the read recovery logic. The tape mark indications will be set if the generated data correspond with the tape mark code.
- 1.3.3.8 The erase operation will be executed in the normal manner.

1.3.2 SET OPERATION MONITOR MODE (10001011)

- 1.3.4.1 This command activates the logic which transmits the Monitor Sense bytes instead of the Sense Data bytes during the subsequent sense operation(s).
- 1.3.4.2 The Monitor Sense bytes (5 bytes) provide detailed information about the operational condition caused by the last operation.

2. Status Byte

- 2.1 The Status Byte provides the overall information about status and conditions detected in the operation completed. The Control Unit initiates the sequences to present status to the Channel at the end of the Initial Selection sequence, at the completion of unit selection of a control operation and at the completion of the operation. The status bits are reset to Binary Zero when the status presented is accepted by the Channel. The following defines the significance of Binary One in each status bit.

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
2.2	0	Attention	Not used, always zero.
2.3	1	Status Modifier	Present with the BUSY bit to indicate Control Unit busy.
2.4	2	Control Unit End	When the Control Unit Completes a CONTROL operation that kept it busy independently of the channel, during which time it was either addressed (causing a Control Unit busy indication) or an unusual condition was detected (UNIT CHECK or UNIT EXCEPTION), CONTROL UNIT END will be presented with DEVICE END. The Control Unit is considered busy independently of the channel during the interval between the TRANSMISSION of the CHANNEL END Status Byte and the Generation of the DEVICE END status byte.
2.5	3	Busy	a) Present with STATUS MODIFIER to indicate Control Unit busy.
2.5.1			b) Present with status already stored if status pending for addressed tape unit, when the Command is other than a TEST, SET INHIBIT STATUS or RESET INHIBIT STATUS.
2.6	4	Channel End	For SENSE, WRITE, READ and READ BACKWARD Commands, CHANNEL END is presented with DEVICE END when the operation is completed at the Control Unit Level and presented on a CONTROL COMMAND, after the tape unit is tested and available. If early errors prevent tape motion, and the operation is aborted early, the CHANNEL END status bit is not sent to the channel. It is also presented at the end of initial selection with DEVICE END on MODE SET functions.
2.7	5	Device End	Indicates that the operation is complete at the Control Unit level. When errors are detected before tape motion is initiated, DEVICE END is not presented with error status. Operations that are aborted when in progress (e.g. Equipment Check) will cause DEVICE END to be sent with UNIT CHECK and CHANNEL END.
2.8	6	Unit Check	a) A bit in Sense Byte 0 has been set as a result of the current operation. If an error condition is detected before tape motion is initiated, UNIT CHECK will be presented without end status.
2.8.1			b) A READ BACKWARD, BACKSPACE BLOCK, or BACKSPACE FILE has been attempted on a tape unit with the tape positioned at load point (no end status is presented in this case).

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
2.8.2		c) A REWIND WITH INTERLOCK has been completed at the Control Unit level, i.e. when the tape unit becomes non-ready. If the operation is initiated, DEVICE END will be presented with UNIT CHECK and CONTROL UNIT END.
2.8.3		d) The asynchronous response of busy (ready and re-winding) is indicated by presenting Unit Check without ending status.
2.9	7 Unit Exception	<u>Indicates:</u>
		a) A WRITE, WRITE TAPE MARK or ERASE operation is performed in the end-of-tape area.
2.9.1		b) A Tape Mark is sensed during a READ, READ BACKWARD, FORWARD SPACE BLOCK, or BACKSPACE BLOCK operation. In cases a) and b) UNIT EXCEPTION is presented with DEVICE END.
2.9.2		c) When tape is moved into Load Point by READ BACKWARD or BACKSPACE Commands, UNIT EXCEPTION is presented with CONTROL UNIT END, UNIT CHECK, and DEVICE END.

3. Sense Data Bytes

3.1 The sense data provides detailed information about unusual conditions detected in the last operation and the current status of the selected tape unit. Sense information bits that are modified with the current status of the tape unit are indicated by an asterisk(*). No additional sense information can be set as a result of executing a SENSE Command once the Command has been accepted (i.e. odd parity and valid function code).

The following describes the significance of the sense bytes.

3.2 Sense Byte 0

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.1	0 Invalid Command	a) Set when a WRITE, WRITE TAPE MARK, or ERASE operation was attempted on a file-protected tape unit.

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.2	0 Invalid Command (cont)	b) Set when an invalid Command is transmitted to the Control Unit (this condition will not be set if a BUS OUT check occurred on a Command transfer).
3.2.3	1 Intervention Required	Set whenever tape unit status A is inactive, i.e. a non-existent or non-ready tape unit was selected (on other than a SENSE Command. (Bit 1 is not set in Sense Byte 1.)
3.2.4	2 Output Bus Check	Set whenever Even Parity appears on the BUS OUT for data or Command transfers. During WRITE operations, if this condition is set on a data transfer, the operation is terminated, and the error byte is not written on the tape. If the error occurs on the first data transfer, Word Count Zero will be set in conjunction with BUS OUT check.
3.2.5	3 Equipment Check	Set whenever an Equipment Check occurs, i.e., bits 0 or 1 or 5 of Sense byte 4 has been set.
3.2.6	4 Data Check	Set whenever a Data Check occurs, i.e., bit 0 of Sense byte 1, or bits 0, 1, 2, 3, or 4 of Sense byte 3 have been set.
3.2.7	5 Data Late	Set if service is requested on the I/O Interface but data cannot be transferred due to a late SERVICE OUT signal from the channel (not set on SENSE Command).
3.2.8	6 Word Count Zero	Set during a WRITE operation if transfer of data is prevented when the first byte of data is requested. No tape motion will occur if this condition is detected.
3.2.9	7 Data Converter Check	Set on 7-track operation only.
3.3	<u>Sense Byte 1</u>	
<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
3.3.1	0 Noise	During WRITE or WRITE TAPE MARK operations, indicates that the GAP signal was detected sooner than was expected. False GAP can occur due to Data Dropout.

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>																				
3.3.1.1	0 Noise (cont)	During WRITE or WRITE TAPE MARK operations, indicates that Bit 6 of SENSE BYTE 4 is set, due to the FALSE END of block.																				
3.3.1.2		During READ, READ BACKWARD, FORWARD SPACE BLOCK, and BACKSPACE BLOCK operations, indicates that data was recognized after the LRC byte but not long enough after to be considered a new block. Data detected after the LRC byte set the noise bit and maintain tape motion but are not transferred. This condition can occur due to a "drop-out" of data during the block, causing a false LRC byte to be detected.																				
3.3.2	1* Tape Unit Status A	Selected and Ready.																				
3.3.3	2* Tape Unit Status B	Not ready, rewinding or under control of the other Control Unit.																				
		<table border="1"> <thead> <tr> <th>Status A</th> <th>Status B</th> <th>Tape Unit Status</th> <th>Bit set in Status Byte</th> </tr> </thead> <tbody> <tr> <td>0</td> <td>0</td> <td>Non-existent</td> <td>UNIT CHECK</td> </tr> <tr> <td>0</td> <td>1</td> <td>Not ready</td> <td>UNIT CHECK</td> </tr> <tr> <td>1</td> <td>0</td> <td>Ready and not busy</td> <td>----</td> </tr> <tr> <td>1</td> <td>1</td> <td>Ready and busy, i.e. rewinding.</td> <td>UNIT CHECK</td> </tr> </tbody> </table>	Status A	Status B	Tape Unit Status	Bit set in Status Byte	0	0	Non-existent	UNIT CHECK	0	1	Not ready	UNIT CHECK	1	0	Ready and not busy	----	1	1	Ready and busy, i.e. rewinding.	UNIT CHECK
Status A	Status B	Tape Unit Status	Bit set in Status Byte																			
0	0	Non-existent	UNIT CHECK																			
0	1	Not ready	UNIT CHECK																			
1	0	Ready and not busy	----																			
1	1	Ready and busy, i.e. rewinding.	UNIT CHECK																			
3.3.4	3* Seven Track	The selected unit has a seven-track head installed.																				
3.3.5	4* Load Point	The tape on the selected unit is positioned at load point.																				
3.3.6	5* End of Tape	The tape on the selected unit is in the end-of-tape area.																				
3.3.7.	6* File Protect	The tape on the selected unit does not have a write enable ring.																				
3.3.8	7	Not used - Always set to Zero.																				

3.4 Sense Byte 2

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
0	Track in Error	Bits 6 and 7 set to 1's unconditionally upon a Data Check.
↓		
7		

3.5 Sense Byte 3

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
3.5.1	0 R/W VRC	a) A Vertical Redundancy Check occurred on a Data Frame or CRC Frame during a READ or READ BACKWARD operation. This indicator is not set after a Data Late indication. b) A speed check error occurred during a WRITE or WRITE TAPE MARK operation.
3.5.2	1 LRC	A Longitudinal Redundancy Check occurred during a WRITE, WRITE TAPE MARK, READ, or READ BACKWARD operation.
3.5.3	2 Skew	Excessive skew detected while read-checking recorded data on a WRITE or WRITE TAPE MARK operation.
3.5.4	3 CRC	Cyclic Redundancy Check on READ.
3.5.5	4 W/VRC	A Vertical Redundancy Check occurred on a Data Frame or CRC Frame during a WRITE or WRITE TAPE MARK operation.
3.5.6	5	Not used - Always set to Zero.
3.5.7	6* BACKWARD	The selected Tape Unit is in BACKWARD Condition.
3.5.8	7	Not used - Always set to Zero.

3.6 Sense Byte 4

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
3.6.1	0 Runaway Check	a) While read checking recorded data during WRITE or WRITE TAPE MARK operations, data was not detected within at least 10 ms. after writing has commenced.

Sense Byte 4 (cont)

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
0	Runaway Check (cont)	b) During all read-type operations, if data is not detected in at least 15 seconds.
3.6.2	1 Tape Motion Fault	a) Tape unit failed to respond to a "start" command. Tape motion may or may not have occurred. b) Tape motion stopped independently of the Control Unit during an operation requiring tape movement. (This condition will be detected if a backward operation is executed <u>into</u> load point.)
3.6.3	2 These bits are reserved for failure-finding mode. ↓ 4	<hr/>
3.6.4	5 Stall	Indicates that the Control Unit is HUNG UP for more than 15 seconds.
3.6.5	6 Tape Fault	During WRITE or TAPE MARK Operation, indicates that end of block was detected sooner than expected. False End of Block can occur when the data drop in the block is longer than 800 μ s.
3.6.6	7 This Bit is reserved for failure-finding mode.	<hr/>

4. MONITOR SENSE BYTES

4.1 Monitor Sense Byte 0

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
4.1.1	0	Program Count 2^0	These three bits hold the program count when a stall condition occurs. The hold is Released when Sense byte 4, Bit 5 is cleared. Since the Monitor Sense byte 0 is transmitted to the channel during the program count of 1, the Channel normally sees $2^0 = 1$, $2^1 = 0$ and $2^2 = 0$.
4.1.2	1	Program Count 2^1	
4.1.3	2	Program Count 2^2	
4.1.4	3	Density Bit 0	Density setting in the Mode Register. The clear condition will be Bit 0 = 1 and Bit 1 = 0. If 7-track feature is not installed, then Bit 0 = 1 and Bit 1 = 1.
4.1.5	4	Density Bit 1	
4.1.6	5	Even Parity	Even parity mode is set and 7-track unit is selected. If 7-track feature is not installed, this bit will always be zero. This bit will be zero for the clear condition.
4.1.7	6	Data Converter On	Data converter mode is set and 7-track unit is selected.
4.1.8	7	Failure-Finding Mode	Device simulation mode is set. This bit will be zero for the clear condition.

4.2 Monitor Sense Byte 1

Monitor Sense byte 1 holds the previously accepted I/O command other than the Sense or Monitor Sense command. The sampling of the command register will be made when the tape unit is being selected. Monitor Sense byte 1 can be cleared with System Reset, but not with Selective Reset.

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
4.2.1	0	Write	Write command.
4.2.2	1	Read	Read or Read Backward command.
4.2.3	2	Backward	Read backward, Backspace block or Backspace file command.
4.2.4	3	Space	Backspace block, Backspace file, Forward space block, or Forward space file command.
4.2.5	4	File	Backspace file or Forward space file command.
4.2.6	5	Rewind	Rewind or Rewind-with-interlock command.
4.2.7	6	Write Tape Mark	Write tape mark command.
4.2.8	7	Erase	Erase command.

4.3 Monitor Sense Byte 2

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
4.3.1	0	Backward/Load Point	A backward command was issued at Load Point. The bit will be cleared at the beginning of the next command other than Sense or Monitor Sense.
4.3.2	1	Early Gap/Write	A gap in the record was detected earlier than expected on a write operation. A detail breakdown on Sense Byte 1, Bit 0. The bit will be cleared as was Bit 0.
4.3.3	2	Tape Mark Detected	Tape Mark was detected on a read, space, or space file operation. There is no significance on this bit for other operations.
4.3.4	3	Low Gain	Previous command was a low gain mode set command.
4.3.5	4	Data Terminate	The control unit did not receive a data terminate signal from the Channel and terminated the data transfer because of data exhaustion. This includes the case where the byte count of the channel is equal to the number of the data bytes to be transmitted. Sense and Monitor Sense commands are included. The bit will be cleared at the beginning of the next command other than Sense or Monitor Sense.
4.3.6	5	Inhibit Status In	Inhibit Status In condition is set.
4.3.7	6	CRC Bit 0	CRC register output Bit 0. The CRC register will be precleared on a write, simulated write, or read operation.
4.3.8	7	CRC Bit 1	CRC register output Bit 1.

4.4 Monitor Sense Byte 3

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
	0	CRC Bit 2	CRC register output Bit 2.
	1	CRC Bit 3	CRC register output Bit 3.
	2	CRC Bit 4	CRC register output Bit 4.
	3	CRC Bit 5	CRC register output Bit 5.
	4	CRC Bit 6	CRC register output Bit 6.
	5	CRC Bit 7	CRC register output Bit 7.
	6	CRC Bit P	CRC register output Bit P.
	7	LRC Bit 0	LRC register output Bit 0.

4.5

Monitor Sense Byte 4

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
0	LRC Bit 1	LRC register output Bit 1.
1	LRC Bit 2	LRC register output Bit 2.
2	LRC Bit 3	LRC register output Bit 3.
3	LRC Bit 4	LRC register output Bit 4.
4	LRC Bit 5	LRC register output Bit 5.
5	LRC Bit 6	LRC register output Bit 6.
6	LRC Bit 7	LRC register output Bit 7.
7	LRC Bit P	LRC register output Bit P.

After a successful read or write, the content of the LRC register should be all zeros. One bits indicate error in the corresponding channel. LRC register will be precleared on any I/O operation other than Sense or Monitor Sense operation.

Inter Computer Control Unit (ICCU)

1. COMMAND REPERTOIRE

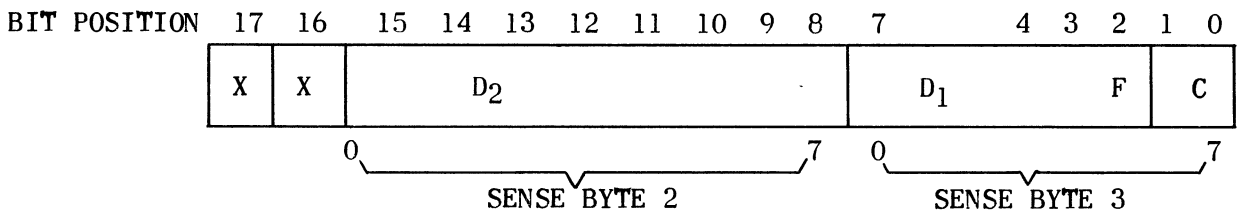
1.1 CONTROL COMMANDS

These commands are provided so that the Master and Slave can communicate to a limited extent without setting up Data Buffers. When one of these Commands is issued an External Interrupt Request is transmitted to the opposite interface and the COMMAND itself is made available to the opposite interface as External Interrupt Status or Sense bytes.

1.2 MASTER EXTERNAL FUNCTION WORD FORMAT

The Format for bits 0—17 of the EF word from the Master is shown below:

MASTER



<u>Field</u>	<u>Bits</u>	<u>Function</u>
X	17,16	These bits are ignored
D ₂	15-8	Detail, transmitted to the slave in Sense Byte 2. Not interpreted by ICCU.
D ₁	7-4	Detail, transmitted to the slave with F and C in Third Sense Byte. Not interpreted by ICCU.
F	3,2	DATA FORMAT SELECTION F = 00 Select Format A F = 01 Select Format B F = 1X Select Format C
C	1,0	CONTROL FIELD 01 INPUT Transmit data to Master 10 OUTPUT Call for data from Master 00 Set "Attention" Interrupt Request to Slave. No data is transferred. 11 Invalid (Automatic No-Match)

1.3 SLAVE COMMAND FORMAT

	<u>COMMAND BYTE</u>	<u>FUNCTION</u>
1.3.1	XX00 0000	<u>TEST I/O</u> No operation, supply status to slave.
1.3.2	XX01 0000	<u>SET INHIBIT STATUS</u> This command is processed as a TEST I/O. (If accepted, it does not generate new status.) The Status Byte is presented to the channel and INHIBIT STATUS IN (Bit 6 of Sense Byte) is set.
1.3.3	XX10 0000	<u>RESET INHIBIT STATUS</u> Same action as SET INHIBIT STATUS, except Bit 6 of Sense Byte is reset.
1.3.4	XXXX 0100 ₍₁₎	<u>SENSE</u> Transmit 4 bytes of Sense data to Slave. The 2nd and 3rd bytes are taken from the Word Register, bits 0-7 and 8-15. This provides a means of transmitting 16 bits of the EXTERNAL FUNCTION word from Master to Slave. The first byte is detail for the Unit Check Status. The 4th byte has the same format as bits 16-9 of the Master Interrupt Status Word.
1.3.5	DDDD DD10 _(1,2)	<u>INPUT</u> Transmit data to Slave.
1.3.6	DDDD DD01 _(1,2)	<u>OUTPUT</u> Call for data from Slave.
1.3.7	DDDD DD11 _(1,2)	<u>SET EXTERNAL INTERRUPT REQUEST</u> No Data Transfer, Send External Interrupt Request to Master, with the 8-bit Command code on Master Input Data Lines 0-7.

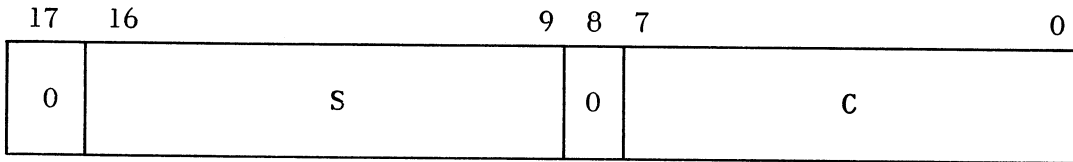
NOTE (1) If the ICCU is "off-line" to the Master computer, bits 0 and 1 of these commands will serve in place of the "F" field of the Master EF word and will control the format. (Bit 0 will be equivalent to Bit 3 of the Master EF word.)

NOTE (2) X Bits and D Bits are not interpreted by the ICCU except as specified in Note (1). D Bits are passed on to the Master via an External Interrupt Word.

2. STATUS BYTES

2.1 EXTERNAL INTERRUPT STATUS WORD

When External Interrupt Request is transmitted to the Master, the data in I/O Input lines 17-0 will be as follows: (Bits above 17 on larger interfaces will be zeros.)



<u>Bits</u>	<u>Field</u>	<u>Description</u>
17		Always zero.
16-9	S	The same Format as Sense Byte 4. Bit 16 corresponds to bit 0 of the Sense byte.
8		Always zero.
7-0	C	The Command Byte from the Slave when the Slave has issued a command other than SENSE I/O or a TEST I/O.

All zeros on termination of data transfer.

2.2 SLAVE STATUS BYTE

<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
------------	--------------------	-----------------------

- | | | | |
|-------|---|-----------------|---|
| 2.2.1 | 0 | ATTENTION | <p>The Master has issued a Control Command to the ICCU, or the Master has issued the First command and a Slave Command is required to initiate data transfer.</p> <p>When the ATTENTION interrupt has been generated, the Slave must issue a Sense Command in order to examine the Master EF Word. Hardware restrictions will cause all subsequent commands to be rejected if the Sense Command is not issued.</p> |
| 2.2.2 | 1 | Status Modifier | Used only on C.U. Busy Sequence |
| 2.2.3 | 2 | Not used | |
| 2.2.4 | 3 | Busy | <p>Indicates the Control Unit cannot accept a command because:</p> <ol style="list-style-type: none"> 1) It is executing a previously initiated I/O operation; STATUS MODIFIER also is set. The Control Unit is defined as Busy from the time a command from the Channel is loaded into the Command Register until both CHANNEL END and DEVICE END are set. 2) The Control Unit is holding pending status conditions detected subsequent to completion at the last data transfer command. (Not applicable to TEST I/O or SET/RESET Inhibit Status.) |

SLAVE STATUS BYTE (cont)

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
2.2.5	4	Channel End	Always occurs with DEVICE END.
2.2.6	5	Device End	A Data Transfer was terminated or a Control Command was accepted. (Control Commands are Control Immediate type.)
2.2.7	6	Unit Check	Set simultaneously with bits 0-5 in Sense Byte 1.
2.2.8	7	Unit Exception	Set whenever an EF is received from the Master during a data transfer, i.e., Master Termination.

3. SENSE BYTE FORMATS

The Slave computer may accept 0, 1, 2, 3, or 4 SENSE BYTES as desired;

3.1 Sense Byte 1

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
	0	Command Reject	Unspecified command issued to ICCU. This indication (to slave) is suppressed if command byte has incorrect parity.
	1	Not used	Transmitted as zero.
	2	BUS OUT Check	Even parity on BUS OUT during transfer of data or command to ICCU from Slave channel.
	3	Not used	Transmitted as zero.
	4	Not used	Transmitted as zero.
	5	Not used	Transmitted as zero.
	6	Inhibit STATUS IN FF state	"1" whenever the FF is set.
	7	Not used	Transmitted as zero.

3.2 Sense Byte 2

(Refer to paragraph 1.2)

3.3 Sense Byte 3

(Refer to paragraph 1.2)

3.4 Sense Byte 4

	<u>Bit</u>	<u>Designation</u>	<u>Interpretation</u>
3.4.1	0	Selective Reset	An operation has been terminated by the Slave with Selective Reset (Error detected by Slave Channel).
3.4.2	1	Master Termination	An operation has been terminated by the Master before normal completion. (Will always be a "0" to SENSE COMMAND. Status FF7 is set by same condition.)
3.4.3	2	Not used	Always transmitted as zero.
3.4.4	3	Bus Parity Error	A parity error has been detected on the Slave OUTPUT BUS. (Will always be a "0" to SENSE Command. Bit 2 of first SENSE BYTE is set by the same condition).
3.4.5	4	Format Reg. FF2	Same as Bit 3 of last Master EF Word. If Master is off-line then same as Bit 0 of Slave SENSE Command byte.
3.4.6	5	Format Reg. FF1	Same as Bit 2 of last Master EF Word. If Master is off-line then same as Bit 1 of Slave SENSE Command byte.
3.4.7	6	Master Function Reg. FF2	Same as Bit 1 of last Master EF Word.
3.4.8	7	Master Func- tion Register FF1	Same as Bit 0 of last Master EF Word.

UNIVAC 9000 Series 900/1100 LPM
Drum Printer and Control

SPECIFICATION SYMBOL SH04479

1. Command Repertoire

1.1 The following command codes may be issued to the Printer Control Unit by the processor. Any other codes will be rejected and will return a Unit Check Status to the processor with the Command Reject bit (0) set in the Sense Byte.

<u>Command</u>	<u>Code</u>	<u>Description</u>
----------------	-------------	--------------------

P01234567
P = Odd Parity Bit
X = Ignored by
Control Units
CDEF = Detail Bits

1.2	Test I/O	PXX110000 or PXX000000	The Control Unit transmits the Status Byte to the channel. SERVICE OUT from the channel resets (clears) the Status.
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1.3	Set Inhibit Status	PXX010000	This command is processed as a Test I/O Command (if accepted, it does not generate any new status). Status will be presented to the channel and the Inhibit Status In Flip-Flop (FF) will be set.
-----	--------------------	-----------	---

1.3.1			The condition of the Inhibit Status In FF can be examined in Sense Byte 1. bit position 6. When Inhibit Status is set, the Printer Subsystem will not initiate any sequences to present status. The Set Inhibit Status Command should not be issued if the Printer Subsystem is connected to a Selector channel.
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1.4	Reset Inhibit Status	PXX100000	This command is processed as a Test I/O Command (if accepted, it does not generate any new status). Status will be presented to the channel and the Inhibit Status In FF will be reset.
-----	----------------------	-----------	---

1.5	Sense I/O	P00000100	The Printer Control Unit transfers the Sense Byte to the channel as input data. The Sense Byte generally supplies details about any unusual conditions that occurred during the last operation.
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1.5.1			The Sense Byte is cleared upon receipt of a valid new command code but is not altered by a Sense or Test I/O command. In addition to supplying pertinent information to the Program, this data can be used as maintenance aids.
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	<u>Command</u>	<u>Code</u>	<u>Description</u>
1.6	Print (Write)	P01234567 POCDEF001	<p>(Print and Advance):* Data Characters for one print line are transferred by the channel to the printer buffer; the line is printed; and the paper is then advanced to the next print line. From 0 to 132 characters may be transferred for printing; loading of the buffer begins with Column 1 and continues sequentially until 132 characters have been loaded or until the channel indicates end of data transfers, whichever occurs first. In the latter case, the Control Unit fills the remaining buffer positions with the selected non-printing code.</p> <p><u>*NOTE:</u> The buffer can be loaded during a previous Advance Paper so as to maintain the maximum print rate. Time to load the buffer is 800 μs nominal</p> <p>CDEF Detail Bits are defined under Forms Control.</p>
1.7	Advance- No Print (Control)	POCDEF011	This code is used for non-data transfer operations in the printer control unit. The paper is advanced, without printing, to the position specified by the detail bits,,C, D, E, and F.
1.8	Read (Diag- nostic)	P00000010	The Read command will first transfer the contents of the 132 byte buffer loaded by a previous print command followed by the 64 byte buffer loaded by the Load Code command.
1.9	Load Code	P11111011	<p>The Load Code command loads a 64 byte buffer with a 6, 7, or 8 bit code that represents the code for the characters on the print drum. This command enables code conversion by the printer.</p> <p>The sequence of loading must be as follows: (Corresponds to the ordering on the print drum).</p>

1. &	17. L	33. 2	49. >	(greater than)
2. Z	18. F	34. 3	50. <	(less than)
3. K	19. H	35. 4	51. ;	
4. J	20. S	36. 5	52. :	
5. Q	21. R	37. 6	53. ¢	
6. X	22. O	38. 7	54.	(absolute)
7. V	23. A	39. 8	55. ¬	(logical not)
8. W	24. N	40. 9	56. <u> </u>	(underline)
9. Y	25. I	41. *	57. " "	(quote)
10. P	26. T	42. /	58. !	
11. G	27. E	43. +	59. ?	
12. B	28. .	44. \$	60. \	
13. U	29. , (comma)	45. (61. %	
14. M	30. - (minus)	46.)	62. #	
15. C	31. 0	47. =	63. @	
16. D	32. 1	48. ' (apost.)	64. Non-printing (space)	

<u>Command</u>	<u>Code</u>	<u>Description</u>
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1.10 Forms Control POCDEF001 (Print) or POCDEF011 (No-Print) This data is transferred as part of a Print or Advance—
No Print command. Paper is spaced as specified in detail bits CDEF as follows:

P01234567
CDEF

Machine A

Machine B

0000	No Advance	No Advance
0001	Advance 1 line	Advance 1 line
0010	Advance 2 lines	Advance 2 lines
0011	Paper Loop Control*	Advance 3 lines
0100		Paper Loop Control*
thru		
1110		Home Paper Loop Control 6 lines/inch
1111	Home Paper Loop Control	Home Paper Loop Control 8 lines/inch

*Paper is advanced under control of the Forms Control tape loop to the line corresponding to the same hole combination in the loop. The Skip may be from 1 to 132 lines maximum.

1.11

"Home Paper" Codes

1.11.1

By programming convention, the codes "1110" and "1111" in the Forms Control tape loop are reserved for "Home Paper". They require no special recognition in the Control Unit.

Home Paper Command Bits	CDEF
Paper Loop Bits	8421
Machine A	1111
Machine B	1110 6 lines/inch
Machine B	1111 8 lines/inch

1.11.2 On Machine B the 6/8 LPI Switch is deleted. For initial set-up, or whenever the loop is changed, the Home Paper Switch is depressed twice before paper is loaded. Thereafter it need only be depressed once. The Home Paper Indicator lights whenever in the Home Paper position. A paper tape loop must always be used with the Home Paper punched in it.

1.11.3 On Machine B, when Forms Out occurs, there may still be 2-1/2 inches of paper left. The Forms Out condition will not be indicated until the home paper position is detected by the loop control photocells. The paper advance portion of the instruction just completed will continue to advance to the location called for in that instruction. The current print or space command will be inhibited at this time and "STOP" and "FORMS OUT" will be set. The operator may now line up the new forms with the last one in the machine.

1.12 Form Overflow

1.12.1 By programming convention, the code "1001" punched in the Forms Control tape loop is reserved to specify "end of form". If this code is detected during a Control or Write command-initiated form advance, either single or double spaced, the Control Unit:

1. Terminates the operation and does not execute a pending Print or Advance-No Print command which may have been initiated by the channel after printing the previous line but prior to the completion of paper advance.
2. Sets the Unit Exception bit (7) in the Status Byte which will be transmitted to the channel at Device End of this command or Initial Selection of the next command.

2. Status Byte

2.1 The Status Byte contains information on the status of the printer and Control Unit and some data on conditions of the last operation. It is presented to the Channel at these times:

1. End of the Initial Selection Sequence.
2. At the end of data transfers for the Print, Read, and Load Code commands.
3. Completion of printing a line and start of paper advance for the current print command.
4. At the start of paper advance for the Advance-No Print command. Normally, it is not presented at the end of paper advance.

2.2 The Status Register in the Control Unit is cleared when the channel responds to STATUS IN with SERVICE OUT. The bits in the Status Byte are defined as follows:

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
2.3	P	Odd Parity	Parity for Status Byte
2.4	0	Attention	Machine A - Not used, always "0". Machine B - This bit will be set whenever the machine is ready, but in the "STOP" condition, and "RUN", is depressed. The Attention Bit is an operator-controlled interrupt indicating that the machine has gone from an inactive to an active state.
2.5	1	Status Modifier	Present with Busy to indicate the printer is busy executing a previously initiated operation.
2.6	2	Control Unit End	Not used, always "0".
2.7	3	Busy	Indicates that the printer cannot accept a command because one of the following conditions exists: <ul style="list-style-type: none"> a. Printer is executing a previously initiated command (Bit 1, Status Modifier, will also be present). b. Printer is holding pending status conditions from a previous command (not applicable to Test I/O or Reset or Set Inhibit Status).
2.8	4	Channel End*	Presented at the end of data transfer on a Print command.
2.9	5	Device End*	Indicates the completion of a command accepted by the printer, exclusive of paper advancement. It is presented in these cases: <ul style="list-style-type: none"> 1. At the completion of printing the line and start of paper advance. 2. At the start of paper advance for an Advance-No Print command. 3. At the completion of a Sense, Read, or Load Code command.
2.10	6	Unit Check	Set when any bit but 6 in the sense byte is set, except during a Sense command when bit 7 of the Sense byte is set.
2.11	7	Unit Exception	Indicates a Form Overflow condition from the end-of-paper detector. Presented with Device End on those commands which initiate paper advance.

*Presented simultaneously at the completion of Sense, Read, and Load Code commands, and at the beginning of the paper advance for the Advance-No Print command.

3. Sense Data Bytes

3.1 The Sense Data Bytes provide information about unusual conditions occurring during the last operation. The Sense Bytes are cleared when the next valid command code is accepted by the Control Unit.

3.2 Sense Byte 1

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.1	P	Odd Parity	Parity for Sense byte.
3.2.2	0	Command Reject	An invalid command was issued by the channel.
3.2.3	1	Intervention Required	Paper low or paper runaway.*
3.2.4	2	BUS OUT CHECK	Parity error on a command or data transfer to the Control Unit. Parity error on command codes causes immediate termination; on data transfers, no immediate termination.
3.2.5	3	Equipment Check	Indicates an equipment malfunction during last printing operation.
3.2.6	4	Data Check	Buffer Parity error.
3.2.7	5	Overrun	Print not completed in 1 revolution.
3.2.8	6	Inhibit Status	Inhibit Status is set.
3.2.9	7	Not Ready	Indicates the Printer and/or Control Unit is not operative. This bit is set whenever one of the conditions described below is encountered.

*A runaway paper condition can arise if the Forms Control code is not punched in to the paper tape loop or from malfunctioning of the paper advance mechanism. The Control Unit contains circuitry which will stop the paper automatically approximately 1.2 seconds after the start of an advance (unless it stops before that time). If this contingency stop is reached, the runaway paper bit in the Sense byte and the Unit Check bit in the Status byte are set. A pending "Print" or "Advance-No Print" command in the Control Unit is suppressed.

Not-Ready Conditions

<u>Machine A</u>	<u>Machine B</u>
1. Power Check	1. Power Check
2. Interlock	2. Interlock
3. Temperature Ck.	3. Temperature Ck.
4. Print Check	4. Print Check
5. Ribbon Check	5. Ribbon Check
6. Carriage Out	6. Carriage Out
7. Forms Runaway	7. Forms Runaway
	8. Parity Check
	9. Forms Out

3.3 Sense Byte 2

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.3.1	P	Odd Parity	Parity for Sense Byte.
3.3.2	0	Buffer Parity Error, Code	Indicates a Buffer Parity Error in the code area only.
3.3.3	1	Buffer Parity Error, Data	Indicates a Buffer Parity Error in the data area only.
3.3.4	2	Once per Revo- lution Error	Indicates Counter is not equal to 63 when the once per revolution pulse occurs.
3.3.5	3	Sprocket Error	Indicates a data pulse identical on two consecu- tive sprocket pulses.
3.3.6	4	Scan Error	Next sprocket occurred before the Scan Cycle was completed.
3.3.7	5	Early Terminate	The Channel terminates data transfers on any com- mand. Status flip-flop 6 is set on Load Code only.
3.3.8	6	Paper Low	<u>Machine A</u> - Indicates the Printer is running out of paper (Forms Out). <u>Machine B</u> - a. Depression of "STOP" will set this bit and the Unit Check Bit, Status Bit 6. This is an operator-action stop. All stops occur at the com- pletion of the current instruction. b. Any non-ready condition, or error condition, will also set Sense Byte 2, Bit 6 and Unit Check and will be further defined in the Sense Bytes. c. The Test, Sense, Read, and Load Code commands can be performed when in the "STOP" mode. The Read and Load Code command cannot be performed on certain "STOP" con- ditions, such as Power, Interlock and Temperature Check.
3.3.9	7	Selective Reset/ Interface Disconnect	This Bit is set if a Selective Reset/Interface Disconnect Sequence occurred anywhere since the last Sense Command was issued.

Perforated Tape Subsystem for the
DCT 2000 and the 9000 Series

1. Command Code

1.1 The basic format for the Command byte transferred from the Channel to the Controller during the Initial Selection Sequence is shown below.

<u>COMMAND</u>	<u>BIT POSITION</u>
	<u>P 0 1 2 3 4 5 6 7</u>
Test	P X X 0 0 0 0 0 0
OR	P X X 1 1 0 0 0 0
Set Inhibit Status	P X X 0 1 0 0 0 0
Reset Inhibit Status	P X X 1 0 0 0 0 0
Sense	P 0 0 0 0 0 1 0 0
Punch	P 0 0 0 0 0 A 0 1
Read	P 0 0 0 0 0 A 1 0
Control	P 1 0 0 0 0 0 1 1

P = Odd Parity Bit

A = 1, ignore control codes, operate binary mode

A = 0, character recognition is operative

X = to be ignored by the Controller

Any other Command Code shall be treated as an invalid Command by the Controller. Issuance of a PUNCH or READ Command in the absence of the associated feature on the subsystem shall constitute an invalid command.

- 1.2 Test. This Command Code shall cause transfer of the Controller Status Byte to the Channel. This command will not cause any new status indications to be generated.
- 1.3 Set Inhibit Status. This command is processed as a Test Command. Status will be presented to the Channel and Inhibit Status In will be set.
- 1.4 Reset Inhibit Status. This command is processed as a Test Command. Status will be presented to the Channel and Inhibit Status In will be reset.
- 1.5 Sense. This Command Code shall cause the Controller to transfer, as input data, up to two bytes of sense indication to the Channel.
- 1.6 Punch. This Command Code shall initiate the punching of one block of data on the Punch. The block is terminated when the Channel responds to SERVICE IN with COMMAND OUT.
- 1.7 Read. This Command Code will initiate the reading of one block of data from the Reader.
- 1.8 Control. This Command Code is reserved for Failure Finding. Non-diagnostic programs should not attempt to set up this Command Code.

2. Status Byte

- 2.1 The Controller shall automatically place a STATUS Byte on the input bus to the Channel before signaling a STATUS IN. The format of the STATUS Byte is as follows:

<u>BIT</u>	<u>STATUS</u>
P	Odd Parity Bit
0	Attention
1	Status Modifier
2	Not Used
3	Busy
4	Channel End
5	Device End
6	Unit Check
7	Unit Exception

- 2.2 Attention. Either Reader or Punch has changed from STOP to RUN mode. (Control panel push-button.)
- 2.3 Status Modifier. This bit is normally set along with the Busy Status Bit. Status Modifier will not be set with Busy if a new Command is issued to the Controller when it is about to initiate an interrupt to present end status from the previous operation.
- 2.4 Busy. This bit is transmitted during the Control Unit Busy sequence. "Busy" is also transmitted when a command other than TEST is attempted and the Controller has status pending from a previous operation.
- 2.5 Channel End. This bit is set whenever a data block is terminated. It is also set during Initial Selection when a CONTROL command is accepted and no data is to be transferred. Channel End will always be presented with Device End.
- 2.6 Device End. This bit is set when the Reader or Punch completes an I/O Operation. Device End will always be presented with Channel End.
- 2.7 Unit Check. Unit Check will be presented when a read command is issued and a reader fault exists and when an error or fault is encountered after a command is initiated. Any bit in sense byte 1 will set Unit Check.
- 2.8 Unit Exception. Unit Exception will be presented if a STOP CHARACTER is detected on Read.

3. Sense Bytes

3.1 Sense Byte 0

<u>BIT</u>	<u>INDICATION</u>
P	Odd Parity Bit
0	Command Reject
1	Intervention Required
2	Bus Out Check
3	Equipment Check
4	Data Check
5	Not Used
6	Inhibit Status Set
7	Tape Fault

3.1.1 Command Reject. The Command Code received is invalid.

3.1.2 Intervention Required. Manual or program intervention is required to clear the Controller or the Reader/Punch of a condition which prevents future operation, such as:

- (r.p.) Program connector not inserted
- (p) Punch Take-up reel full
- (r) Broken tape in reader
- (r) End of tape in reader
- (p) Low Tape on Punch
- (r) Reader in Stop Mode
- (p) Punch in Stop Mode

3.1.3 Bus Out Check. Bus Out Check sets when a parity error has occurred.

- (p) Does not punch the bad character if in punch data
- (rp) Parity error on instruction transfer or last data character.

3.1.4 Equipment Check. A read error, broken tape, or overshoot condition exists on the Reader. A low paper tape supply condition exists on the Punch.

3.1.5 Data Check. A read parity error has been detected. Data is read until the Channel terminates data transfers.

3.1.6 Inhibit Status. Inhibit Status FF set.

3.1.7 Tape Fault. indicates:

- (r) Normal End of Tape
- (p) Low Tape Supply

3.2

Sense Byte 1

<u>BIT</u>	<u>INDICATION</u>
P	Odd Parity Bit
0	Reader STOP FF
1	Punch STOP FF
2	Program Connector not inserted
3	Not used.
4	Punch Take-up reel full
5	Low tape supply on Punch
6	Broken tape on Reader
7	Normal End of Tape on Reader

DCS 1, 4Data Communications Subsystems

1. Command Byte Repertoire - Table A lists the commands accepted by the DCS from the channel. Table B lists the bit configurations of these commands when they are encoded by the LTC and accepted by the line terminals.
2. Status Byte - The Status Byte indicates to the processor the operational condition of the DCS and initiates processor I/O interruption for a variety of reasons, such as the receipt of an invalid sequence of commands. When an abnormal or error condition exists in the DCS, a Unit Check Status Byte is sent to the processor. After the processor returns the required Sense command, additional information is sent to the processor in two Sense Bytes, indicating the specific nature of the abnormal condition.
 - 2.1 Status Byte Repertoire - Table C lists the Status Bits generated by the DCS.
3. Sense Bytes - The Sense Bytes are used by the DCS when it is necessary to convey additional information to the processor. When an error condition arises in the DCS, a Unit Check Status Byte is sent to the processor. The processor replies with a Sense Command. The DCS then presents the more detailed information in two Sense Bytes.
 - 3.1 The DCS always transmits two Sense Bytes to the processor. The Input LT encodes both Sense Bytes. The Output LT encodes the first Sense Byte and can encode the second Sense Byte when a Dialing Adapter is attached (Dial No Good).
 - 3.2 Tables D and E itemize the first and second Sense Byte bit-indicators generated by the DCS.

Table A. Command Byte Repertoire

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
<u>WRITE</u> <u>Send Data</u>	P 0 0 0 0 0 0 0 1	A command sent during an Initial Selection Sequence which starts the Output Data Sequence and causes the LT to generate an all-zeros Status Byte as a response.	-00, -02, & -06.	-00 & -02.	-00, -02, & -04.	
<u>Dial</u>	P 0 0 0 0 0 1 0 1	Same as <u>Send Data</u> . Only accepted by an Output LT equipped with a Dialing Adapter (F1007-00). Output LT does not perform the dialing function. A <u>Turn-On</u> Command Byte must be sent to the Input LT before sending a <u>Dial</u> Command Byte to the Output LT.	-00, -02, & -06.	-02.	-00, -02, & -04.	
<u>Send Break</u>	P 0 0 0 1 0 0 0 1	A command sent to an Output LT which causes the CI (F1002-09) to send a break (spacing) signal for a minimum of 205 ms. The command also causes the CI (F1002-10) to send a break (spacing) signal for one second. The break is normally used to stop a remote transmitter. This command causes the LT to generate an all-zeros Status Byte as a response.	-06.			

Table A. Command Byte Repertoire (cont)

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
<p>READ</p> <p><u>Turn-On</u></p>	P 0 0 0 0 0 0 1 0	<p>A command sent during an Initial Selection Sequence which starts an Input Data Sequence and causes the LT to generate an all-zeros Status Byte as a response. When data is available on the Input Data lines, it will be transmitted to the processor. This command is also used by the F1002-04, -06, or -09 CI to accept an incoming call following the receipt of the RING INDICATOR signal, or it is used to condition the CI to permit a Dial function to be performed.</p>	-01, -03, & -07.	-01 & -03.	-01, -03, & -05.	-01.
<p><u>New Sync</u></p>	P 0 0 0 0 1 0 1 0	<p>A command accepted by an Input LT which controls the CI (F1002-03 & -04 only) and enables it to quench the receive clock of a synchronous modem. This causes fast resynchronization with a newly turned-on remote transmitter and causes the Input LT to generate an all-zeros Status Byte as a response. This command is normally used for multiple-party connections only.</p>			-01, -03, & -05.	

Table A. Command Byte Repertoire (cont)

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-L F1004-XX	LT-S F1005-XX	LT-P F1006-XX
READ (cont) <u>Look-For Sync (LFS) or Parallel Test</u>	P 0 0 0 0 0 1 1 0	A command which nullifies character synchronization in an Input LT-S and then causes the LT-S to identify two contiguous unique Sync Characters and a non-sync character (SOM Character is optional) out of a serial data stream. New character synchronization is then established. This command also causes the Input LT-S to stop sending data. The LT-S begins sending data only when a non-sync character (SOM or Data Character) is received following re-synchronization. This command causes the Input LT-S to generate an all-zeros Status Byte as a response. <u>Parallel Test</u> provides the LT-P with back-to-back testing capability (used only during the DCS Test mode). It is the final command transmitted by the processor and immediately follows a <u>DCS Test</u> and a <u>Turn-On</u> command.			-01, -03,	-01

Table A. Command Byte Repertoire (cont)

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
<u>READ (cont)</u>						
<u>Answer Back A</u>	P 0 0 0 1 0 0 1 0	A command sent to the Parallel LT which allows the CI (F1002-07) to send three different tones on the ANSWER-BACK channel of the 403D5 or 403D6 Data Set. The processor can select and control these tones via the coding within the command. The select-tone is sent for three to five seconds. This command causes the Parallel LT to generate an all-zeros Status Byte as a response.				-01.
<u>Answer Back B</u>	P 0 0 0 1 0 1 1 0					
<u>Answer Back AB</u>	P 0 0 0 1 1 0 1 0					
<u>CONTROL</u>						
<u>Turn-Off</u>	P 0 0 0 0 0 0 1 1	A command which causes the immediate termination of an Input or Output Data Sequence and causes the LT to generate a <u>Channel End - Device End Status Byte</u> as a response.	-00, -01, -02, -03, -06, & -07.	-00, -01, -02, & -03.	-00, -01, -02, -03, -04, & -05.	-01.
<u>DCS Test</u>	P 0 0 0 0 1 0 1 1	A command to the Input LT which terminates the connections between the CI and the communications lines or modem and causes the Input LT to generate a <u>Channel End - Device End Status Byte</u> as a response. This command connects the output signal to the input signals for loop-back testing of the DCS by the processor.	-01, -03, & -07.	-01 & -03.	-01, -03, & -05.	-01.

UNIVAC

SHEET 15-5

REVISION -

SPECIFICATION SYMBOL

SH04479

SPECIFICATION SHEET

Table A. Command Byte Repertoire (cont)

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
CONTROL (cont) <u>End Test</u>	P 0 0 0 0 1 1 1 1	A command to the Input LT which switches the CI back to normal operation following a DCS or Local Test operation and causes the Input LT to generate a <u>Channel End - Device End</u> Status Byte as a response.	-01, -03, & -07.	-01,& -03.	-01, -03, & -05.	-01.
<u>Disconnect</u>	P 0 0 0 1 0 0 1 1	A command to the CI (F1002-04, -06, or -09) via the Input LT for the purpose of terminating a call. Upon receipt of the signal, the DATA TERMINAL READY signal is dropped to the modem, indicating a "hang-up". This command causes the Input LT to generate a <u>Channel End - Device End</u> Status Byte as a response.	-01, -03, & -07.	-01,& -03.	-01, -03, & -05.	-01.
<u>Local Test</u>	P 0 0 0 0 0 1 1 1	A command to the Input LT which causes the CI (F1002-05) to exercise the Local Test Control on the associated modem. This command places the modem in the loop-back test mode for testing all local (on-site) hardware including the modem. (Applies only to modems which have turn-around capability.) This command causes the Input LT to generate a <u>Channel End - Device End</u> Status Byte as a response.	-01, -03, & -07.	-01 & -03.	-01, -03, & -05.	

SHEET 15-6

REVISION

SPECIFICATION SYMBOL

SH04479

Table A. Command Byte Repertoire (cont)

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
SENSE	P 0 0 0 0 0 1 0 0	When an error condition exists in the DCS, the appropriate line terminal sends (via the LTC) a <u>Unit Check Status Byte</u> to the processor. The processor then replies with a <u>Sense</u> command. The <u>Sense</u> command tells the line terminal to return an all-zeros Status Byte followed by two Sense Bytes.	-00, -01, -02, -03, -06, & -07.	-00, -01, -02, & -03.	-00, -01, -02, -03, -04, & -05.	-01.
TEST I/O	P 0 0 0 0 0 0 0 0	A command which is used to obtain the present status of a line terminal. This command does not cause the generation of new status but does cause the LT to generate an all-zeros Status Byte as a response.	-00, -01, -02, -03, -06, & -07.	-00, -01, -02, & -03.	-00, -01, -02, -03, -04, & -05.	-01.

SHEET 15-7

REVISION -

SPECIFICATION SYMBOL

SH04479

Table B. Bit Configurations of
LTC Encoded Command Bytes

Title of Command	Bit Configuration P 0 1 2 3 4 5 6 7
<u>Send Data</u>	P 0 0 0 0 0 1 0 1
<u>Dial</u>	P 0 0 0 0 1 0 0 1
<u>Send Break</u>	P 0 1 0 0 0 0 0 1
<u>Turn-On</u>	P 0 0 0 0 0 1 1 0
<u>New Sync</u>	P 0 0 0 1 0 0 1 0
<u>Look-For-Sync (LFS)/ Parallel Test</u>	P 0 0 0 0 1 0 1 0
<u>Answer Back A</u>	P 0 1 0 0 0 0 1 0
<u>Answer Back B</u>	P 1 0 0 0 0 0 1 0
<u>Answer Back AB</u>	P 0 0 0 1 0 0 1 0
<u>Turn-Off</u>	P 0 0 0 0 0 1 1 1
<u>DCS Test</u>	P 0 0 0 1 0 0 1 1
<u>End Test</u>	P 0 0 1 0 0 0 1 1
<u>Disconnect</u>	P 0 1 0 0 0 0 1 1
<u>Local Test</u>	P 0 0 0 0 1 0 1 1
SENSE	P 0 0 0 0 0 1 0 0
TEST I/O	P 0 0 0 0 0 1 0 0

Table C. Status Byte Repertoire¹

Title of Status	Bit Configuration P 0 1 2 3 4 5 6 7	Description
<u>Busy</u>	P 0 0 0 1 0 0 0 0	This status condition is generated by an Output or Input LT and tells the processor that a previously initiated command is in progress.
<u>Channel End</u>	P 0 0 0 0 1 0 0 0	Same as Device End.
<u>Device End</u>	P 0 0 0 0 0 1 0 0	This status condition is generated by an Output or Input LT and tells the processor that a previously initiated command is completed.
<u>Unit Check</u>	P 0 0 0 0 0 0 1 0	This status condition is generated by an Output or Input LT and tells the processor that an abnormal or error condition exists. It also tells the processor to send a <u>Sense Command</u> if additional information on an error or status condition is required.
<u>Unit Exception</u>	P 0 0 0 0 0 0 0 1	This status condition is generated by the LTC and indicates a non-existent or inactive line terminal.

¹All Status Bytes are applicable to all line terminals.

Table D. First Sense Byte Repertoire

Title of Sense	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
<u>Command Reject</u>	P 1 0 0 0 0 0 0 0	Indicates an invalid Command Byte was presented to either an Input or Output LT.	-00, -01, -02, -03, -06, & -07.	-00, -01, -02, & -03.	-00, -01, -02, -03, -04, & -05.	-01.
<u>Bus Out Check</u>	P 0 0 1 0 0 0 0 0	Indicates a parity error exists in a Command Byte. This error condition is detected by the LTC.	-00, -01, -02, -03, -06, & -07.	-00, -01, -02, & -03.	-00, -01, -02, -03, -04, & -05.	-01.
<u>Data Check</u>	P 0 0 0 0 1 0 0 0	Indicates a parity error existed on a Data Byte in the previous Data Block. This error condition is detected by the LTC and only applies to Output LT's.	-00, -02, & -07.	-00, & -02.	-00, -02, & -04.	
<u>Overrun (Data Late)</u>	P 0 0 0 0 0 1 0 0	Indicates data was late in being acknowledged or sent by the processor.	-01, -03, & -07.	-01, & -03.	-00, -01, -02, -03, -04, & -05.	-01.
<u>Ring Indicator</u>	P 0 0 0 0 0 0 1 0	Indicates that a ringing signal is being received from a remote station. A Turn-On Command Byte must then be sent to the Input LT. The DCS will answer calls automatically. This particular condition only applies to an Input LT.	-03, & -07.	-03.	-01, -03, & -05.	-01.

SHEET 15-10

REVISION -

SPECIFICATION SYMBOL

SH04479

Table E. Second Sense Byte Repertoire

Title of Sense	Bit Configuration P 0 1 2 3 4 5 6 7	Description	Applicable Line Terminals			
			LT-L F1003-XX	LT-M F1004-XX	LT-S F1005-XX	LT-P F1006-XX
<u>Message Status (LRE)</u> Longitudinal Redundancy Error	P 1 0 0 0 0 0 0 0	Indicates a message (or block) parity error is detected. This condition only applies to an Input LT.		-03.	-03, & -05	
<u>Message Status (CPE)</u> Character Parity Error	P,0 1 0 0 0 0 0 0	Indicates a Data Character (or Data Byte) parity error is detected in a message (or block). This condition only applies to an Input LT.	-03, & -07.	-03.	-03, & -05.	
<u>Error - Carrier OFF (AGC Lock)</u>	P 0 0 1 0 0 0 0 0	Indicates loss of carrier when receiving a message (the INPUT DATA signal has dropped). This condition only applies to an Input LT.	-03, & -07.	-03.	-03, & -05.	
<u>Dial No Good</u>	P 0 0 0 1 0 0 0 0	Indicates no connection established after a <u>Dial</u> command is send. Only generated by an Output LT connected to a Dialing Adapter (F1007-00).	-00, -02, & -06.	-00, & -02.	-00, -02, & -04.	
<u>Time-Out (180 ms) Break</u>	P 0 0 0 0 0 1 0 0	Indicates the Input LT has received a BREAK signal from a station on the TWX network. A BREAK signal is a spacing signal held for 180 ms duration. The BREAK signal is sent by a remote station for the purpose of stopping a transmitter. When operating in a TELEX network, the BREAK signal indicates a disconnection.	-07.			

SPECIFICATION SYMBOL
SH04479

SHEET 15-11 REVISION -

FUNCTION CODES

U12/U16 Control Unit No. 5017-XX

Command	0	1	2	3	4	5	6	7
TEST	X	X	0 1	0 1	0	0	0	0
SET INHIBIT STATUS	X	X	0	1	0	0	0	0
RESET INHIBIT STATUS	X	X	1	0	0	0	0	0
SENSE	0	0	0	0	0	1	0	0
SENSE/RESERVE	1	1	1	1	0	1	0	0
SENSE/RELEASE	1	1	0	1	0	1	0	0
WRITE	0	0	0	0	0	0	0	1
READ	0	0	0	I	0	0	1	0
READ BACKWARD	0	0	0	I	1	1	0	0
CONTROL	0	0	C	C	C	1	1	1
MODE SET	D	D	M	M	M	0	1	1

X, I = 1 or 0 bit

CCC (Control Code)

000 = REWIND
 001 = REWIND WITH INTERLOCK
 010 = ERASE
 011 = WRITE TAPE MARK
 100 = BACKSPACE BLOCK
 101 = BACKSPACE FILE
 110 = FORWARD SPACE BLOCK
 111 = FORWARD SPACE FILE

DD (Density Set)

00 = 200 bpi
 01 = 556 bpi
 10 = 800 bpi
 11 = Set 9-track Mode

} 7-track NRZI
 Operation

DDMMM (Maintenance Mode)

00001 = RESET FAILURE-FINDING MODE
 01001 = SET DEVICE SIMULATION MODE
 10001 = SET MONITOR MODE

MMM (Mode Modifiers; DD = 11 only)

000 = 1600 bpi Phase Encoding (Reset Condition)
 001 = 800 bpi NRZI

MMM (Mode Modifiers; DD ≠ 11 (refer to next page)).

NOTE: 9-track operation overrides but does not reset a 7-track mode setting.
 7-track operation overrides but does not reset a 9-track mode setting.
9-track operation mode settings apply only to WRITE, WRITE TAPE MARK, or ERASE commands executed from load point.

MMM (Mode Modifiers; DD ≠ 11)

MMM (Mode Modifiers DD ≠ 11)	Set Density	Set Odd Parity	Set Even Parity	Data Converter On	Data Converter Off	Translator On	Translator Off	Request TIE (Track in Error)	Low Gain	
000										NOP (No Operation)
001										Failure-Finding Mode Only
010	x	x		x			x			Reset Condition (Only if Data Converter installed)
011 (DD = 00)								x		9-track only
011 (DD = 01)									x	*
100	x		x	x			x			
101	x		x	x		x				
110	x	x		x			x			Reset Condition (If Data Converter not installed)
111	x	x		x		x				

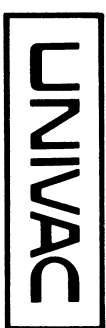
*The low gain condition will apply to the "READ" or "SPACE" operation immediately following the MODE SET command. At the end of the operation, the mode is reset to normal.

X = Condition set or activated by related mode modifier bit configurations.

U12/U16 Subsystem Type 5017-XX									
STATUS, SENSE DATA, MONITOR SENSE DATA, AND SENSE BYTE BIT-DECODE MNEMONICS*									
BIT POSITION	0	1	2	3	4	5	6	7	
STATUS BYTE	ATTENTION	STATUS MODIFIER	CONTROL UNIT END	BUSY	CHANNEL END	DEVICE END	UNIT CHECK	UNIT EXCEPTION	
SENSE BYTE S	BYTE 0	*CMRJ Command Reject	*INRQ Inter-vention Required	*BSCK Bus Out Check	*EQCK Equipment Check	*DACK Data Check	*OVRN Overrun	*WDCZ Word Count Zero	*SB07 Data Converter Check *DCCK
	BYTE 1	*NOIS Noise	*TUSA Tape Unit Status "A"	*TUSB Tape Unit Status "B"	*7TRK Seven Track	*BOT Load Point	*EOT End of Tape	*TUFPP File Protect	*TUIC Tape Unit Incompatibility
	BYTE 2	*TIE0 TIE0	*TIE1 TIE1	*TIE2 TIE2	*TIE3 TIE3	*TIE4 TIE4	*TIE5 TIE5	*TIE6 TIE6	*TIE7 TIE7
	BYTE 3	*VRC RWVRC RVRC *RVRC	*MDT MDT LRC *LRC	*SKEW SKEW	*PSTC Postamble CK CRC *CRC	*SDT SDT WVRC *WVRC	*TUPH 1600 Bpi	*BKWD Backward	*SB37 "0"
	BYTE 4	*RWAY Runaway	*TMFT Tape Motion Fault	*SB42 "0"	*SB43 "0"	*SB44 "0"	*STAL Stall	*TPFT Tape Fault	*SB47 "0"
MONITOR BYTE S	BYTE 0	*PC00 Prog Count Bit 0	*PC01 Prog Count Bit 1	*PC02 Prog Count Bit 2	*6AV 6AV	*7AV 7AV	*8AV 8AV	*RES Channel Interface Reserved	*SIM Device Simulation Mode Set
	BYTE 1	*WRIT Write	*READ Read	*BKWD Backward	*SPAC Space	*FILE File	*REW Rewind	*WTM Write Tape Mark	*ERAS Erase
	BYTE 2	*PRER Backward Cmd. at LP	*SENT Stop Sentinel Detected	*TMD Tape Mark Detected	*PSTA Inhibit Status Set	*CTRM Early Terminate	*MRPH Erase Mode Set	*DTP DTP CYP *CRCP	*DT0 DT0/CY0 *CRC0
	BYTE 3	*DT1 DT1/CY1 *CRC1	*DT2 DT2/CY2 *CRC2	*DT3 DT3/CY3 *CRC3	*DT4 DT4/CY4 *CRC4	*DT5 DT5/CY5 *CRC5	*DT6 DT6/CY6 *CRC6	*DT7 DT7/CY7 *CRC7	*PZEP PZEP/LP *LRCP
	BYTE 4	*PZE0 PZERO LO *LRC0	*PZE1 PZER1 L1 *LRC1	*PZE2 PZER2 L2 *LRC2	*PZE3 PZER3 L3 *LRC3	*PZE4 PZER4 L4 *LRC4	*PZE5 PZER5 L5 *LRC5	*PZE6 PZER6 L6 *LRC6	*PZE7 PZER7 L7 *LRC7

SHEET 16-3 REVISION -

SH04479 SPECIFICATION SYMBOL



SPECIFICATION SHEET

Uniservo 12/Uniservo 16 Subsystem Type 5017

1. Command Repertoire

Command codes not shown and MODE SET or SENSE commands without the corresponding feature in the Control Unit are invalid and will be rejected by the Control Unit. The Command Reject indication sets the UNIT CHECK bit of the status byte.

1.1 TEST (XX000000 or XX110000)

The TEST command initiates the sequence of presenting the status byte to the channel. The STATUS IN pending condition and the status register will be cleared when the status byte is accepted by the channel. TEST commands generate no new status.

1.2 TEST INHIBIT STATUS (XX010000)

This command is performed as a TEST command. In addition, further Control Unit initiated sequences to present status to the channel will be inhibited. This condition remains until reset by a System or Selective Reset, or a RESET INHIBIT STATUS command.

1.3 RESET INHIBIT STATUS (XX100000)

This command is performed as a TEST command. In addition, the Inhibit Status In condition is reset, allowing Control Unit initiated sequences for presentation of status to the channel.

1.4 SENSE (00000100)

The SENSE command stores the current status of the selected tape unit, and then proceeds to transfer the sense bytes to the channel. The information in the sense bytes contains the current status of the tape unit and any error or fault conditions that occurred during the last operation. The status byte presented at the completion of the SENSE command will contain CHANNEL END (Bit 4) and DEVICE END (Bit 5). Any non-ready condition detected in the selected tape unit will not be indicated in the status byte.

1.5 SENSE/RESERVE (11110100)

This command is performed as a SENSE command. In addition, the I/O Interface which issued the command is locked on to the Control Unit. This will prevent operations issued from the other I/O Interface from being initiated until a Reset or a SENSE/RELEASE command is received from the operating interface.

1.6 SENSE/RELEASE (11010100)

- 1.6.1 This command is performed as a SENSE command. In addition, the reserved state set by the SENSE/RESERVE command, is reset and the Control Unit is free to operate with either I/O Interface. The Control Unit is released when the end status byte for the SENSE/RELEASE command is accepted by the channel.
- 1.6.2 The actual reserve or release operations are performed during initial selection. After initial selection, the sense operation proceeds as usual. If the reserve and release capability is not utilized, then the first I/O Interface to select the Control Unit will lock on for the duration of the operation.
- 1.6.3 At the completion of the operation in progress, the Control Unit will be free to operate with either I/O Interface unless:
- Command chaining is indicated.
 - The end status byte is stacked by the channel.
 - The end status byte contains the UNIT CHECK bit (bit 6).
 - No command other than TEST, SET INHIBIT STATUS, RESET INHIBIT STATUS, or MODE SET (except REQUEST TIE) has been initiated since condition (c) occurred.

1.7 WRITE (00000001)

- 1.7.1 The WRITE command moves tape on the selected unit in the forward direction. Data is requested from the channel and is written on tape until the channel terminates the data transfer. Writing in the end-of-tape area will cause the UNIT EXCEPTION bit (bit 7) to be included in the end status byte. UNIT EXCEPTION will be set at the completion of the operation in which the end-of-tape marker is detected.
- 1.7.2 The following description of a normal termination applies for WRITE, READ and READ BACKWARD operations: The end status byte, consisting of the CHANNEL END bit (bit 4) and the DEVICE END bit (bit 5) along with other status bits, if any, will be presented to the channel when the end-of-block is detected on the Read or Check Read. The end-of-block condition is detected when data in all tracks "drops out" for more than 790 μ s on a U12 or U6-C, or more than 280 μ s on a U16 or U8-C.

1.8 READ (00010010)

- 1.8.1 The READ command moves the tape on the selected unit in the forward direction. Data is transferred from the tape and sent to the channel until the end-of-block occurs or the channel terminates the transfer.

The end status byte will include the UNIT EXCEPTION bit (bit 7) if the block read is a tape mark block.

READ (000I0010) (cont)

- 1.8.2 In NRZI mode, the tape mark character will not be transferred to the channel when detected as a single character tape mark block. However, if the tape mark code appears anywhere in the body of a multiple-character block, it will be transferred to the channel as data. The tape mark in 7-track operations is detected in both even and odd parity modes during "read" and "space" operations.

1.9 READ BACKWARD (000I1100)

- 1.9.1 The READ BACKWARD command moves the tape on the selected unit in the backward direction and causes a block of data to be read in the reverse order in which it was written on the tape. Data is transferred from the tape and sent to the channel until the end-of-block occurs or the channel terminates the transfer.

Sensing a tape mark is the same as in the READ operation.

- 1.9.2 Reading backward in 7-track mode should not be attempted with tapes generated on other than U6-C, U8-C, U12, U16, or other tape units which provide scatter correction of the Longitudinal Redundancy Check (LRC) character.

The READ BACKWARD operation in 7-track data conversion mode should not be attempted with tapes having block length other than a multiple of four frames.

- 1.9.3 The I bit in the read command codes pertains to the Phase Encoding mode of operation only. When this bit is a one, the UNIT CHECK bit (bit 6) will be included in the end status byte if a correctable error occurred during the current read operation (see description of Bit 4, Sense Byte 3, and the Command Code Chart).

1.10 CONTROL (00CCC111)

The CONTROL command involves no transfer of data. When the selected tape unit is tested and is in an operational state, the status byte consisting of the CHANNEL END bit (bit 4) only will be presented to the channel.* The end status byte will include the CONTROL UNIT END bit (bit 2) if the Control Unit was addressed or an unusual condition was detected and caused the UNIT CHECK or UNIT EXCEPTION bit to be set while the Control Unit was busy independently of the Channel. The Control Unit is considered busy independently of the Channel during the interval between the acceptance of the status byte containing CHANNEL END and the acceptance of the status byte containing DEVICE END by the channel.*

The particular control operation is specified by the modifier bits (CCC) of the command. The description of each operation follows.

1.11 REWIND (CCC=000)

- 1.11.1 This command rewinds the tape on the selected unit to load point. If the tape is already rewound, the operation proceeds as in other CONTROL commands with respect to the presentation of the CHANNEL END and DEVICE END status bits. If the tape is not rewound, the CHANNEL END status byte will be presented at

*Exceptions to these statements are given under REWIND.

REWIND (CCC=000) (cont)

the completion of the operation in the Control Unit, i.e., once the rewind operation has successfully been initiated in the tape unit. Once the CHANNEL END bit has been accepted, the Control Unit is available.

- 1.11.2 The rewind operation terminates in the tape unit when the tape is positioned at load point and available for use. At this point a DEVICE END status byte is presented to the Channel indicating end of rewind. If the operation in the tape unit terminates unsuccessfully, e.g., due to power dropping, an end status byte will be presented containing the UNIT CHECK bit (Bit 6). CONTROL UNIT END is not returned in this case.
- 1.11.3 Since the CHANNEL END status byte on a successfully initiated rewind operation indicates that the operation is complete at the Control Unit level, unusual conditions or addressing of the Control Unit beyond this point will not result in the inclusion of the CONTROL UNIT END bit (Bit 2) in the end status byte.

1.12 REWIND WITH INTERLOCK (CCC=001)

- 1.12.1 This command rewinds the tape on the selected unit to the unload point and sets the interlock condition in the tape unit. The operation in the Control Unit terminates after the operation has been initiated in the tape unit. The end status byte consisting of the UNIT CHECK bit (Bit 6), the DEVICE END bit (Bit 5), and the CONTROL UNIT END bit (Bit 2) is presented to the channel. The operation in the tape unit terminates when the tape is positioned at the unload point.
- 1.12.2 If the unit set to the interlock condition is addressed (on other than a SENSE command), the status byte of that command will contain the UNIT CHECK bit (Bit 6) only, to indicate that the addressed tape unit is not ready. The interlock condition of the tape unit can only be removed by manual intervention.

1.13 ERASE (CCC=010)

- 1.13.1 The ERASE command moves the tape on the selected unit forward and erases tape for approximately 3.5 inches. The end status byte consisting of the DEVICE END bit (Bit 5) along with other bits, if any, will be presented to the channel when the erase timing in the Control Unit has expired. The tape is checked for spurious pulses arising from any portion of the tape that is unerased.
- 1.13.2 Performing an ERASE operation in the end-of-tape area causes an end status byte to be presented to the channel consisting of the UNIT EXCEPTION bit (Bit 7), the DEVICE END bit (Bit 5) and the CONTROL UNIT END bit (Bit 2).

1.14 WRITE TAPE MARK (CCC=011)

- 1.14.1 This command moves the tape on the selected unit forward generating an interblock gap of approximately 3.5 inches before writing the tape mark in the NRZI mode of operation. In the Phase Encoding mode the normal gap is generated before writing the tape mark burst. When writing a tape mark in 7-track NRZI mode, the parity mode setting is overridden (but not reset) and the tape mark is written with even parity.

WRITE TAPE MARK (CCC=011) (cont)

- 1.14.2 When the end-of-block is detected on Check Read, the end status byte, consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the channel. Performing this operation in the end-of-tape area results in the same end status byte as the ERASE operation.
- 1.15 BACKSPACE BLOCK (CCC=100)
- 1.15.1 This command moves the tape on the selected unit to the next interblock gap in the backward direction. When the end-of-block is detected on Read, the end status byte consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the channel.
- 1.15.2 Sensing a tape mark causes the UNIT EXCEPTION bit (bit 7) and the CONTROL UNIT END bit (bit 2) to be included in the end status byte along with the DEVICE END bit (bit 5).
- 1.15.3 During 7-track BACKSPACE BLOCK operations, tape marks may be erroneously identified with tapes generated by other than U6-C, U8-C, U12, U16, or other tape units which provide scatter correction of the LRC character. The verification of the tape mark is accomplished by reading forward.
- 1.16 BACKSPACE FILE (CCC=101)
- 1.16.1 This command moves the tape on the selected tape unit backward to the interblock gap beyond the next tape mark encountered. If a tape mark is not encountered, the tape will stop at load point. Sensing the tape mark does not set the UNIT EXCEPTION bit or the CONTROL UNIT END bit.
- 1.16.2 Erroneous termination of BACKSPACE FILE operations may occur when in 7-track mode due to uncertainty in detection of tape marks. This may occur during BACKSPACE FILE operations with tapes generated by other than U6-C, U8-C, U12, U16, or other tapes which provide scatter correction of the LRC character. Verification is obtained by reading forward. The BACKSPACE FILE operation terminates when the end-of-tape mark block is detected.
- 1.17 FORWARD SPACE BLOCK (CCC=110)
- This command moves the tape on the selected unit to the next interblock gap in the forward direction. When the end-of-block is detected on Read, the end status byte consisting of the DEVICE END bit (bit 5) along with other bits, if any, will be presented to the channel. Sensing a tape mark is the same as in a BACKSPACE BLOCK operation.
- 1.18 FORWARD SPACE FILE (CCC=111)
- This command moves the tape on the selected unit forward to the interblock gap, beyond the next tape mark encountered. Sensing the tape mark does not set the UNIT EXCEPTION bit or the CONTROL UNIT END bit.
- The FORWARD SPACE FILE operation terminates when the end-of-tape mark block is detected.

1.20 MODE SET (DDMMMO11)

1.20.1 The MODE SET command is used to select the data transfer mode of operation. Bits 0, 1, 2, 3, and 4 determine the mode selected. Once set, data transfer modes normally remain set until modified by another MODE SET command or reset by the channel. The reset conditions are 1600 bpi Phase Encoding mode (9-track), and 800 bpi NRZI mode (7-track). For the 7-track mode, the reset condition includes odd parity, data converter on, and translator off. If the data converter feature is not installed, the reset condition is odd parity, data converter off, and translator off. The 7-track and 9-track mode settings are independent of one another. The mode that prevails (7- or 9-track) will be the mode determined when the tape unit is selected on the next operation. The mode setting command (for 9-track operation), applies to a WRITE, WRITE TAPE MARK, or ERASE operation starting at load point. The setting holds for the tape unit until the tape is returned to load point and a new setting is received. The read operation requires no mode setting (for 9-track operation). The setting will be determined by reading the identification burst at the beginning of the tape. A burst of bits in the P track between load point and the first recorded tape block identifies a 1600 bpi tape, the lack of this burst identifies an 800 bpi tape. Again, this setting will be retained until the tape is returned to load point.

1.20.2 Seven-track operations require mode settings on write and read operations.

1.20.3 ALL MODE SET commands except REQUEST TIE are completed during the initial selection sequence. Normally CHANNEL END and DEVICE END are included in the status byte presented at the end of initial selection. When this status byte is accepted, the Control Unit is available for a new operation. For the REQUEST TIE command, the status presented at the end of initial selection is normally clear (binary zeros). After the single byte data transfer is complete, the status byte indicating termination will be presented to the channel. Normally the bits included are CHANNEL END and DEVICE END.

MODE SET commands will not clear the SENSE bytes when accepted.

1.20.4 MODE (000)

This defines a "NO OPERATION" command. No mode setting will be altered.

1.20.5 MODE (001)

This mode is used for failure-finding only. Non-diagnostic programs should not attempt to set this mode of operation.

1.20.6 MODE (010)

This mode defines a 7-track mode with odd parity, translator off, data converter on, and a density defined by the DD bits.

1.20.7 MODE (011)

When DD = 00, this mode defines a REQUEST TIE command. This operation causes a byte of information to be transferred to the Control Unit, to be used for error correction on 9-track NRZI tapes. If the following READ or READ BACKWARD operation is addressed to either a 9-track Phase Encoding only tape unit or a 7-track unit, data correction will not be attempted and the track-in-error information will be cleared.

When DD = 01, this mode defines a low gain setting for the next "read" or "space" operation. Low gain settings apply to operations on Phase Encoded or NRZI tapes. The low gain condition will be cleared at the end of the operation following the MODE SET.

1.20.8 MODE (100)

This mode defines a 7-track mode with even parity, translator off, data converter off, and a density defined by the DD bits.

1.20.9 MODE (101)

This mode defines a 7-track mode with even parity, translator on, data converter off, and a density defined by the DD bits.

1.20.10 MODE (110)

This mode defines a 7-track mode with odd parity, translator off, data converter off, and a density defined by the DD bits.

1.20.11 MODE (111)

This mode defines a 7-track mode with odd parity, translator on, data converter off, and a density defined by the DD bits.

1.30 MAINTENANCE COMMANDS1.30.1 RESET FAILURE-FINDING MODES (00001011)

This command resets the Device Simulation Mode and Operation Monitor Mode, if they were set. The control unit will return to the normal state. The System Reset, or Selective Reset, will also reset these modes.

1.30.2 SET DEVICE SIMULATION MODE (01001011)

This command activates the tape unit simulation logic. The signals to the tape unit will be blocked and simulated return signals will be generated during the execution of subsequent commands. This facilitates the checkout of the control unit without a tape unit.

1.30.3 SET DEVICE SIMULATION MODE (01001011) (cont)

- 1.30.3.1 For write operation, the write data received from the Channel will be processed through the write logic, then will be fed back into the read recovery logic. The Cyclic Redundancy Check (CRC) frame will be generated, but a Longitudinal Redundancy Check (LRC) frame will not be generated. However, the content of the LRC register will be the LRC frame supposed to be written on the tape.
- 1.30.3.2 For read operation, the content of the CRC register will be used as the simulated data. The content will be shifted end-around one place from high to low order for every frame generated. The simulated data will be generated at nominal data frequency until it receives the data terminate signal from the Channel.
- 1.30.3.3 The output of CRC register will be added with the R.O. pattern (111010111) in binary addition before it is gated into the read recovery logic. The CRC register will be precleared only before a write, simulated write, or read operation.

To set up desired data in the CRC register for the simulated read, a write operation should be performed beforehand. The parity of the content of the CRC register depends on the number of characters written during the previous write operation. The vertical parity checker in the read recovery can be checked with the data having a wrong parity.

If the initial content or the shifted content of the CRC register does correspond with R.O. pattern, the generated data block will have a blank frame for every ninth frame. By this, the frame dropout checker in the read recovery can be checked.

- 1.30.3.5 For Write Tape Mark operation, the generated Tape Mark frame will be gated into the read recovery logic.

For space, or space file operation, one frame of the generated data from the CRC register will be gated into the read recovery logic. The tape mark indications will be set if the generated data correspond with the tape mark code.

- 1.30.3.6 The erase operation will be executed in the normal manner.

1.30.4 SET OPERATION MONITOR MODE (10001011)

This command activates the logic which transmits the Monitor Sense bytes instead of the Sense Data bytes during the subsequent sense operation(s).

The Monitor Sense bytes (5 bytes) provide detailed information about the operational condition caused by the last operation.

2. STATUS BYTE

2.1 The Status Byte provides the overall information about status and conditions detected in the operation completed. The Control Unit initiates the sequences to present status to the channel at the end of the Initial Selection Sequence, at the completion of unit selection of a CONTROL operation, and at the completion of the operation. The status bits are reset to binary zero when the status presented is accepted by the channel. The following defines the significance of binary one in each status bit.

Bit DesignationInterpretation

2.2 0 ATTENTION Indicates that a tape unit has become ready (i.e. Tape Unit Status A active and Tape Unit Status B inactive) after the Control Unit has detected a Non-Ready State in that tape unit. This status bit is indicative of an operator intervention at the tape unit (e.g. loading a new tape). This status is unsolicited and is not presented as a result of any previously initiated operation. The least significant four bits of the device address associated with the ATTENTION Status byte indicate the address of the tape unit which became ready. The monitoring of the state of each tape unit takes place when the Control Unit has completed the execution of previously issued commands.

If either simultaneous feature is installed, both Control Units will attempt to present ATTENTION when required. Furthermore, when the Dual Access Control feature is installed, the ATTENTION bit will be presented to both I/O Interfaces. Changes of state on units not "existent" on an I/O Interface will not be presented to that interface.

2.3 1 STATUS MODIFIER Present with the BUSY bit to indicate Control Unit busy. On a Control Unit with two I/O Channel Interfaces, Control Unit busy is indicated to one Interface if an Initial Selection Sequence is attempted while the Control Unit is presently operating with, or reserved by, the alternate I/O Interface.

2.4 2 CONTROL UNIT END

a. When the Control Unit completes a CONTROL operation that kept it busy independently of the channel, during which time it was either addressed (causing a Control Unit busy indication) or an unusual condition was detected (UNIT CHECK or UNIT EXCEPTION), CONTROL UNIT END will be presented with DEVICE END. The Control Unit is considered busy independently of the Channel during the interval between the acceptance of the CHANNEL END status byte and the DEVICE END status byte by the channel.

b. Whenever a Control Unit busy sequence occurs on one I/O Interface of a Dual Access Control Unit, and the Control Unit is presently operating with, or reserved by, the alternate I/O Interface, a CONTROL UNIT END Status byte will be presented to the I/O Interface that received the Control Unit busy indication when the Control Unit completes the operation in progress, or is released by, the alternate I/O Interface.

	<u>Bit Designation</u>	<u>Interpretation</u>
2.5	2 CONTROL UNIT END	During the presentation of the Control Unit End Status byte to the I/O Interface that received the Control Unit busy indication, the alternate I/O Interface will not be denied access to the Control Unit.
2.6	3 BUSY	<p>a. Present with STATUS MODIFIER to indicate Control Unit Busy.</p> <p>b. Present with status already stored if status pending for addressed tape unit, when the command is other than a TEST, SET INHIBIT STATUS or RESET INHIBIT STATUS.</p>
2.7	4 CHANNEL END	<p>For SENSE, REQUEST TIE, WRITE, READ and READ BACKWARD commands, CHANNEL END is presented with DEVICE END when the operation is completed at the Control Unit level. It is presented on CONTROL commands, after the tape unit is tested and available. On REWIND commands, when the tape is not initially at load point, CHANNEL END is presented at the completion of the operation at the Control Unit level.</p> <p>If early errors prevent tape motion, and the operation is aborted early, the CHANNEL END status bit is not sent to the channel. It is also presented at the end of initial selection with DEVICE END on MODE SET commands (except REQUEST TIE).</p>
2.8	5 DEVICE END	<p>a. Indicates that the operation (except a successfully initiated REWIND command) is complete at the Control Unit level. When errors are detected before tape motion is initiated, DEVICE END is not presented with error status. Operations involving data transfers that are aborted while in progress (e.g. due to Equipment Check) will cause DEVICE END to be sent with UNIT CHECK and CHANNEL END.</p> <p>b. Indicates that a REWIND has been completed at the tape unit level. If the REWIND terminates unsuccessfully in the tape unit, DEVICE END will be presented with UNIT CHECK.</p>
2.9	6 UNIT CHECK	<p>a. Indicates a bit in Sense Byte 0 has been set as a result of the current operation. (If the error condition is detected before tape motion is initiated, UNIT CHECK will be presented without end status.)</p> <p>b. The selected tape unit is busy, i.e., ready and rewinding or ready and under control of the other Control Unit. End status will not be presented with UNIT CHECK. When a rewinding tape unit is selected by the Control Unit which issued the rewind operation, the tape unit is busy until the DEVICE END status byte associated with the end of rewind has been accepted by the channel.</p> <p>c. A rewind operation terminated unsuccessfully in the tape unit. DEVICE END is presented with UNIT CHECK.</p>

Bit DesignationInterpretation

6 UNIT CHECK
(cont)

- d. A READ BACKWARD, BACKSPACE BLOCK, or BACKSPACE FILE is attempted on a tape unit when the tape is positioned at load point. (No end status is presented in this case.)
- e. A REWIND WITH INTERLOCK has been completed at the Control Unit level, i.e. when the tape unit becomes non-ready. If the operation is initiated, DEVICE END will be presented with UNIT CHECK and CONTROL UNIT END.

2.10

7 UNIT
EXCEPTION

Indicates:

- a. A WRITE, WRITE TAPE MARK, or ERASE operation is performed in the end-of-tape area.
- b. A tape mark is sensed during a READ, READ BACKWARD, FORWARD SPACE BLOCK, or BACKSPACE BLOCK operation.

In cases a. and b. UNIT EXCEPTION is presented with DEVICE END (and CONTROL UNIT END on CONTROL operations).

3.

Sense Data Bytes

3.1

The sense data provides detailed information about the unusual conditions detected in the last operation and the current status of the selected tape unit. Sense bits that set as a result of error or fault conditions during an operation will remain set until cleared upon initiation of a new command. Executing a SENSE command will not change the state of these bits (all those not marked with an asterisk). Bits that are marked with an asterisk (*) will reflect the current state of the selected tape unit. For example, if a "non-ready" condition is detected and the operation is aborted early, Tape Unit Status B and Intervention Required will set in sense bytes 1 and 0 respectively. If, between the time that the operation was aborted, and the SENSE command executed, the tape unit became "ready", then the sense data returned to the channel will be Intervention Required and Tape Unit Status A.

3.2

No additional sense information can be set as a result of executing a SENSE command once the command has been accepted (i.e. odd command byte parity and valid command code). The following tables describe the significance of the sense bytes.

SENSE BYTE 0		MODE OF OPERATION	
BIT	DESIGNATION	PHASE-ENCODING	NRZI
0	Command Reject	<p>a. Set when a WRITE, WRITE TAPE MARK, or ERASE command was attempted on a file protected tape unit.</p> <p>b. Set when an invalid command is transmitted to the Control Unit. (This condition will not be set if a BUS OUT Check occurred on a command transfer.)</p> <p>c. The Tape Unit Incompatibility bit was set (Bit 7, Sense Byte 1).</p>	Same
1	Intervention Required	Set whenever tape unit status A is inactive, i.e., a non-existent or non-ready tape unit was selected on other than a SENSE command. (Bit 1 is not set in Sense Byte 1.)	Same
2	BUS OUT Check	Set whenever even parity appears on the BUS OUT for data or command transfers. During WRITE operations, if this condition is set on a data transfer, the operation is terminated, and the error byte is not written on the tape. If the error occurs on the first data transfer Word Count Zero will be set in conjunction with BUS OUT Check.	<p>Same</p> <p>If this condition is detected during the data transfer on a REQUEST TIE command, the operation terminates but the information received is ignored. Any TIE information already stored is not disturbed.</p>
3	Equipment Check	Set whenever an Equipment Check occurs, i.e., bits 0, 1, or 5 of Sense Byte 4 have been set.	Same
4	Data Check	Set whenever a Data Check occurs, i.e., bit 0 of Sense Byte 1, or bits 0, 1, 2, 3, 4 of Sense Byte 3 have been set.	Same

SENSE BYTE 0 (cont)		MODE OF OPERATION (cont)	
BIT	DESIGNATION	PHASE-ENCODING	NRZI
5	Overrun	<p>Set if service is requested on the I/O Interface but data cannot be transferred due to a late response signal from the channel.</p> <p>If this occurs on the first data transfer of a WRITE operation, Word Count Zero will be set in conjunction with Overrun. (Not set on REQUEST TIE or SENSE commands.)</p>	Same
6	Word Count Zero	<p>a. Set during a WRITE operation if transfer of data is prevented when the first byte of data is requested. This can be due to a "COMMAND OUT" response to the data byte request, even parity detected for the data byte transfer (see BUS OUT Check), or a channel overload (see Overrun). No new tape motion will occur if any of these conditions are detected. If non-stop operation is indicated, the previous operation will terminate properly.</p> <p>b. Set if the end-of-block is detected on READ or READ BACKWARD operations before any data bytes are recognized (missed start sentinel).</p>	Same
7	Data Converter Check	Not applicable—always set to zero.	Set on 7-track operations only.

MODE OF OPERATION (cont)

SENSE BYTE 1

BIT	DESIGNATION	PHASE-ENCODING	NRZI
0	Noise	<p>When Reading or Read Checking data from Phase Encoded tapes, the checks performed to set the Noise bit are essentially the same as in NRZI recording. However, two basic differences pertaining to the quality of the check exist.</p> <p>First, when checking for tape hash, the outputs of the block detector circuits for each track are monitored. Since these circuits tend to reject noise, a single "bit pick-up" would not activate the block detector outputs and the Noise bit would not set. In NRZI recording, the Noise bit would set, since the data lines are monitored directly.</p> <p>Second, when checking for gaps in the data, or data "drop-outs", all block detector outputs must be deactivated together, before the Noise bit sets. In Phase Encoded recording, a signal results from writing either a "1" bit or a "0" bit. Therefore, within the block, a signal is normally present in all tracks. Thus only a relatively serious condition could cause the Noise bit to set (e.g., a lateral crease in the tape). In NRZI recording, however, a signal is present only when "1" bits are written. Therefore, a small defect in one track, when recording one bits only in that track, will cause the Noise bit to set.</p> <p>The Noise bit, then, should set relatively infrequently, as compared to the NRZI mode of operation.</p>	<p>a. Tape Hash During WRITE or WRITE TAPE MARK operations, data (or noise due to tape defects) was detected on Read Check sooner than was expected.</p> <p>During ERASE operations, data (or noise due to tape defects) was detected on Read Check while the tape was being erased.</p> <p>b. During WRITE or WRITE TAPE MARK operations, while Read Checking the recorded data, a gap in the data was detected which was not long enough to set the end-of-block condition.</p> <p>This can occur due to unrecordable areas on the tape.</p> <p>c. During READ, READ BACKWARD, FORWARD SPACE BLOCK, and BACKSPACE BLOCK operations a data "drop-out" occurred on Read which was not long enough for the end-of-block condition to be detected.</p> <p>For conditions a, b, and c, above tape motion does not cease in the middle of the block. Writing (or erasing) will continue to the normal termination point.</p> <p>d. Bit 6 of Sense Byte 4 was set (Tape Fault).</p>

SENSE BYTE 1 (cont)

MODE OF OPERATION (cont)

BIT	DESIGNATION	PHASE-ENCODING			NRZI
1*	Tape Unit Status A	Selected and Ready			Same
2*	Tape Unit Status B	Not ready, rewinding, or under control of the other Control Unit.			Same
		Status A	Status B	Tape Unit Bit Set in Status Status Byte	
		0	0	Non-existent UNIT CHECK	
		0	1	Not Ready UNIT CHECK	
		1	0	Ready and not busy	
1	1	Ready and busy, i.e. rewinding or under control of other Control Unit. UNIT CHECK			
3*	Seven Track	Same			The selected unit has a seven-track head installed.
4*	Load Point	The tape on the selected unit is positioned at load point.			Same
5*	End of Tape	The tape on the selected unit is in the end-of-tape area.			Same
6*	File Protect	The tape on the selected unit does not have a write enable ring.			Same



SENSE BYTE 1 (cont)

MODE OF OPERATION (cont)

BIT	DESIGNATION	PHASE-ENCODING	NRZI
7	Tape Unit Incompatibility	<p>a. Tape Unit is selected on any command requiring tape motion and any of the following conditions occur:</p> <p>Addressed tape unit is a U6-C or U8-C, 7- or 9-track, and is indicating the phase encoding mode of operation.</p> <p>Addressed tape unit is a U12 or U16, 7-track, and is indicating the phase encoding mode of operation.</p> <p>Addressed tape unit is a U12 or U16, 9-track, and failed to reset to 1600 bpi mode. (Load point only.)</p> <p>b. Tape unit is selected for a "write-type" operation from load point and the following occurs:</p> <p>Addressed tape unit is U6-C or U8-C, 9-track type.</p> <p>c. Tape unit is selected for a "read-type" operation from load point and any of the following conditions occur:</p> <p>Addressed tape unit is a U6-C or U8-C, 9-track, and the tape is written in 1600 bpi phase encoding mode.</p> <p>Addressed tape unit is a U12 or U16, 9-track, and failed to set 800 bpi mode when the tape is written in 800 bpi NRZI mode.</p> <p>d. A "write-type" operation was attempted on a Uniservo 12, 6-C, or 8-C on the Second Control Unit (CUB).</p>	<p>Same</p> <p>b. Tape unit is selected for a "write-type" operation from load point and the following occurs:</p> <p>Addressed tape unit is a U12 or U16, 9-track, and failed to set to 800 bpi mode.</p> <p>Same</p> <p>Same</p>

NOTE: In cases a, b, and d above, no tape motion occurs as a result of the attempted operation.

In case c above, the condition is detected after the the first "read type" operation has been initiated. If the "read-type" command is to be attempted a second time, a REWIND command should first be executed in order to reposition the tape. Case d. does not apply if Bank Write/Write Simultaneity Feature is installed (F1105-00).



SENSE BYTE 2 MODE OF OPERATION (cont)

BIT	DESIGNATION	PHASE-ENCODING	NRZI
0	Track in Error	Not applicable—Always set to zeros.	<p>This sense byte contains the track-in-error indicator bits that are set at the end of a READ or READ BACKWARD operation if a Data Check has been encountered. A single 1 bit in any bit position indicates a single-track error, the bit position indicates the track in error. Binary zeros in bits 0 → 7 implies bit P.</p> <p>If bits 6 and 7 contain binary ones, then a multiple track error has been encountered and no track error identification has been made.</p> <p>At the completion of a properly executed READ or READ BACKWARD operation with no Data Check, sense byte 2 contains at least bits 6 and 7 set to 1's. No error correction is attempted when operating with seven-track tape units. Bits 6 and 7 are set to 1's in sense byte 2.</p>
7			

MODE OF OPERATION (cont)

SENSE BYTE 3

BIT	DESIGNATION	PHASE-ENCODING	NRZI
0	R/W VRC	A Vertical Redundancy Check occurred on a data frame without a Dead Track indication during a WRITE, READ, or READ BACKWARD operation (Uncorrectable error).	<p>a. A Vertical Redundancy Check occurred on a data frame or CRC frame during a READ or READ BACKWARD operation. This indicator is not set after an Overrun indication.</p> <p>b. A speed check error occurred during a WRITE or WRITE TAPE MARK operation.</p>
1	Multiple Dead Track Check-Track Start failure/LRC	<p>a. A marginal signal occurred in more than one track on a READ or READ BACKWARD operation. (Uncorrectable.)</p> <p>b. Valid information was not detected in at least one track while Read Checking the preamble during a WRITE operation. This indicates a track start failure, possibly indicating the track was never written on the tape. This check is only performed during the preamble before the circuits that detect marginal signals are operable. Normally Bit 4 of Sense Byte 3 will set in conjunction with this bit if the track is missing entirely.</p>	A longitudinal Redundancy Check occurred during a WRITE, WRITE TAPE MARK, READ, or READ BACKWARD operation.
2	Skew	Excessive skew is detected during a WRITE, READ or READ BACKWARD operation. (Deskew register underflow.)	Excessive skew detected while read checking recorded data on a WRITE or WRITE TAPE MARK operation.
3	Postamble Check/CRC	Set when the postamble following the data is not read correctly, or is recognized before the actual end of data (early stop sentinel).	A Cyclic Redundancy Check occurred during a READ or READ BACKWARD operation (9-track only).

SENSE BYTE 3 (cont)

MODE OF OPERATION (cont)

BIT	DESIGNATION	PHASE-ENCODING	NRZI
4	Dead Track Check/W VRC	<p>a. Indicates at least one track with marginal signal during WRITE or WRITE TAPE MARK operations.</p> <p>b. Indicates a marginal signal in only one track during a READ or READ BACKWARD operation (correctable error). This bit will not be set if a multiple track error occurs (see Bit 1). If I = 1 in the read command code, and this bit is set, Data Check will set. However, if this bit is set and I = 0 in the read command code, Data Check will not set. In either case, the data is correct.</p> <p>c. Indicates that a tape mark was not properly detected on the Read Check of a WRITE TAPE MARK operation.</p>	A Vertical Redundancy Check occurred on a data frame or CRC frame during a WRITE or WRITE TAPE MARK operation.
5*	Tape Unit— 1600 bpi	The selected tape unit is set to 1600 bpi mode.	Same — This bit is always set to zero when selecting a 7-track tape unit.
6*	Backward	The selected tape unit is conditioned for backward tape motion.	Same
7		NOT USED — Always set to zero.	Same

SENSE BYTE 4		MODE OF OPERATION (cont)	
BIT	DESIGNATION	PHASE-ENCODING	NRZI
0	Runaway Check	<p>a. While read checking recorded data during WRITE, or WRITE TAPE MARK operations, the end-of-block was not detected within at least 8.3 ms (U12 or U6-C) or 2.9 ms (U16 or U8-C) after writing has ceased.</p> <p>b. During all read-type operations, if data is not detected within at least 7.0 seconds (U12 or U6-C) or 2.5 seconds (U16 or U8-C).</p>	Same
1	Tape Motion Fault	<p>a. Tape unit failed to respond to a "start" command. Tape motion may or may not have occurred.</p> <p>b. Tape motion stopped independently of the Control Unit during an operation requiring tape movement. (This condition will be detected if a backward operation is executed <u>into</u> load point.)</p>	Same
2 ↓ 4	These bits are reserved for failure finding mode.		
5	Stall	Indicates that the Control Unit is hung up for more than 2.5 seconds.	Same
6	Tape Fault	During WRITE or WRITE TAPE MARK operations, indicates that the end-of-block was detected sooner than expected. False end-of-block can occur if a data dropout (all tracks) is longer than 790 μ s. on a U12 or U6-C, or more than 280 μ s. on a U16 or U8-C.	Same
7	This bit is reserved for failure-finding mode.		

MONITOR SENSE BYTES

4.

	BYTE 0	BYTE 1	BYTE 2	BYTE 3	BYTE 4
BIT POS.	PC1M	PC2M	PC3M	PC4M	PC5M
0	MPC00	PFW	PRERR	DT1 CY1	PZERO L0
1	MPC01	PFR	SENT	DT2 CY2	PZER1 L1
2	MPC02	PFB	TMD	DT3 CY3	PZER2 L2
3	6AV	PFSFL	PSTAT	DT4 CY4	PZER3 L3
4	7AV	PFFL	CHTRM	DT5 CY5	PZER4 L4
5	8AV	PFRW	PHASE	DT6 CY6	PZER5 L5
6	RES	PFWTM	DTP CYP	DT7 CY7	PZER6 L6
7	SIM	PFERS	DT0 CY0	PZERP LP	PZER7 L7

MONITOR SENSE BYTE DESCRIPTION

4.1 PC1M

4.1.1 MPC00, MPC01, MPC02 - Contents of CU Program Counter, useful when the SB45 (Stall Condition) FF is set during the execution of any command other than Mode Set Commands. These 3 FF's will then indicate the CU cycle which was effective when the Stall Condition occurred.

4.1.2 6AV, 7AV, 8AV - Status Lines from Servo presently being addressed.

	<u>6AV</u>	<u>7AV</u>	<u>8AV</u>	
	1	0	0	U6-C
	1	1	0	U12
	0	0	1	U8-C
	0	1	1	U16

} Servo
} Available

Any combination other than those listed will result in an unavailable servo.

4.1.3 RES (Reserved) - Indicates that the CU is available for use by only one channel.

4.1.4 SIM - Simulator Mode of Operation in effect.

4.2 PC2M

These bit positions indicate the previous non-Sense, non-Mode Set Command (except Request Tie) executed by the Control Unit.

- PFW - Previous Function Write
- PFR - Previous Function Read (Forward or Backward)
- PFB - Previous Function Backward
- PFSFL - Previous Function Space (Forward or Backward)
- PFFL - Previous Function File
- PFWR - Previous Function Rewind
- PFWTM - Previous Function Write Tape Mark
- PFERS - Previous Function Erase

All zero bits in PC2M represent the generally cleared condition of the CU or a previously executed Request Track in Error Command.

4.3 PC3M

- PRERR - Program Error. Attempted backward operation (Read Backward or Space Backward) with servo at Load Point.
- SENT - Ending Sentinel of the Postamble of a phase recorded data block detected on the previously executed Read type operation.
- TMD - Tape Mark Detected.
- PSTAT - Inhibit Status FF set in Channel Interface Package.
- CHTRM - Channel Termination (TERM) received by the Control Unit on Read (forward or backward) operations before entire block of tape data transferred.
- PHASE - Phase Mode (1600 ppi) set.

- 4.4 PC4M-PC5M - The remaining two bits of Monitor Sense Byte three and Monitor Sense Bytes four and five are dual indications dependent upon the type of servo setting (Bits 5 of Normal Sense Byte 3 (NRZ). NRZ active (high for a phase recording servo) will cause the contents of the Dead Track Register (DTP, 0-7) and the Zeros Alert Register (PZERP, 0-7) to be transmitted to the Channel.

DTP-DT7
CYP-CY7
PZERP-
PZER7
LP-L7

NRZ active (high when servo recording in non-return-to-zero mode) will cause the contents of the Cyclical Redundancy Register (CYP, 0-7) and the Longitudinal Parity Check Register (LP, 0-7) to be transmitted to the channel.

DISC FILE CONTROL

TYPE 5024

1. COMMAND REPERTOIRE:

The table below summarizes all the commands executable by the subsystems. The M bit, when zero defines normal operation. When one, operation is in the multiple track mode.

1.1 TABLE OF VALID COMMAND CODES WITH AND WITHOUT M/T

TYPE	COMMAND	BINARY CODE						HEX CODE	HEX CODE		
		0	1	2	3	4	5	6	7	SINGLE-TRK	MULTI-TRK
CONTROL	NO OPERATION	0	0	0	0	0	0	1	1	03	
	SEEK	0	0	0	0	0	1	1	1	07	
	SEEK CYLINDER	0	0	0	0	1	0	1	1	0B	
	SPACE COUNT	0	0	0	0	1	1	1	1	0F	
	RECALIBRATE	0	0	0	1	0	0	1	1	13	
	SEEK HEAD	0	0	0	1	1	0	1	1	1B	
	SET FILE MASK	0	0	0	1	1	1	1	1	1F	
READ	READ IPL (4)	M	0	0	0	0	0	1	0	02	82
	READ DATA	M	0	0	0	0	1	1	0	06	86
	READ KEY-DATA	M	0	0	0	1	1	1	0	0E	8E
	READ COUNT	M	0	0	1	0	0	1	0	12	92
	READ RO	M	0	0	1	0	1	1	0	16	96
	READ HOME ADDRESS	M	0	0	1	1	0	1	0	1A	9A
	READ COUNT, KEY, DATA	M	0	0	1	1	1	1	0	1E	9E
WRITE	WRITE SPECIAL COUNT, KEY, DATA (1)	0	0	0	0	0	0	0	1	01	
	WRITE DATA	0	0	0	0	0	1	0	1	05	
	WRITE KEY-DATA	0	0	0	0	1	1	0	1	0D	
	ERASE	0	0	0	1	0	0	0	1	11	
	WRITE RO	0	0	0	1	0	1	0	1	15	
	WRITE HOME ADDRESS	0	0	0	1	1	0	0	1	19	
	WRITE COUNT, KEY, DATA	0	0	0	1	1	1	0	1	1D	
SEARCH	SEARCH EQUAL ID	M	0	1	1	0	0	0	1	31	B1
	SEARCH HIGH ID	M	1	0	1	0	0	0	1	51	D1
	SEARCH HIGH OR EQUAL ID	M	1	1	1	0	0	0	1	71	F1
	SEARCH EQUAL KEY	M	0	1	0	1	0	0	1	29	A9
	SEARCH HIGH KEY	M	1	0	0	1	0	0	1	49	C9
	SEARCH HIGH EQUAL KEY	M	1	1	0	1	0	0	1	69	E9
	SEARCH EQUAL HOME ADDRESS	M	0	1	1	1	0	0	1	39	B9
	SEARCH EQUAL KEY DATA (2)	M	0	1	0	1	1	0	1	2D	AD
	SEARCH HIGH KEY DATA (2)	M	1	0	0	1	1	0	1	4D	CD
	SEARCH HIGH EQUAL KEY DATA (2)	M	1	1	0	1	1	0	1	6D	ED

COMMAND REPERTOIRE (continued)

Table of Valid Command Codes with and without M/T (continued)

TYPE	COMMAND	BINARY CODE						HEX CODE	HEX CODE		
		0	1	2	3	4	5	6	7	SINGLE-TRK	MULTI-TRK
SEARCH (cont)	CONTINUE SCAN EQUAL (3)	M	0	1	0	0	1	0	1	25	A5
	CONTINUE SCAN HIGH (3)	M	1	0	0	0	1	0	1	45	C5
	CONTINUE SCAN HIGH EQUAL (3)	M	1	1	0	0	1	0	1	65	E5
	CONTINUE SCAN NO COMP (3)	M	1	0	1	0	1	0	1	55	D5
	CONTINUE SCAN SET COMP (3)	M	0	1	1	0	1	0	1	35	B5
	CONTINUE SCAN SET COMP (3)	M	1	1	1	0	1	0	1	75	F5
SENSE	TEST I-0	0	0	0	0	0	0	0	0	00	
	SENSE I-0	0	0	0	0	0	1	0	0	04	
	SENSE RESERVE	1	1	1	1	0	1	0	0	F4	
	SENSE RELEASE	1	1	0	1	0	1	0	0	D4	

- NOTE:
1. INVALID IF NO RECORD OVERFLOW FEATURE
 2. INVALID IF NO FILE SCAN FEATURE
 3. INVALID IF NO RECORD OVERFLOW AND FILE SCAN FEATURES
 4. THE M BIT WILL BE IGNORED BY THE CONTROL UNIT ON INITIAL LOAD AND A SINGLE RECORD WILL BE READ.

1.2 Set File Mask (0001 1111)

1.2.1 Most commands to the control unit will be part of a "command chain." The Set File Mask command affects certain subsequent commands in the chain. Although the Set File Mask can be executed anywhere in the chain, issuance of this command as the first command protects the entire chain. If an attempt is made to issue more than one Set File Mask within a chain, a Unit Check status, associated with Command Reject sense information will result.

1.2.2 Execution of this command causes one byte of data, called a Mask Byte, to be transmitted from the channel to the control unit. The status pair Device End and Channel End signal completion of the command.

1.2.3 The effect of the Mask Byte on Write Commands is as follows:

<u>Mask Byte</u>	<u>Writes Permitted</u>
00XYXX	All except Home Address and TD Record
01XYXX	None
10XYXX	Data or Key and Data
11XYXX	All

<u>Mask Byte</u>	<u>Seeks Permitted</u>
YYX00XX	All
YYX01XX	Head and Cylinder
YYX10XX	Head
YYX11XX	None

COMMAND REPERTOIRE (continued)Set File Mask (0001 1111) (continued)

1.2.4 The File Mask is cleared to all zeros under the following conditions:

1. End of command chain.
2. Control unit is master cleared.
3. Channel indicates Selective Reset.
4. Channel indicates System Reset.

1.3 Seek Commands

1.3.1 The Seek Commands cause the transfer of six bytes of addressing information to the control unit. Only two of the six bytes are actually used; the remaining bytes are provided for possible future expansion of capabilities.

1.3.2 The significance of the bytes is listed below. The range is the decimal equivalent of the binary number range possible.

<u>Byte</u>	<u>Function</u>	<u>Inclusive Range</u>
0	Not used	Must be zero
1	Not used	Must be zero
2	Not used	Must be zero
3	Cylinder address	0-202
4	Not used	Must be zero
5	Head address	0-9

1.3.3 The Seek command allows positioning to any track and the selection of any Head in order to specify which of the Discs surfaces is to be used. Only Bytes 3 and 5 of the Address are significant when addressing the 8411 Disc.

The Seek Cylinder command is identical to the Seek command when used in addressing the 8411 Disc.

The Seek Head command allows the selection of any Head. Byte 3 of the address is ignored so that no physical positioning motion will occur.

1.3.4 Channel End status will be presented to the Channel after the transfer of the six address bytes to the Control Unit.

Device End status will be presented with Channel End in the case of the Seek Head.

Device End status will not be presented until the completion of Motion Control in the cases of the other Seeks.

1.3.5 By issuing a Seek command to one device and another command to a second device, it is possible to overlap the two commands. Seek commands to all eight devices can be overlapped in this fashion.

COMMAND REPERTOIRE (continued)1.4 Write Commands

Write commands cause information to be transferred from the channel and stored on the disc. The control unit will automatically generate and append the appropriate Cyclic Check bytes to the record. There are two classes of Write commands; Format Writes and Data Writes. The Format Write commands are used to initialize the recording area; whereas the Data Write commands are the commands used by the ultimate user of the records.

1.4.1 Format Write Commands

After each command is completed, Channel End and DeviceEnd status are presented to the channel and the control unit continues to erase the track operated on. Device End will cause chaining in the channel and subsequent commands in the chain will be received and executed by the subsystem. After the last command in the chain has been responded to by Channel End and Device End, the control unit continues to erase the track until the Index Mark is reached. Note that Device End does not signal the ultimate end of a command as it does on more typical 9000 series subsystems. If the Control Unit should be addressed after Channel End and Device End status have been presented but before the Index Mark is reached, Busy status will be presented to the Channel. When the operation is complete, Control Unit End status will be presented.

1.4.1.1 Write Home Address (0001 1001)

This command causes the Home Address area to be written. The channel must send five bytes of information to the subsystem:

Flag byte (one byte)
Cylinder No. (two bytes)
Head No. (two bytes)

1.4.1.2 Write Track Descriptor Record (0001 0101)

This command causes the TD Record to be written. This record is unique, from the hardware standpoint, in that it is the first record following the Home Address and it is not preceded by an Address Marker.

The Flag Byte and all check bytes are provided by the control unit. The remaining bytes (eight in the Count Area plus Key Area information plus Data Area information) must be provided by the channel. If the channel provides less bytes than are needed, the control unit writes binary zeros so that the Key and Data Areas conform to the lengths specified in the Count Area. However, because R_0 is intended to specify alternate tracks, R_0 will normally have no key Area.

This command must be chained from a Write Home Address, or a Search HA that was equal on all five bytes of the Home Address.

COMMAND REPERTOIRE (continued)1.4.1.3 Write Count, Key and Data (0001 1101)

This command causes records similar to Data Record R₁, to be written. The control unit provides the Address Marker, the Flag Byte, and the necessary Cyclic Check bytes. The Remaining bytes must be supplied by the channel. If the channel provides less bytes than are needed, the control unit pads binary zeros so that the Key and Data Areas conform to the lengths specified in the Count Area.

This command should be chained from a Write TD Record, another Write Count, Key and Data, a Search Equal ID, or Search Equal Key command.

Write Special Count, Key, and Data (0000 0001). See Section on Overflow Records for details.

1.4.2 Data Write Commands1.4.2.1 Write Data (0000 0101)

This command causes data to be obtained from the channel by the control unit and recorded in the Data Area. The length is specified by the Length Byte in the previously recorded Count Area. If the channel does not provide enough data to allow the actual data length to conform to the Data Length byte; the control unit pads the binary zeros necessary to attain conformity.

This command should be chained from a Search Equal ID, or from a Search Equal Key command.

1.4.2.2 Write Key and Data (0000 1101)

This command causes information to be obtained from the channel and recorded in the Key and Data Areas of the record. The lengths are specified by the three Length Bytes in the previously recorded Count Area. If the channel does not provide enough data to allow the actual lengths to conform to the Key and Data Length bytes; the control unit pads binary zeros, as necessary, to attain conformity.

This command should be chained from a Search Equal ID command.

COMMAND REPERTOIRE (continued)1.5 Search Commands

On search operations, the channel operates in a write mode while the device operates in a read mode. These two sources of information are compared by the control unit. The comparison made is device to channel. Thus a 2₁₆ on the disc compared with a 1₁₆ at the channel meets the criterion for a "find" on a Search High command.

The information processed by the control unit is error checked as the search is executed.

If the find is made (and no errors occur) the status bits sent to the channel are: Status Modifier, Channel End, and Device End. (If the Unit Check bit is set, Status Modifier will not be set). If a find is not made, the status bits are: Channel End, and Device End. The presence or absence of Status Modifier thus controls branching within the command chain.

1.5.1 Multiple Track Operation

On all search commands, the "M" (multiple track) bit allows operation within cylinder, rather than head boundaries. If M is zero, head switching does not take place. If M is one, the "Head Register" is incremented by one when the Index Marker is detected. If Head switching has occurred and the search command is repeated; the search will continue on the next head.

The M bit should be set to one with discretion. For example, if M is a one and the Index Marker is detected before an entire track has been searched, the first portion of the first track will be ignored on the search.

Head switching will continue to occur until End-of-Cylinder is detected.

1.5.2 Search Home Address Equal (M011 1001)

This command causes two bytes of Cylinder Number and two bytes of Head Number from the disc to be compared with four bytes of information from the channel. The Flag Byte is not transferred or compared during this command. The comparison made is bit by bit binary. An equal condition is indicated by the presence of the Status Modifier bit in the Status Byte.

1.5.3 Search Identifier Equal (M011 0001)

The term "Identifier" (ID) is introduced to define the five bytes of Cylinder, Head, and Record Number bytes located in the Count Area. The ID to be compared is the ID following the next Address Marker or Index Marker. In the latter case, the comparison is on the TD Record.

COMMAND REPERTOIRE (continued)1.5.4 Search ID High (M101 0001)

This command is similar to the Search ID Equal command except that a find results when the ID on the disc is greater than the information presented by the channel.

1.5.5 Search ID Equal or High (M111 0001)

This command is similar to the other two Search ID commands except that a find is made if the comparison indicates either equal or high.

1.5.6 Search Key

The Search Key commands cause information from the Key Area of the disc to be compared to information from the channel. The key on which comparison is made is:

1. The Key Area of the record following the next Address Marker or;
2. The Key Area of the TD Record, if chaining is from a Search ID that compared on the ID of the TD Record.

The Search Key commands never return a Status Modifier bit if the Key Length of the record examined is zero.

1.5.7 Search Key and Data (these Search commands are associated with the File Scan Feature, F1099-00).

These search commands cause a comparison of both the Key and Data Areas of a record. It is possible to selectively compare any byte(s) in these two areas. The "Inhibit Byte" (a byte of all binary ones) makes the selective comparison possible. If an Inhibit Byte appears in the information coming from the channel (but not the disc); then comparison is not made on the byte coming from the disc that was destined to be compared with the channel byte. By making the first n channel bytes all binary ones (where n is the number of bytes in the Key Area) these search commands can effectively be reduced to "search data." There are no restrictions on the number or placement of Inhibit Bytes. These search commands may be used on records where the Key Area field is nonexistent.

Note that reading of a record, once found, will typically require an additional revolution of the disc.

COMMAND REPERTOIRE (continued)1.6 Read Commands

On all read commands, the control unit reads information from the discs, checks information for errors, strips off the Cyclic Check bytes, and presents the information to the channel.

On all read commands, the M bit allows operation within cylinder, rather than head, boundaries. If M is zero, head switching does not take place. If M is one, the Head Register is incremented by one when the Index Marker is detected. If head switching has occurred, and the read command is repeated; the read will continue on the next head.

Since the TD Record is not preceded by an Address Marker, it cannot be read by this command.

1.6.1 Initial Program Load (M000 0010)

1.6.1.1 Facilities will exist in the central processor to select one device as a source of information for initial loading of a program. Additionally, a switch will exist which will transmit a command code of 0000 0010 to that selected device. The entire system should be "reset" before the IPL command is executed. The M Bit will be ignored and a single record will be read.

1.6.1.2 When this subsystem receives the IPL command, it will:

1. Cause the selected device to move to head zero, cylinder zero.
2. Wait for Index Marker.
3. Skip the following Home Address and TD Record.
4. Present the data portion of record one to the channel. Error checks are similar to those provided for Read Data commands.
5. At the end of record one, Channel End and Device End are presented to the channel.

1.6.2 Overflow Records (Provided by Feature F1098-00)

1.6.2.1 Provisions exist in the control unit so that record lengths can be limited by the cylinder, rather than the head, boundaries.

A portion of an overflow record which is written on one track is called a record segment. The Write Special Count, Key, and Data (0000 0001) command is provided for formatting all segments of an overflow record except the last. The Write Special Count, Key and Data differs from a Write Count, Key, and Data (0001 1101) only in that a one bit is written in bit position one of the Flag Byte.

COMMAND REPERTOIRE (continued)

1.6.2.2 All overflow segments must:

1. Be recorded as the first record following the TD Record except the 1st segment.
2. Not be on a defective track.
3. Not be on an alternate track.
4. Be full track records except the last segment.

The Count Areas in a record pertain to the segment of the record on that track, rather than the aggregate record.

1.6.2.3 A one bit in bit position one of the Flag Byte alters the operation of the following commands:

Read Data
Read Key and Data
Read Count, Key, and Data
Write Data
Write Key and Data

1.6.2.4 After completing the read or write operation on the first segment, the control unit waits for the Index Marker. When the Index Marker is reached, the control unit selects the next sequential head and searches for the first Address Marker on the track. It then processes the Data Area of this segment. The operation continues until a record segment is detected which contains a zero bit in Flag Byte bit position one. At the end of data transfers involving this segment, the operation is terminated.

Operations need not start on the first segment of an overflow record. The first segment to be entered is processed as though it were the first segment.

1.7 Miscellaneous Commands

The following commands cannot be categorized as Seek, Write, Search, Read or Sense. No information other than the command itself is transferred on the I-O channel on any of the commands.

1.7.1 Recalibrate (0001 0011)

The device determines the accessor movement to attain a new cylinder position on the basis of the present accessor position, rather than from a fixed reference. Consequently, it is possible for the accessor to "get lost" after a period of operation; perhaps because of electrical noise. The Recalibrate command is provided to give the device a new absolute reference position to allow continued operation if this situation should arise.

This command causes the device to seek head zero and cylinder zero. Channel End is generated as soon as the positioning information has been forwarded to the device, Device End on completion of Motion Control. This command operates under the constraints imposed by the "seek portion" of the File Mask.

COMMAND REPERTOIRE (continued)1.7.2 No Operation (0000 0011)

This command causes the control unit to respond with Channel End and Device End. The addressed device takes no action.

1.7.3 Space Count (0000 1111)

This command enables the control unit to pass over an unreadable Count Area to gain access to subsequent good records. This command causes the control unit to search for the next Address Marker; when detected, Channel End and Device End are presented to the channel.

1.7.4 Erase (0001 0001)

This command is used to erase to the end of a track after a Track Overrun has occurred. The command causes the track to be erased from the end of the Data Area of the record on which the preceding search was satisfied; or the record just written by Write Count, Key, and Data; to the end of the track. Channel End and Device End are generated when the Index Mark is reached.

1.7.5 Test I-0 (0000 0000)

This command allows the program to interrogate the Status Byte stored in the control unit while inhibiting status from other control units on the same I-0 channel. Receipt of this command will cause the control unit to transmit the content of the eight-bit Status Register (the "register" may be hypothetical in the case of some bits) to the computer. Then, any control logic that would tend to send a Status Byte to the channel will be cleared. The Status Register itself will remain set to allow meaningful observation of the control unit's maintenance panel. The net effect of the command is to report and then clear impending interrupt conditions.

The Test I-0 command does not have a status per se, the Status Byte transferred is the result of a previous command.

1.7.6 Selective Reset and System Reset

These are not commands in the usual sense. The effect produced by either of these conditions is identically the same as if the Master Clear switch on the maintenance panel of the control unit were depressed; all memory elements in the control unit are reset. No status is presented as a result of a Reset.

Any command in progress when the Reset condition was detected is stopped immediately and any information received by the channel as a result of the command should be regarded as invalid.

COMMAND REPERTOIRE (continued)1.8 Sense Commands

1.8.1 When the Unit Check bit in the Status Byte is a one, additional details on the nature of the unusual condition are available in the form of "Sense Bytes". The Sense I-O commands present these bytes, in sequential order, to the channel; the channel may accept as many of the 32 possible bytes as it wishes.

1.8.2 There are three types of Sense I-O commands. The basic command merely causes Sense Bytes to be presented to the interface.

The other two Sense I-O commands are associated with the Dual Access Control Unit Feature. A Sense Reserve command from an I-O channel reserves use of the subsystem for the exclusive use of this channel until a Sense Release command is received at the subsystem. During the time interval between receipt of Sense Reserve and receipt of Sense Release, the alternate channel will receive a "Busy Status" in response to commands. All three Sense commands present Channel End and Device End status upon completion of the command.

The first 6 sense bytes are for the normal error recovery and the remaining 8 sense bytes are for on-line diagnostic and failure finding procedures. The transfer may be limited to the first 6 bytes if the CCW byte count is set to 6 and the incorrect length indicator suppressed.

1.8.3 SENSE bytes, except sense byte 3, indicate conditions which occurred in the control unit and selected device during the previous operation. Sense byte 3 indicates the present device status.

Sense data transfer rate is the same as the read or write data transfer rate.

SENSE bytes 0, 1, 2, and 5 are reset to all zeros during the early part of the initial selection sequence for commands other than TEST I-O and SENSE, if no status is stacked on selected device.

SENSE commands present all zero status at the end of the initial selection sequence even if the selected device is not operable.

1.8.4 SENSE I-O

1.8.4.1 SENSE I-O performs the operations described above.

COMMAND REPERTOIRE (continued)1.8.4.2 SENSE RESERVE

The Sense Reserve command includes all of the functions of the Sense I-0 command, and in addition, causes the control unit to become reserved to the channel issuing the command.

Once the control unit becomes reserved to a channel, it remains reserved until that channel releases the control unit by issuing a Sense Release command or a system reset is performed.

If a Set File Mask command precedes the Sense Reserve command in the same command chain, the Sense Reserve is rejected with Unit Check (Command Reject and Invalid Sequence).

1.8.4.3 SENSE RELEASE

The Sense Release command includes all of the functions of the Sense I-0 command, and in addition, causes the reservation of the control unit to be terminated.

If a Set File Mask command precedes the Sense Release command in the same command chain, the Sense Release command is rejected with Unit Check (Command Reject and Invalid Sequence).

2. STATUS BYTE

- 2.1 Two Status Bytes will typically be presented to the channel during the execution of one command. The first byte (typically all zeros), will be transmitted before data services are requested. The second byte will be transmitted after all data have been operated on and the results checked for validity. No means of suppressing status, other than that required by SU00039 will be provided.

The table below lists the significance of one bits in the Status Byte.

	<u>Bit Position</u>	<u>Description</u>	<u>Interpretation</u>
2.2	0	Attention	Set when power is brought up on attached device.
2.3	1	Status Modifier	<ol style="list-style-type: none"> 1. A search command has been executed and the condition called for by the command has been met. 2. Modifies the Busy status to indicate that the control unit, rather than the device, is busy.
2.4	2	Control Unit End	1. This is, in a sense, an unsolicited status. If an I-O channel requests service and the control unit responds with a Busy Status; then at the next non-busy opportunity, a Control Unit End Status is presented to that same requesting I-O channel.
2.5	3	Busy	<p>If this bit is set, Status Modifier will also be set, indicating that the Control Unit was busy. The Control Unit was busy because:</p> <ol style="list-style-type: none"> 1. A new command was initiated while the control unit was still erasing a track following a Format Write command. 2. On a dual access control unit configuration, the control unit was busy via the other I-O channel. 3. Busy, set without Status Modifier, will indicate Device Busy.
2.6	4	Channel End	Channel End indicates that the Channel-to-Control Unit operation is complete.
2.7	5	Device End	Device End will be presented with Channel End except in the case of a Seek command. Device End, in the case of a Seek, indicates the completion of Motion Control.

STATUS BYTE

	<u>Bit Position</u>	<u>Description</u>	<u>Interpretation</u>
2.8	6	Unit Check	An exceptional condition (but not necessarily an error) was detected. Additional information on this condition is contained in the Sense Bytes.
2.9	7	Unit Exception	<p>This status results from a Data Length of zero in the Count Area of a record; and indicates End-of-File. When this condition is detected, information will be transferred from (or to) a (non-zero length) Key Area but not from (or to) the Data Area. This bit can be set on the following read commands:</p> <ol style="list-style-type: none"> 1. TD Record 2. Count, Key and Data 3. Key and Data 4. Data <p>This bit can be set on the following write commands:</p> <ol style="list-style-type: none"> 1. Key and Data 2. Data

3. SENSE BYTES3.1 Sense Byte 0

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.1.1	Bit 0		<ol style="list-style-type: none"> 1. Invalid Command. 2. Filemask is violated on a write command. 3. Two sets of file mask commands have been received in the same command chain. 4. A command code for a feature that is not installed. 5. A seek command with invalid address. 6. A command which makes an invalid sequence. 7. A seek command with less than 6 bytes of address. 8. Filemask in preceding read IPL in same chain.
3.1.2	Bit 1	Intervention Required	Device addressed is either physically or electrically nonexistent. After this status bit is set the program may try the same command again but not another command without causing other error.
3.1.3	Bit 2	Busout Check	Even parity appears on the output bus for data or command.
3.1.4	Bit 3	Equipment Check	Set by Sense Byte 2.
3.1.5	Bit 4	Data Check	Data error has been detected in the information received by the control unit from the device.
3.1.6	Bit 5	Overrun	<p>The channel did not accept input information rapidly enough to assure the validity of the information.</p> <p>A byte was received too late, during writing, to be properly written. The remaining portion of the record area was filled with binary zero.</p> <p>Chained command was received too late to be properly executed.</p> <p>Overrun stops data transmission to or from the channel.</p>
3.1.7	Bit 6	Track Condition Check	A read, write, or search command was attempted on a track which the flag byte indicates is defective. These commands are permitted, however, on home address and TD record.

SENSE BYTES (continued)Sense Byte 0 (continued)

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.1.7.1	Bit 6 (cont)	<u>DEFECTIVE TRACK</u>	<ol style="list-style-type: none"> 1. Any read or search (except search HA, Read HA, Read RO) is attempted on the track in either multitrack or single track mode. The interrupt occurs prior to transmission of any data to or from the channel. 2. An overflow record being read, written, or searched overflows to a track flagged as defective. The interrupt occurs after the last byte on the previous track has been operated on and before the first byte for the defective track is requested from or to the channel.
3.1.7.2		<u>ALTERNATE TRACK</u>	<ol style="list-style-type: none"> 1. A track condition check is generated when command chaining and multiple track mode signals indicate that operations are to continue on the next higher-order track or the record is not the last segment of an overflow record.
3.1.8	Bit 7	<u>SEEK CHECK</u>	<ol style="list-style-type: none"> 2. Track condition check inhibits the increment head switching. <ol style="list-style-type: none"> 1. Transferred seek address is outside the valid address boundaries of the device. The unused bytes must contain zero. This condition also sets command reject. 2. Less than six bytes of seek address is sent. This also sets command reject. 3. Failure of hardware which results in the access mechanism failing to detent correctly. Mechanism going to either inner or outer stop. This case no command rejects. 4. On multi-track operation, the home address of the track advanced to does not compare with the physical address.

SENSE BYTES (continued)

3.2

Sense Byte 1

Bit

Position DesignationInterpretation

3.2.1

Bit 0 Count Area
Check

Data error in count area. Set data check.

3.2.2

Bit 1 Track Overrun

1. Writing has not been completed by the time the index point is detected.
2. Detected on Write RO, Write C-K-D, Write K-D, Write D, or Space Count.

3.2.3

Bit 2 End of Cylinder

CCW command chain has not been completed, but end of cylinder has been detected.

3.2.4

Bit 3 Invalid Sequence

Invalid Sequence of CCW.

3.2.5

Bit 4 No-Record-Found

1. An index passed condition is turned on whenever an index point is sensed on the device.
2. The index passed condition is turned off whenever the control unit performs a read operation in a HA or Data field area, any write command, a sense command, or any control command.
3. No-record-found condition occurs whenever the control unit senses an index point while performing a single track read or search operation other than Read RO or Read HA and the index passed latch is already on.
4. A no record found condition occurs when an index is sensed while executing a space count command following HA and no address mark is found.
5. A no-record-found condition occurs with missing address mark when neither HA or RO can be found on the track.
6. No-record-found is never set if the multi-track bit in the command is on.

3.2.6

Bit 5 File Protected

Seek, Write, Multi-track Read or Search command was issued that violated the file mask.

3.2.7

Bit 6 Missing Address
Marker

This bit will be accompanied by bit 4 of Sense Byte 0 (Data Check).

1. 2 successive records in which bit 0 of the flag bytes were equal were read from the track; and there was no Index Marker between the 2 records. This is an indication that an Address Marker was missed. The Search ID command will inhibit detection of this condition, making it possible to pass over the missing Address Marker so that the remaining data on the track can be retrieved.
2. 2 index markers were passed without encountering any Address Markers.

3.2.8

Bit 7 Overflow

1. Overflow to a defective track.
2. Overflow from an alternate track.
3. Overflow to file protected bound.
4. Overflow to wrong track.
5. Data check in overflow record other than last record.

SENSE BYTES (continued)

3.3

Sense Byte 2

<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
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3.3.1

Bit 0 Unsafe

This bit is used to indicate that a device malfunction has been detected. Some of these malfunctions are:

More than one head has been selected.
The device is trying to read and write at the same time.
The write gate is Off and write driver is On.
The write gate is On and write driver is Off.
The erase driver is Off and the erase gate is On.
The erase driver is On and the erase gate is Off.
One of the DC file voltages has been lost.

3.3.2

Bits 1,2,3
and 4

Not used: always zero

3.3.3

Bit 5 Unselected Status

This bit indicates that some bit in the file status lines is on without being selected. This indicates a device malfunction of some kind since no bit should be on prior to selection.

3.3.4

Bits 6
and 7

Not used: always zero.

3.4

Sense Byte 3

Sense byte 3 indicates the present status of selected device.

Bit 0	Ready	The device is ready for operation.
Bit 1	On-line	The device is on-line.
Bit 2	Unsafe	The device malfunction has been detected.
Bit 3		Not used: always zero.
Bit 4		Not used: always one.
Bit 5	End of Cylinder	The end-of-cylinder has been detected.
Bit 6		Not used: always zero.
Bit 7	Seek Incomplete	The seek-incomplete condition has been detected.

SENSE BYTES (continued)3.5 Sense Byte 4

This byte is always zero.

3.6 Sense Byte 5

This byte is zero at all times except when overflow incomplete occurs (Byte 1, Bit 7). The codes in byte 5 indicate the type of command being executed when the overflow incomplete occurs. The codes and their meaning when the Unit Check (overflow incomplete sense) interruption occurs are:

<u>Code in Hex.</u>	<u>Meaning</u>
06	A read command was in progress.
05	A write command was in progress.
25	A search key-data-equal command was in progress, and the comparison is equal to this point.
45	A search key-data-high command was in progress, and the comparison is equal to this point.
65	A key-data-high command was in progress, and the comparison is equal to this point.
55	Any search key-data operation was in progress, and the comparison is low; or a search key-data equal was in progress, and the comparison was high.
75	A search key-data high or high-equal command was in progress, and the comparison is high.

See Record Overflow and Continue Scan for the programming usage of Sense byte 5 as command code.

3.7 Sense Bytes 6-31

Sense Bytes 6-31 are for on-line diagnostics and failure finding. A brief description of the sense bytes follows.

<u>Sense Byte Number</u>	<u>Sense Byte Contains the Contents of:</u>
6	Command Register
7	Head Register
8	Track Orientation Register
9	Unit Register
10	Gated Attention Encode
11	Data Length High Register
12	Data Length Low Register
13	Key Length Register
14	Flag Register
15	Mask Register
16	Cyclic Parity High Register

SENSE BYTES (continued)Sense Bytes 6-31 (continued)

<u>Sense Byte Number</u>	<u>Sense Byte Contains the Contents of:</u>
17	Cyclic Parity Low Register
18	File Tag & Binary Counter High
19	Binary Counter Low
20	Cylinder Address Register
21	Status Register
22	File Bus Register
23	Adder Sum
24	Sequence Counter & Program Counter
25	Miscellaneous FF's
26	Queueing Register Stage 1
27	Queueing Register Stage 2
28	Queueing Register Stage 3
29	Data Register
30	X or Y Seek Register
31	Reserved

UNIVAC 9000 SERIES 600 CPM READER AND CONTROL

1. COMMAND REPERTOIRE

The following Command Codes may be issued to the Reader Control by the processor. Any other codes will be rejected and will return a Unit Check Status to the Processor.

P = Odd Parity Bit X = Ignored by Control Unit F = Detail Bit

<u>Bit Position</u>	<u>Command</u>	<u>Interpretation</u>
---------------------	----------------	-----------------------

P01234567

- | | | | |
|-------|------------------------------|----------------------|---|
| 1.1 | PXX000000
or
PXX110000 | Test I-0 | The Reader Control presents a status byte to the Channel. SERVICE OUT from the Channel clears the status. |
| 1.2 | PXX010000 | Set Inhibit Status | This command is processed as a Test I-0 Command. Status will be presented to the Channel and Inhibit Status In will be set. |
| 1.3 | PXX100000 | Reset Inhibit Status | This command is processed as a Test I-0 command. Status will be presented to the Channel and Inhibit Status In will be reset. |
| 1.4 | PXXXX0100 | Sense | The Reader Control transfers from one to three sense bytes to the computer as input data. The first sense byte generally has details about any unusual conditions that occurred during the last operation. The channel can issue an early termination if the transfer of all sensebytes is not desired. |
| 1.4.1 | | | Prior to transmitting the sense data to the Channel, the Control Unit will test the Reader. The results of the test will modify the sense by setting additional flip-flops. The status will not be modified and no sense bits will be reset. Channel End and Device End will signal completion of the Sense Commands. |
| 1.5 | PAXXXF10 | Read | <p>A = 0: Read data from the card and send to the Channel. Advance cards one station. At the completion of the data transfer, the Reader Control presents Status to the Channel.</p> <p>F = 0: Read in translate mode.</p> <p>F = 1: Read in image mode.</p> |

COMMAND REPERTOIRE (continued)

1.5.1 A = 1 } Maintenance mode read. Cards are advanced one station but card data
is not read. Two bytes containing the following sixteen (16) special
diagnostic status bits are sent as input data to the channel for
F = 1 } maintenance purposes.

1.5.2

<u>Data Byte 1</u>	<u>Bit</u>	<u>Diagnostic Designation</u>
	0	Sector A
	1	Sector B
	2	Photocell 13
	3	Pinch Roller
	4	On-Off FF
	5	Feed FF
	6	Go FF
	7	Always 1

1.5.3

<u>Data Byte 2</u>	<u>Bit</u>	<u>Diagnostic Designation</u>
	0	25 ms Delay Flop
	1	11 ms Delay Flop
	2	Counter Bit 7
	3	Counter Bit 2
	4	Brake Peak
	5	Clutch Peak
	6	Clutch Hold
	7	Clutch/Brake Control

1.6 PXXXXXX11 Control No. OP. This code is used for diagnostics.

2. STATUS BYTE

2.1 The Status Byte supplies information pertaining to conditions of the last operation. The Status Byte will be presented to the Channel at the following times:

1. The end of the Initial Selection Sequence.
2. The completion of data transfers on the Read Command.

2.2 The status register will be cleared when the Channel responds to STATUS IN with SERVICE OUT. The following list defines use of the bits in the Status Byte.

<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
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2.3	P	Odd Parity	Parity for Status Byte.
2.4	0	Attention	Set by RUN switch.
2.5	1	Status Modifier	Normally set with the Busy bit to indicate that the Control Unit is busy performing a previously initiated command. Status Modifier will not be set with Busy if a new command is issued to the Control Unit when it is about to initiate an interrupt sequence to present end status from the previous operation.
2.6	2	Control Unit End	Not used. Bit always 0.
2.7	3	Busy	Indicates that the Control Unit cannot accept a Command because of one of the following reasons: a) Control is executing a previously initiated operation. b) Control is holding pending status conditions. NOTE: Condition (a) also presents the Status Modifier bit. Busy can occur only during the Initial Selection Sequence. Busy, due to pending status, will not be set if the command issued in (b) is a Test I-O.
2.7.1	4	Channel End	Channel End indicates the completion of the data transfers between the Control Unit and the Channel or the acceptance of a control command. If Channel End is "stacked," the Control Unit will disconnect and try to present the status when the priority allows. Channel End and Device End are presented together. Following is a list of conditions which will present Channel End. a) The Control Unit will generate Channel End after the 80th column has been read. b) Acceptance of a Control Command.

STATUS BYTE (continued)

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
2.8	5	Device End	Indicates the completion of a command initiated by the Channel and readiness to accept a new command. Device End and Channel End are presented together. In the Card Reader, Device End is presented in the following cases: Same as a) and b) for Channel End above.
2.9	6	Unit Check	One or more bits were set in Sense Byte 1 (bits 0 thru 7) when sampled with the setting of Channel End or Device End. A parity error in the Command Byte, an Invalid Command, or a Unit Abnormal, when tested in the Initial Selection Sequence, has been detected. In these cases, the Unit Check is sent to the Channel during the Initial Selection Sequence. The Reader was found to be non-ready when tested during Initial Selection. The command will be rejected and no end status will be generated. The normal sense bits will be set to indicate the type of error that occurred.
2.10	7	Unit Exception	Not used. Bit always 0.

3. SENSE BYTES

3.1 Sense data provides information about unusual conditions that occurred during the last operation. The sense information will be cleared when the next command is accepted if the command is not a Sense Command or a Test I-0.

3.2 Sense Byte 1

The status of various flip-flops in the Control Unit are transferred to this byte. This byte is used for error recovery routines or for maintenance functions in conjunction with failure finding routines.

Sense Byte 1

	<u>Bit Position</u>	<u>Designation</u>	<u>Interpretation</u>
3.2.1	P	Odd Parity	Parity bit for Sense Byte 1
3.2.2	0	Command Reject	An unspecified command was issued. This bit is suppressed if bad parity is detected during transfer of the command code. Neither Channel End nor Device End is set in the status.
3.2.3	1	Intervention Required	A Reader error, other than Read Check, was detected during the previous operation. The fault may be empty hopper, stacker full, misfeed, read jam, non-ready, or stacker jam.
3.2.4	2	BUS OUT Check	Parity error on the command transfer to the Control Unit. If the Control Unit is not holding pending status, a parity error during the command byte transfer causes immediate termination. Neither Device End nor Channel End will be set in the Status Byte. If the Control Unit is holding pending status, a parity error during the command byte transfer will be ignored. The sequence will be handled as if the Control Unit was holding pending status and the command byte had good parity.
3.2.5	3	Card Jam	A card transport error has occurred. A jam into the pre-read station, into the read station, or into the stacker will light the Feed Check indicator on the Reader Control Panel.
3.2.6	4	Data Check	A mispunched card, improper registration, or read head failure has been detected.
3.2.7	5	Overrun	New data has been read by Reader before SERVICE OUT has been received from the Channel for the data presently stored in the data register.
3.2.8	6	Inhibit Status In	Inhibit Status In is set.
3.2.9	7	Non-Repeat Abnormal	Hopper Empty, Stacker Full, Interlock Error, or Stacker Jam.

SENSE BYTE (continued)3.3 Sense Bytes 2 and 3

The status of various flip-flops in the Control Unit are transferred to these bytes. Sense bytes 2 and 3 are used for maintenance analysis functions in conjunction with failure finding routines.

3.4 Sense Byte 2

<u>Bit Position</u>	<u>Designation</u>
0	Stop
1	Sector A
2	Status Acknowledge
3	Active
4	Read
5	Go
6	All on
7	On-Off FF

3.5 Sense Byte 3

<u>Bit Position</u>	<u>Designation</u>
0	Feed FF
1	Upper Cells Off
2	Lower Cells Off
3	Clutch/Brake Control
4	Initial Write
5	Sprocket C
6	Input to Motor Driver
7	Data Request

SPEC REV	EIR NO.	SHEET		DESCRIPTION OF REVISION (DESCRIBE REVISION IN ONE OF THE FOLLOWING 3 WAYS)			CHG BY	CHK	APPROVAL	DATE
		NO.	REV.	1. ADDED _____	2. DELETED _____	3. CHANGED FROM _____ TO _____				
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SHEET 19 REVISION -

SPECIFICATION SYMBOL
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ROUTINE ESCR 3 XIOFS - ENGINEER'S SPECIAL CONTROL ROUTINE

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** ALTER PARAMETER LOCATIONS BEGINNING IN LOCATION 1F9 AT INITIAL

** LOAD DISPLAY HALT OF 00EE. CLEAR LOCATIONS 1D, 1E, 1F TO FF

ESCR0000
ESCR0010
ESCR0020
ESCR0030
ESCR0040
ESCR0050
* ESCR0060
* ESCR0070
* ESCR0080
* ESCR0090
* ESCR0100
ESCR0110
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** BCW1 ADR SET LOCATION 01FC TO 1 BYTE ADR OF BCW1 FOR C1-MX      ESCR0340
** BCW2 ADR SET LOCATION 01FD TO 1 BYTE ADR OF BCW2 FOR C2-MX      ESCR0350
** BCW3 ADR SET LOCATION 01FE TO 1 BYTE ADR OF BCW3 FOR C3-MX      ESCR0360
**      DA SET LOCATION 1FF TO DEVICE ADDRESS, COMMAND 1          ESCR0370
**      DA SET LOCATION 200 TO DEVICE ADDRESS, COMMAND 2          ESCR0380
**      DA SET LOCATION 201 TO DEVICE ADDRESS, COMMAND 3          ESCR0390
** COMMANDS SET LOCATION 202 TO COMMAND 1                          ESCR0400
**          SET LOCATION 203 TO COMMAND 2                          ESCR0410
**          SET LOCATION 204 TO COMMAND 3                          ESCR0420
**          SET LOCATION 205 TO OPTION SELECTION                    ESCR0430
**      BIT 0 - 0 PHASE          9 TRACK, 1600 BPI                  ESCR0440
**      BIT 0 - 1 NPZI          9 TRACK, 800 BPI                    ESCR0450
**      BIT 1 - 0                DO NOT STOP BEFORE XIOF           ESCR0460
**      BIT 1 - 1                STOP BEFORE XIOF TO ENABLE CYCLING ESCR0470
**      BIT 2 - 0                EXECUTE XIOF IN PM. 40 - 43 = STATUS ESCR0480
**      BIT 2 - 1                EXECUTE XIOF IN IO. TIO FOR STATUS ESCR0490
**      BIT 3 - 0                DO NOT SET SIMULATE MODE          ESCR0500
**      BIT 3 - 1                SET SIMULATE MODE                  ESCR0510
**      BIT 4 - 0                EXECUTE COMMANDS 1,2,3 NORMALLY    ESCR0520
**      BIT 4 - 1                EXECUTE COMMAND 1 - EXECUTE COMMANDS ESCR0530
**                                2 AND 3 ON ERROR. RESUME COMMAND 1 ESCR0540
**      BIT 5 - 0                DO NOT PRINT ON ERROR              ESCR0550
**      BIT 5 - 1                PRINT ON ERROR                      ESCR0560
**      BIT 6 - 0                DO NOT UTILIZE DATA GENERATOR     ESCR0570
**      BIT 6 - 1                UTILIZE DATA GENERATOR            ESCR0580
**      BIT 7 - 0                DO NOT PRINT ON SUCCESSFUL TERM.   ESCR0590
**      BIT 7 - 1                PRINT ON SUCCESSFUL TERMINATION    ESCR0600
** BCWS SET LOCATIONS 206-9 TO BUFFER CONTROL WORD 1 IF MX CHAN.  ESCR0610
**          SET LOCATIONS 20A-D TO BUFFER CONTROL WORD 2 IF MX CHAN. ESCR0620
**          SET LOCATIONS 20E-211 TO BUFFER CONTROL WORD 3 IF MX CHA ESCR0630
** CAWS SET LOCATIONS 218-21F SEL. CHAN, COMMAND WORD 1          ESCR0640
**          SET LOCATIONS 220-227 SEL. CHAN, COMMAND WORD 2        ESCR0650
**          SET LOCATIONS 228-22F SEL. CHAN, COMMAND WORD 3        ESCR0660
** DATA SET LOCATIONS 230-237 TO DESIRED DATA PATTERN AND SET  ESCR0670
**          OPT - BIT 6 TO 1                                         ESCR0680

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0071 01F9 07
 0072 01FA 07
 0073 01FB 07
 0074 01FC 70
 0075 01FD 70
 0076 01FE 70
 0077 01FF E0
 0078 0200 E0
 0079 0201 E0
 0080 0202 012702
 0081 0205 00
 0082 0206 0040
 0083 0208 1000
 0084 020A 0040
 0085 020C 2000
 0086 020E 0040
 0087 0210 3000
 0088 0212 021A
 0089 0214 0222
 0090 0216 022A
 0091 0218 0100100010000040
 0092 0220 0100200010000040
 0093 0228 0100300010000040
 0094 1000
 0095 2000
 0096 3000
 0097 0230 FFA9FF81D7A9FFA9
 0098 0238 4412443A6C124412
 0099 0240 0100
 0100
 0101
 0102 0242 0000
 0103 0244 0005
 0104 0246 0260
 0105 0248 0005

TM1 DC X'07'
 TM2 DC X'07'
 TM3 DC X'07'
 MBC1 DC X'70'
 MBC2 DC X'70'
 MBC3 DC X'70'
 DA00 DC X'E0'
 DA01 DC X'E0'
 DA02 DC X'E0'
 C123 DC X'012702'
 OPT DC X'00'
 BCW1 DC X'0040'
 DC Y(DAT1)
 BCW2 DC X'0040'
 DC Y(DAT2)
 BCW3 DC X'0040'
 DC Y(DAT3)
 CCW1 DC Y(CW1+2)
 CCW2 DC Y(CW2+2)
 CCW3 DC Y(CW3+2)
 CW1 DC X'0100100010000040'
 CW2 DC X'0100200010000040'
 CW3 DC X'0100300010000040'
 DAT1 EQU X'1000'
 DAT2 EQU X'2000'
 DAT3 EQU X'3000'
 DATA DC X'FFA9FF81D7A9FFA9'
 DC X'4412443A6C124412'
 RDT DC X'0100'
 *
 *
 IR8 DC X'0000'
 BCW4 DC X'0005'
 DC Y(NSNS)
 BCW5 DC X'0005'

TEST MASK FOR 2 INTS - DEVICE 1 ESCR0690
 TEST MASK FOR 2 INTS - DEVICE 2 ESCR0700
 TEST MASK FOR 2 INTS - DEVICE 3 ESCR0710
 BCW1 ADDRESS ESCR0720
 BCW3 ADDRESS ESCR0730
 BCW3 ADDRESS ESCR0740
 DEVICE ADDRESS - COMMAND 1 ESCR0750
 DEVICE ADDRESS - COMMAND 2 ESCR0760
 DEVICE ADDRESS - COMMAND 3 ESCR0770
 COMMAND SELECTION (3) ESCR0780
 OPTION SELECTION ESCR0790
 64(10) = BYTE COUNT ESCR0800
 DATA ADDRESS = 1000(16) ESCR0810
 64(10) = BYTE COUNT ESCR0820
 DATA ADDRESS = 2000(16) ESCR0830
 64(10) = BYTE COUNT ESCR0840
 DATA ADDRESS = 3000(16) ESCR0850
 ESCR0860
 ESCR0870
 ESCR0880
 ESCR0890
 ESCR0900
 ESCR0910
 ESCR0920
 ESCR0930
 ESCR0940
 ESCR0950
 ESCR0960
 ESCR0970
 ESCR0980
 ESCR0990
 ESCR1000
 ESCR1010
 ESCR1020
 ESCR1030

0106 024A 026D
 0107 024C 0250
 0108 024E 0000
 0109 0250 0268
 0110 0252 10000005
 0111 0256 025A
 0112 0258 0000
 0113 025A 026D
 0114 025C 10000005
 0115 0260 FFFFFFFFFFFFFFFF
 0116 0268
 0117 026D
 0118 0272 0001
 0119 0274 0100
 0120 0276 3010
 0121
 0122 0278 0201058A000E0
 0123 027E 020105C6000E0
 0124 0284 91200205
 0125 0288 47100290
 0126 028C 47F00380
 0127 0290 020108B4000E2
 0128 0296 47F00380
 0129 029A 470005E0
 0130 029E 92F00290
 0131 02A2 920C000C0
 0132 02A6 47F00950
 0133 02AA 47000000
 0134 02AE 92F002A0
 0135 02B2 920C000C0
 0136 02B6 47F00950
 0137 02BA 020710000230
 0138 02C0 91000205
 0139 02C4 471002EA
 0140 02C8 02FF10001000

DC Y(MSNS)
 CCW4 DC Y(**4)
 CW4 DC X'0000'
 DC Y(NSNS)
 DC X'10000005'
 CCW5 DC Y(**4)
 CW5 DC X'0000'
 DC Y(MSNS)
 DC X'10000005'
 FF DC X'FFFFFFFFFFFFFFF'
 NSNS DS 1CL5
 MSNS DS 1CL5
 D1 DC X'0001'
 D256 DC X'0100'
 DLIM DC X'3010'
 **
 SCPO MVC HPR5-2(2),YCP
 MVC INT2+0(2),YCP
 TM OPT,X'20'
 BC 1,**+8
 BC 15,TB2-4
 MVC RIOM+2(2),YCP+2
 BC 15,TB2-4
 SPSP BC 0,SPM
 MVI SPSP+1,X'F0'
 MVI IS+2,X'0C'
 BC 15,P*PR
 SPSI BC 0,0(,0)
 MVI SPSI+1,X'F0'
 MVI IS+2,X'0C'
 BC 15,P*PR
 DGEN MVC DAT1(8),DATA
 TM OPT,X'00'
 BC 1,D48K
 MVC DAT1+8(256),DAT1

NORMAL SENSE COMMAND WORD - SEL

MONITOR SENSE COMMAND WORD - SEL

PRESET INSTRUCTIONS

SUCCESSFUL COMMAND COMPLETION, PRNT

RESET CHANNEL END, DEVICE END STATUS

RESET CHANNEL END, DEVICE END STATUS

IF OPT - BIT 4 IS SET, GENERATE
8 K OF DATA FOR WRITE

ESCR1040
 ESCR1050
 ESCR1060
 ESCR1070
 ESCR1080
 ESCR1090
 ESCR1100
 ESCR1110
 ESCR1120
 ESCR1130
 ESCR1140
 ESCR1150
 ESCR1160
 ESCR1170
 ESCR1180
 ESCR1190
 ESCR1200
 ESCR1210
 ESCR1220
 ESCR1230
 ESCR1240
 ESCR1250
 ESCR1260
 ESCR1270
 ESCR1280
 ESCR1290
 ESCR1300
 ESCR1310
 ESCR1320
 ESCR1330
 ESCR1340
 ESCR1350
 ESCR1360
 ESCR1370
 ESCR1380

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0141	02CE D20720000230	MVC	DAT2(8),DATA	E5CR1390
0142	02D4 D2FF20002000	MVC	DAT2+8(256),DAT2	E5CR1400
0143	02DA D20730000230	MVC	DAT3(8),DATA	E5CR1410
0144	02E0 D2FF30003000	MVC	DAT3+8(256),DAT3	E5CR1420
0145	02E6 47F00308	BC	15, TB2+4	E5CR1430
0146	02EA 48F00208	LH	15, BCW1+2	E5CR1440
0147	02EE D207F0000230	MVC	8(8,15),DATA+8	E5CR1450
0148	02F4 AAF00894	AH	15, D16	E5CR1460
0149	02F8 D2FFF0001000	MVC	8(256,15),DAT1	E5CR1470
0150	02FE AAF00274	AH	15, D256	E5CR1480
0151	0302 49F00276	CH	15, DLIM	E5CR1490
0152	0306 47800308	BC	8, TB2+4	E5CR1500
0153	030A 47F002F8	BC	15, CGD	E5CR1510
0154	030E 92480541	MVI	XI0+3, X'4B'	E5CR1520
0155	0312 D2010078024C	MVC	X'78'(2), CCW4	E5CR1530
0156	0318 4580052E	BAL	8, XI0-16	E5CR1540
0157	031C 47F0041A	BC	15, SPC	E5CR1550
0158	0320 D2048CB10E20	MVC	S0+35(5), NESI	E5CR1560
0159	0326 D2090D0060E25	MVC	S0+120(10), NESI+5	E5CR1570
0160	032C D2090D150E2F	MVC	S0+135(10), NESI+15	E5CR1580
0161	0332 D2590DC40E39	MVC	M0+110(90), NESI+25	E5CR1590
0162	0338 92CB0541	MVI	XI0+3, X'CB'	E5CR1600
0163	033C D2010078024C	MVC	X'78'(2), CCW4	E5CR1610
0164	0342 4580052E	BAL	8, XI0-16	E5CR1620
0165	0346 47F003F0	BC	15, MS	E5CR1630
0166	034A A86008D8	LPSC	PSC6, X'60'	E5CR1640
0167	034E D201051A08C0	MVC	XI0F+4(2), LIM1+2	E5CR1650
0168	0354 920003ED	MVI	CLSW+1, 0	E5CR1660
0169	0358 9200040B	MVI	SPC-15, 0	E5CR1670
0170	035C D201031E0C8C	MVC	SNRZ-2(2), ARSM+2	E5CR1680
0171	0362 928C08C8	MVI	IS+2, X'0C'	E5CR1690
0172	0366 D20004C501FC	MVC	MX1+9(1), MBC1	E5CR1700
0173	036C D20004D501FD	MVC	MX2+9(1), MBC2	E5CR1710
0174	0372 D20004E501FE	MVC	MX3+9(1), MBC3	E5CR1720
0175	0378 91010205	TM	OPT, 1	E5CR1730

D48K

CGD

SIMU

SNRZ

NRZI

CKPC

CONTINUE GENERATING DATA
SET SIMULATE MODE COMMAND

EXECUTE SIMULATE MODE COMMAND

CORRECT SENSE TABLE FOR NRZI

9 TRACK, NRZI, 800 BPI MODE SET

EXECUTE MODE COMMAND

SET IO TO INDICATE UNSOLICITED INT.

RESETS TO COMMAND 1

RESET STRT LOOP

RESET SIMULATE AND NRZI SWITCHES

RESET CE, DE FOR GENERAL CLEAR, STRT

SET ADDRESS OF BCW, COMMAND 1

SET ADDRESS OF BCW, COMMAND 2

SET ADDRESS OF BCW, COMMAND 3

PRINT ON SUCCESSFUL COMPLETION

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0176	037C	47100276	BC	1,SCPO	OF COMMAND ?	ESCR1740
0177	0380	91020205	TM	OPT,X'02'	DATA GENERATOR REQUESTED	ESCR1750
0178	0364	471002BA	BC	1,DGEN		ESCR1760
0179	0308	91200205	TM	OPT,X'20'	PM OR IO MODE FOR XIOF?	ESCR1770
0180	038C	4710067A	BC	1,EXIO		ESCR1780
0181	0390	91000205	TM	OPT,X'08'	IS SPECIAL ERROR RECOVERY DESIRED	ESCR1790
0182	0394	47100836	BC	1,RCVY		ESCR1800
0183	0398	48A008E4	LH	10,LDA		ESCR1810
0184	039C	D20902680267	MVC	NSNS(10),NSNS-1	CLEAR SENSE INFORMATION	ESCR1820
0185	03A2	D205007A0260	MVC	X'7A'(6),FF	CLEAR SEL CHANNEL CAW	ESCR1830
0186	03A8	D20300400260	MVC	X'40'(4),FF	CLEAR INT. LOCATIONS	ESCR1840
0187	03AE	92FF08CA	MVI	DS,X'FF'	CLEAR DS	ESCR1850
0188	03B2	D2000693A006	MVC	TI01+1(1),6(10)	SET DA IN TI01	ESCR1860
0189	03B8	D20006DFA006	MVC	TI02+1(1),6(10)	SET DA IN TI02	ESCR1870
0190	03BE	D200053FA006	MVC	XI0+1(1),6(10)	SET DA IN XIOF	ESCR1880
0191	03C4	D20008C9A006	MVC	IS+3(1),6(10)	SET DA IN STATUS COMPARE AREA	ESCR1890
0192	03CA	D20007A5A003	MVC	MXS+3(1),3(10)	SET BCW ADDRESS IN SENSE CONTROLS	ESCR1900
0193	0300	D20007F9A003	MVC	SELS-7(1),3(10)		ESCR1910
0194	03D6	D2000AFFA003	MVC	EMX+5(1),3(10)	SET BCW ADDRESS FOR EDITING ON PRINT	ESCR1920
0195	03DC	D200057BA000	MVC	HPR5-17(1),8(10)	SET TM CONTROL FOR PM	ESCR1930
0196	03E2	D20006ABA000	MVC	SDS+1(1),0(10)	SET TM CONTROL FOR IO	ESCR1940
0197	03E8	AAA00272	AH	10,D1		ESCR1950
0198	03EC	4700F000	BC	0,0(,15)		ESCR1960
0199	03F0	9180A005	TM	5(10),X'80'	DA INDICATES SHARED MX CHANNEL?	ESCR1970
0200	03F4	471004BC	BC	1,MX1		ESCR1980
0201	03F8	9120A005	TM	5(10),X'20'	DA INDICATES MX OR SEL CHANNEL?	ESCR1990
0202	03FC	478004BC	BC	8,MX1		ESCR2000
0203	0400	D20008C6A005	MVC	IS(1),5(10)	SET IS TO CORRECT SEL CHAN VALUE	ESCR2010
0204	0406	920008C7	MVI	IS+1,0	SET IS + 1 TO CORRECT SEL CHAN VALUE	ESCR2020
0205	040A	47000422	BC	0,SPC+0	SKIP SIMULATE AND NRZI	ESCR2030
0206	040E	92F00400	MVI	*-3,X'F0'		ESCR2040
0207	0412	91100205	TM	OPT,X'10'	IS SIMULATION INDICATED	ESCR2050
0208	0416	4710030E	BC	1,SIMU		ESCR2060
0209	041A	91800205	TM	OPT,X'80'	PHASE OR NRZI	ESCR2070
0210	041E	47100320	BC	1,SNRZ		ESCR2080

TB2

STRT

CLSW

MS

SPC

0211	0422	D20100780212		MVC	X'78'(2),CCW1	SET CAW TO COMMAND WORD 1	E5CR2090
0212	0428	45800516		BAL	8,XIOF	EXECUTE COMMAND 1	E5CR2100
0213	042C	A90000C1	HPR1	HPR	X'00C1'	COMMAND 1 EXECUTED - SEL. CHANNEL	E5CR2110
0214	0430	9247042C		MVI	HPR1,X'47'	RESET HALT AT COMMAND 1	E5CR2120
0215	0434	47000390		BC	0,STRT-4		E5CR2130
0216	0430	9180A006		TM	6(10),X'00'	DA INDICATES SHARED MX CHANNEL?	E5CR2140
0217	043C	471004CC		BC	1,MX2		E5CR2150
0218	0440	9120A006		TM	6(10),X'20'	DA INDICATES MX OR SEL CHANNEL?	E5CR2160
0219	0444	478004CC		BC	0,MX2		E5CR2170
0220	0440	D20000C6A006		MVC	IS(1),6(10)	SET IS TO CORRECT SEL CHAN VALUE	E5CR2180
0221	044E	920000C7		MVI	IS+1,0	SET IS + 1 TO CORRECT SEL CHAN VALUE	E5CR2190
0222	0452	D20100780214		MVC	X'78'(2),CCW2	SET CAW TO COMMAND WORD 2	E5CR2200
0223	0458	92F003ED	SEL2	MVI	CLSW+1,X'F0'	SET CLSW SWITCH	E5CR2210
0224	045C	92000521		MVI	XIOF+11,0		E5CR2220
0225	0460	45F0039C		BAL	15,STRT	PRESET CONDITIONS	E5CR2230
0226	0464	920000B5		MVI	RIOM+3,0	SWITCH FOR RESETTING OPT BIT 4 TO C1	E5CR2240
0227	0468	91000205		TM	OPT,X'00'		E5CR2250
0228	046C	471004EC		BC	1,SRC2		E5CR2260
0229	0470	45800516		BAL	0,XIOF	EXECUTE COMMAND 2	E5CR2270
0230	0474	A90000C2	HPR2	HPR	X'00C2'	COMMAND 2 EXECUTED - SEL. CHANNEL	E5CR2280
0231	0478	92470474		MVI	HPR2,X'47'	RESET HALT AT COMMAND 2	E5CR2290
0232	047C	9180A006		TM	6(10),X'00'	DA INDICATES SHARED MX CHANNEL?	E5CR2300
0233	0480	471004DC		BC	1,MX3		E5CR2310
0234	0484	9120A006		TM	6(10),X'20'	DA INDICATES MX OR SEL CHANNEL?	E5CR2320
0235	0488	478004DC		BC	0,MX3		E5CR2330
0236	048C	D20000C6A006		MVC	IS(1),6(10)	SET IS TO CORRECT SEL CHAN VALUE	E5CR2340
0237	0492	920000C7		MVI	IS+1,0	SET IS + 1 TO CORRECT SEL CHAN VALUE	E5CR2350
0238	0496	D20100780216		MVC	X'78'(2),CCW3	SET CAW TO COMMAND WORD 3	E5CR2360
0239	049C	45F0039C	SEL3	BAL	15,STRT	PRESET CONDITIONS	E5CR2370
0240	04A0	45800516		BAL	0,XIOF	EXECUTE COMMAND 3	E5CR2380
0241	04A4	A90000C3	HPR3	HPR	X'00C3'	COMMAND 3 EXECUTED - SEL. CHANNEL	E5CR2390
0242	04A8	924704A4		MVI	HPR3,X'47'	RESET HALT AT COMMAND 3	E5CR2400
0243	04AC	45F00390		BAL	15,STRT-4	PRESET CONDITIONS	E5CR2410
0244	04B0	91800205		TM	OPT,X'00'		E5CR2420
0245	04B4	471004F4		BC	1,SRC1		E5CR2430

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0246	0408 47F003F0		BC	15,MS	REPEAT	E5CR2440
0247	04BC D20108C60260	MX1	MVC	IS(2),FF	SET IS,IS+1 TO CORRECT MX CHAN VALUE	E5CR2450
0248	04C2 D20300700206		MVC	X'70'(4),BCW1	SET BCW1	E5CR2460
0249	04C8 47F0040A		BC	15,SPC-16		E5CR2470
0250	04CC D20108C60260	MX2	MVC	IS(2),FF	SET IS,IS+1 TO CORRECT MX CHAN VALUE	E5CR2480
0251	04D2 D2030070020A		MVC	X'70'(4),BCW2	SET BCW2	E5CR2490
0252	04D8 47F00458		BC	15,SEL2		E5CR2500
0253	04DC D20108C60260	MX3	MVC	IS(2),FF	SET IS,IS+1 TO CORRECT MX CHAN VALUE	E5CR2510
0254	04E2 D2030070020E		MVC	X'70'(4),BCW3	SET BCW3	E5CR2520
0255	04E8 47F0049C		BC	15,SEL3		E5CR2530
0256	04EC A601051A	SRC2	AI	XIOF+4,1		E5CR2540
0257	04F0 47F00470		BC	15,HPR2=4		E5CR2550
0258	04F4 92F00521	SRC1	MVI	XIOF+11,X'F0'		E5CR2560
0259	04F8 47F003F0		BC	15,MS	REPEAT	E5CR2570
0260	04FC D201051A00C0	RC	MVC	XIOF+4(2),LIM1+2		E5CR2580
0261	0502 47F0052E		BC	15,XIO-16		E5CR2590
0262		*				E5CR2600
0263		***	ISSUE	START INPUT-OUTPUT COMMAND, CHECKING FOR ACCEPTANCE	***	E5CR2610
0264	0506 A8500512		LPSC	YIOU-2,X'50'		E5CR2620
0265	050A A8600808	IOUI	LPSC	PSC6,X'60'	IO MODE UNSOLICITED INTERRUPTS	E5CR2630
0266	050E 47F0050E		BC	15,*		E5CR2640
0267	0512 0000		DC	X'0000'		E5CR2650
0268	0514 050E	YIOU	DC	Y(IOUI+4)		E5CR2660
0269	0516 D20005410202	XIOF	MVC	XIO+3(1),C123	SET UP COMMAND	E5CR2670
0270	051C A601051A		AI	XIOF+4,1		E5CR2680
0271	0520 470004FC		BC	0,RC		E5CR2690
0272	0524 D501051A00BE		CLC	XIOF+4(2),LIM1		E5CR2700
0273	052A 478004FC		BC	8,RC	RESET TO FIRST COMMAND	E5CR2710
0274	052E A86008BA		LPSC	PSC1,X'60'	SET IO INT. RETURN. STAY IN PM	E5CR2720
0275	0532 91400205		TM	OPT,X'40'	CHECK TO SEE IF HALT BEFORE XIOF	E5CR2730
0276	0536 4780053E		BC	8,XIO	IS DESIRED	E5CR2740
0277	053A A900053A		HPR	*	HALT BEFORE XIOF	E5CR2750
0278	053E A4E00001	XIO	XIOF	1,X'E0'	XIOF COMMAND EXECUTION	E5CR2760
0279	0542 4780054E		BC	8,**+12		E5CR2770
0280	0546 A9000540	HPR4	HPR	*	COMMAND NOT ACCEPTED	E5CR2780

0281	054A 47F0054A		BC	15,*	RECOVERY SWITCH	ESCR2790
0282	054E 47F0054E	LOOP	BC	15,*	WAIT FOR INTERRUPT - PM SET	ESCR2800
0283		**	BC	15,TIO1	BRANCH TO TIO - IO SET	ESCR2810
0284	0552 47F0054E		BC	15,LOOP		ESCR2820
0285		*				ESCR2830
0286		***		ANALYZE STATUS GENERATED BY PROCESSOR MODE INTERRUPTS		*** ESCR2840
0287	0556 D50100020736	INT	CLC	X'02'(2),YXIO		ESCR2850
0288	055C 4740072E		BC	4,HPRA		ESCR2860
0289	0560 D50100020738		CLC	X'02'(2),YXIO+2		ESCR2870
0290	0566 47C005EE		BC	12,UINT		ESCR2880
0291	056A 91800042		TM	X'42',X'80'		ESCR2890
0292	056E 471005EE		BC	1,UINT	HANDLE AS UNSOLICITED INTERRUPT	ESCR2900
0293	0572 9503053F		CLI	XIO+1,3	INTERNAL DEVICE STATUS EXPECTED?	ESCR2910
0294	0576 47C00508		BC	12,ES00		ESCR2920
0295	057A 91070541		TM	XIO+3,X'87'	COMMAND EXPECTS 2 INTERRUPTS	ESCR2930
0296	057E 47100598		BC	1,IN22		ESCR2940
0297	0582 D503004008C6		CLC	X'40'(4),IS	COMPARE STATUS	ESCR2950
0298	0588 478005E0		BC	8,SPM	COMMAND IS COMPLETED SUCCESSFULLY	ESCR2960
0299	058C A900058C	HPR5	HPR	*	COMMAND WAS IN ERROR. CK 40 THRU 43	ESCR2970
0300	0590 47F0084C		BC	15,GRPM		ESCR2980
0301	0594 47F00594		BC	15,*	RECOVERY SWITCH	ESCR2990
0302	0598 920008C8	IN22	MVI	IS+2,X'00'	SET UP CE STATUS COMPARE	ESCR3000
0303	059C D503004008C6		CLC	X'40'(4),IS	COMPARE CE STATUS	ESCR3010
0304	05A2 47800586		BC	8,L4DE	CHANNEL END STATUS OK. LOOK FOR DE	ESCR3020
0305	05A6 920C08C8		MVI	IS+2,X'0C'	RESET STATUS TO EXPECT CE,DE	ESCR3030
0306	05AA A90005AA	HPR6	HPR	*	CE STATUS EXPECTED. CK 40 THRU 43	ESCR3040
0307	05AE 47F0084C		BC	15,GRPM		ESCR3050
0308	05B2 47F005B2		BC	15,*	RECOVERY SWITCH	ESCR3060
0309	05B6 920408C8	L4DE	MVI	IS+2,X'04'	SET UP DE STATUS COMPARE	ESCR3070
0310	05BA A84008C2		LPSC	PSC2,X'40'	SET PM TO LOOP WAITING FOR 2ND INT.	ESCR3080
0311	05BE D503004008C6	INT2	CLC	X'40'(4),IS	COMPARE DE STATUS	ESCR3090
0312	05C4 478005E0		BC	8,SPM	COMMAND IS COMPLETED SUCCESSFULLY	ESCR3100
0313	05C8 920C08C8		MVI	IS+2,X'0C'	RESET STATUS TO EXPECT CE,DE	ESCR3110
0314	05CC A90005CC	HPR7	HPR	*	DE STATUS EXPECTED. CK 40 THRU 43	ESCR3120
0315	05D0 47F0084C		BC	15,GRPM		ESCR3130

0316	0504 47F005D4		BC	15,*	RECOVERY SWITCH	ESCR3140
0317	0508 920008C8	ES00	MVI	IS+2,0	SET EXPECTED STATUS TO 00 AND LOOK	ESCR3150
0318	050C 47F00582		BC	15,HPR5-10	FOR ONLY ONE INTERRUPT	ESCR3160
0319	05E0 920C08C8	SPM	MVI	IS+2,X'0C'	RESET CHANNEL END, DEVICE END STATUS	ESCR3170
0320	05E4 0202001D0260		MVC	X'10'(3),FF	CLEAR MX CHAN ERROR LOCATIONS	ESCR3180
0321	05EA A84008CC		LPSC	PSC3,X'40'	SET PM	ESCR3190
0322	05EE D50100020780	UINT	CLC	2(2),YPR1+4	DETERMINE PRINTER SITUATION	ESCR3200
0323	05F4 47200616		BC	2,NPHI		ESCR3210
0324	05F8 D50100020784		CLC	2(2),YPR1		ESCR3220
0325	05FE 47400616		BC	4,NPHI		ESCR3230
0326	0602 D50100020786		CLC	2(2),YPR1+2		ESCR3240
0327	0608 4780075C		BC	8,PXHI		ESCR3250
0328	060C D20109140780	PRIU	MVC	PEXT+2(2),YPRI	PRINTER IS IN USE	ESCR3260
0329	0612 A8700000		LPSC	0,X'70'	RETURN TO PROCESS AT INT POINT, IO	ESCR3270
0330	0616 D2830ED00000	NPHI	MVC	SPA(132),X'80'	STORE PRINTER AREA	ESCR3280
0331	061C 45C00942		BAL	12,CPAR		ESCR3290
0332	0620 D21700000EB1		MVC	X'80'(24),EUI	EDIT UNSOLICITED INTERRUPT	ESCR3300
0333	0626 45C00B6E		BAL	12,EDS	EDIT DEVICE STATUS	ESCR3310
0334	062A 45C008E6		BAL	12,PRNT		ESCR3320
0335	062E D28300000ED8		MVC	X'80'(132),SPA	RESTORE PRINTER AREA	ESCR3330
0336	0634 9180053F		TM	XI0+1,X'80'	DA INDICATES SHARED MX CHANNEL?	ESCR3340
0337	0638 4710076E		BC	1,R401		ESCR3350
0338	063C 9120053F		TM	XI0+1,X'20'	DA INDICATES MX OR SEL CHANNEL?	ESCR3360
0339	0640 4760076E		BC	8,R401		ESCR3370
0340	0644 A9000644		HPR	*	IO STILL SET. UNEXPECTED INTERRUPT	ESCR3380
0341		*			OR PREVIOUS LPSC DID NOT WORK	ESCR3390
0342	0648 D50100020514	DRET	CLC	X'02'(2),YIOU		ESCR3400
0343	064E 4780053E		BC	8,XIO		ESCR3410
0344	0652 D50100020736		CLC	X'02'(2),YXIO		ESCR3420
0345	0658 47400672		BC	4,UIRT-4		ESCR3430
0346	065C D5010002073A		CLC	X'02'(2),YXIO+4		ESCR3440
0347	0662 47200672		BC	2,UIRT-4		ESCR3450
0348	0666 A86008BA		LPSC	PSC1,X'60'	SET IO INT RETURN TO INT. SET PM.	ESCR3460
0349	066A A900066A		HPR	*	PREVIOUS LPSC DID NOT SWITCH TO PM.	ESCR3470
0350		*			IF INTERRUPTED, CONTROL DID NOT GO	ESCR3480

#351
 #352 #66E 47F#0644
 #353 #672 470#0672
 #354 #676 A86#08D8
 #355
 #356
 #357
 #358
 #359 #67A D2#1052E#08DC
 #360 #680 D2#10550#08DE
 #361 #686 A87#08D4
 #362 #68A A9#0868A
 #363 #68E 47F#068E
 #364 #692 A5E#08CA
 #365 #696 472#0692
 #366 #69A 474#078E
 #367 #69E A9#0869E
 #368 #6A2 47F#086C
 #369 #6A6 47F#06A6
 #370 #6AA 91#07541
 #371 #6AE 471#06C6
 #372 #6B2 95#0C#08CA
 #373 #6B6 478#08B2
 #374 #6BA A9#0868A
 #375 #6BE 47F#086C
 #376 #6C2 47F#06C2
 #377 #6C6 95#08#08CA
 #378 #6CA 478#06DE
 #379 #6CE 92#0C#08C8
 #380 #6D2 A9#08#06D2
 #381 #6D6 47F#086C
 #382 #6DA 47F#06DA
 #383 #6DE A5E#08CB
 #384 #6E2 474#06F6
 #385 #6E6 92#0C#08C8

* LOCATION INT. ESCR3490
 BC 15,DRET=4 ESCR3500
 BC #,* RECOVERY SWITCH ESCR3510
 UIRT LPSC PSC6,X'60' LOAD IO PSC TO EXPECT OTHER ESCR3520
 * UNSOLICITED INTERRUPTS. RETURN TO PM AT POINT OF LAST INTERRUPT * ESCR3530
 * ESCR3540
 *** ANALYZE INHIBITED STATUS GENERATED BY XIOFS AND UNSOLICITED *** ESCR3550
 *** INTERRUPT CONDITIONS. *** ESCR3560
 EXIO MVC XIO-16(2),IOC SET UP FOR IO MODE ESCR3570
 MVC LOOP+2(2),IOC+2 ESCR3580
 LPSC PSC5,X'70' SET IO MODE ESCR3590
 HPR * IO MODE NOT SET ESCR3600
 BC 15,* RECOVERY SWITCH ESCR3610
 TIO1 TIO DS,X'E0' ESCR3620
 BC 2,TIO1 LOOP ON TIO TILL BUSY STATUS DROPS ESCR3630
 BC 4,SDSC NON-ZERO STATUS IS STORED ESCR3640
 HPR * BUSY STATUS IS FOLLOWED BY ZERO DS ESCR3650
 BC 15,GRI0 RECOVERY SWITCH ESCR3660
 BC 15,* RECOVERY SWITCH ESCR3670
 SDS TM XIO+3,X'07' COMMAND EXPECTS 2 INTERRUPTS? ESCR3680
 BC 1,HPR#+12 ESCR3690
 CLI DS,X'0C' COMPARE CE DE STATUS ESCR3700
 BC 8,RIOM ESCR3710
 HPR8 HPR * COMMAND STATUS NOT CE,DE. CK LOC DS ESCR3720
 BC 15,GRI0 ESCR3730
 BC 15,* RECOVERY SWITCH ESCR3740
 CLI DS,X'08' COMPARE CE STATUS ESCR3750
 BC 8,*+20 ESCR3760
 MVI IS+2,X'0C' RESET STATUS TO EXPECT CE,DE ESCR3770
 HPR * BUSY STATUS IS FOLLOWED BY NO CE ESCR3780
 BC 15,GRI0 ESCR3790
 BC 15,* RECOVERY SWITCH ESCR3800
 TIO2 TIO DS+1,X'E0' THIS 2ND TIO SHOULD STORE DE STATUS ESCR3810
 BC 4,*+20 ESCR3820
 MVI IS+2,X'0C' RESET STATUS TO EXPECT CE,DE ESCR3830

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0386	06EA A90006EA	HPR	*	CC NOT #1 ON 2ND TIO FOR DE STATUS	ESCR3840	
0387	06EE 47F0086C	BC	15,GRIO		ESCR3850	
0388	06F2 47F006F2	BC	15,*	RECOVERY SWITCH	ESCR3860	
0389	06F6 950408CB	CLI	DS+1,X'04'	COMPARE DE STATUS	ESCR3870	
0390	06FA 478008B2	BC	8,RIOM		ESCR3880	
0391	06FE 920C08C8	MVI	IS+2,X'0C'	RESET STATUS TO EXPECT CE,DE	ESCR3890	
0392	0702 A9000702	HPR	*	DS+1 NOT DE STATUS	ESCR3900	
0393	0706 47F0086C	BC	15,GRIO		ESCR3910	
0394	070A 47F0070A	BC	15,*	RECOVERY SWITCH	ESCR3920	
0395	070E 9503053F	SDSC	CLI	XI0+1,3	INTERNAL DEVICE STATUS EXPECTED?	ESCR3930
0396	0712 47C0071A	BC	12,CDS0		ESCR3940	
0397	0716 47F006AA	BC	15,SDS		ESCR3950	
0398	071A 95F008CA	CDS0	CLI	DS,X'FB'	COMPARE STATUS(INTERNAL DEVICE) TO 0	ESCR3960
0399	071E 478008B2	BC	8,RIOM		OR BIT 5(INTERRUPT REQUEST PENDING)	ESCR3970
0400	0722 A9000722	HPR9	HPR	*	COMMAND STATUS NOT 00 OR 04 FOR	ESCR3980
0401		*			INTERNAL DEVICE	* ESCR3990
0402	0726 47F0086C	BC	15,GRIO		ESCR4000	
0403	072A 47F0072A	BC	15,*	RECOVERY SWITCH	ESCR4010	
0404	072E A900072E	HPRA	HPR	*	AN INT SHOULD NOT GIVE CONTROL TO	ESCR4020
0405	0732 47F0072E	BC	15,HPRA		LOC TAGGED INT FROM SUCH AN ADDRESS.	ESCR4030
0406	0736 0532	YXIO	DC	Y(XI0-12)		ESCR4040
0407	0738 054A		DC	Y(XI0+12)	INT SHOULD NOT BE FROM THIS XI0F.	ESCR4050
0408		*			PRINT UNT AND RETURN TO THIS POINT.	ESCR4060
0409	073A 0552	DC	Y(LOOP+4)		ESCR4070	
0410	073C D2010914094E	IWP	MVC	PEXT+2(2),P+PR=2	RESTORE PRINTER EXIT	ESCR4080
0411	0742 D201078C0028		MVC	IR12(2),X'28'	HOLD PM IR12	ESCR4090
0412	0748 D20306720778		MVC	EXI0-8(4),ISW1		ESCR4100
0413	074E 47F0061C		BC	15,NPHI+6		ESCR4110
0414	0752 D2030672077C		MVC	EXI0-8(4),ISW1+4		ESCR4120
0415	0758 A840078A		LPSC	IR12-2,X'40'	SET PM, RETURN TO NORMAL PRINT EXIT	ESCR4130
0416	075C 95001000	PXHI	CLI	0(1),X'80'		ESCR4140
0417	0760 4780060C		BC	8,PRIU		ESCR4150
0418	0764 D20109140780		MVC	PEXT+2(2),YPRI	PRINTER IS IN USE. XI0F REJ. CASE	ESCR4160
0419	076A 47F008EA		BC	15,PRNT+4		ESCR4170
0420	076E D20100400260	R401	MVC	X'40'(2),FF	CLEAR 40, 41 SET BY UNSOLICITED INT.	ESCR4180

0421	0774 47F0066E	BC	15,EXIO-12	ESCR4190
0422	0778 47F00752	ISW1	BC 15,IWP+22	ESCR4200
0423	077C 47000672	BC	0,EXIO-8	ESCR4210
0424	0780 073C	YPRI	DC Y(IWP)	ESCR4220
0425	0762 08FA	DC	Y(PRNT+20)	ESCR4230
0426	0784 08FE	YPR1	DC Y(PRNT+24)	ESCR4240
0427	0786 0916	DC	Y(P*00-4)	ESCR4250
0428	0788 0942	DC	Y(CPAR)	ESCR4260
0429	078A 0000	DC	X'0000'	ESCR4270
0430	078C 0000	IR12	DC X'0000'	ESCR4280
0431		*		ESCR4290
0432		**	CODING TO OBTAIN SENSE AND MONITOR SENSE INFORMATION	** ESCR4300
0433	078E A84008D0	LPSC	PSC4,X'40'	SET PM - ENTER IN IO DUE TO ERROR
0434	0792 47F005EE	BC	15,UINT	PM NOT SET OR UNSOLICITED INTERRUPT
0435	0796 47F00796	BC	15,*	RECOVER SWITCH
0436	079A 40000242	GSW	STH 0,IR8	GET SENSE WORDS
0437	079E 92040541	MVI	XIO+3,X'04'	
0438	07A2 D20300700244	MXS	MVC X'70'(4),BCW4	SET NORMAL SENSE COMMAND UP - MX
0439	07A8 D2010078024C	MVC	X'70'(2),CCW4	SET NORMAL SENSE COMMAND - SEL
0440	07AE 4580052E	BAL	0,XIO-16	
0441	07b2 D2000260053F	MVC	MSNS(1),XIO+1	STORE CURRENT DA
0442	07B6 94E0026D	NI	MSNS,X'E0'	ERASE DEVICE NUMBER
0443	07BC 9560026D	CLI	MSNS,X'60'	MAGNETIC TAPES ON SELECTOR CHANNEL -
0444	07C0 478007D0	BC	0,GMS+4	DA EQUAL 60 - 6F
0445	07C4 95E0026D	CLI	MSNS,X'E0'	MAGNETIC TAPES ON CHANNEL
0446	07C8 478007D0	BC	0,GMS+4	DA EQUAL E0 - EF
0447	07CC 95C0026D	CLI	MSNS,X'C0'	MAGNETIC TAPES ON MX CHANNEL -
0448	07D0 47800B96	BC	0,E46C	
0449	07D4 47F0082C	GMS	BC 15,PRSW-4	
0450	07D8 92000A2F	MVI	SSBE+1,0	SET SENSE BYTE-BIT-EDIT SWITCH
0451	07DC D20005410258	MVC	XIO+3(1),CW5	SET MONITOR MODE COMMAND
0452	07E2 D2010078024C	MVC	X'70'(2),CCW4	
0453	07E8 4580052E	BAL	0,XIO-16	
0454	07EC 92040541	MVI	XIO+3,X'04'	SET SENSE COMMAND
0455	07F0 D20100780256	MVC	X'70'(2),CCW5	SET MONITOR SENSE COMMAND UP - SEL

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0456	07F6 D20308700248	MVC	X'70'(4),BCW5	SET MONITOR SENSE COMMAND UP - MX	ESCR4540
0457	07FC 4560052E	BAL	8,XIO-16		ESCR4550
0458	0800 47000800	SELS	BC 0,*	DISPLAY SENSE INFORMATION SWITCH	ESCR4560
0459	0804 D2000541024E	MVC	XIO+3(1),CW4	SET RESET MONITOR MODE COMMAND	ESCR4570
0460	080A D2010070024C	MVC	X'78'(2),CCW4		ESCR4580
0461	0810 4580052E	BAL	8,XIO-16		ESCR4590
0462	0814 91100205	TM	OPT,X'10'	SIMULATE SET?	ESCR4600
0463	0818 4780082C	BC	8,PRSW-4		ESCR4610
0464	081C D201031E0C8A	RSIM	MVC SIMU+16(2),ARSM		ESCR4620
0465	0822 47F0030E	BC	15,SIMU		ESCR4630
0466	0826 D201031E04BA	MVC	SIMU+16(2),MX1-2		ESCR4640
0467	082C 48800242	LH	8,IR8	RESUME TEST	ESCR4650
0468	0830 47000A00	PRSW	BC 0,EGS+24		ESCR4660
0469	0834 47F00800	BC	15,0(0)		ESCR4670
0470	0838 92F00435	RCVY	MVI HPR1+9,X'F0'	SET OPT - BIT 4 SWITCH SEL	ESCR4680
0471	083C 92F00521	MVI	XIOF+11,X'F0'		ESCR4690
0472	0840 92F009C1	MVI	ECC-25,X'F0'	EDIT CW1 ONLY	ESCR4700
0473	0844 92F00811	MVI	EMX+23,X'F0'	EDIT BCW1 ONLY	ESCR4710
0474	0848 47F00390	BC	15,STRT-4		ESCR4720
0475		**		GENERAL RECOVERY PROCEDURE - PROCESSOR MODE	ESCR4730
0476	084C 498008BC	GRPM	CH 8,PSC1+2		ESCR4740
0477	0850 4700088C	BC	0,RSIC	REISSUE SENSE INFORMATION COMMAND	ESCR4750
0478	0854 92F00290	MVI	SPSP+1,X'F0'		ESCR4760
0479	0858 91040205	TM	OPT,4	ERROR PRINT OPTION?	ESCR4770
0480	085C 47100950	BC	1,P*PR	PRINT ERROR	ESCR4780
0481	0860 91080205	TM	OPT,X'00'	OPT - BIT 4	ESCR4790
0482	0864 47100896	BC	1,ERCY-24		ESCR4800
0483	0868 47F005E0	BC	15,SPM	RESUME PROCESSOR MODE	ESCR4810
0484		**		GENERAL RECOVERY PROCEDURE - INPUT OUTPUT MODE	ESCR4820
0485	086C 498008BC	GRI0	CH 8,PSC1+2		ESCR4830
0486	0870 4720088C	BC	2,RSIC	REISSUE SENSE INFORMATION COMMAND	ESCR4840
0487	0874 92F002A0	MVI	SPSI+1,X'F0'		ESCR4850
0488	0878 91040205	TM	OPT,4	ERROR PRINT OPTION?	ESCR4860
0489	087C 47100950	BC	1,P*PR	PRINT ERROR	ESCR4870
0490	0880 91080205	TM	OPT,X'00'		ESCR4880

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0491	0884 471088A6	BC	1,ERCY-8		ESCR4890
0492	0888 47F088B2	BC	15,RIOM	RESUME IO MODE	ESCR4900
0493	088C AB808894	RSIC	SH 8,D16		ESCR4910
0494	0890 47F08800		BC 15,0(,8)	REISSUE SENSE INFORMATION COMMAND	ESCR4920
0495	0894 0010	D16	DC X'0010'		ESCR4930
0496	0896 95030510		CLI XI0F+5,3	IF C2 OR C3 IN ERROR, DO NOT SET	ESCR4940
0497	089A 472005E0		BC 2,SPM	OPT BIT 4 SWITCH	ESCR4950
0498	089E 920C08B5		MVI RIOM+3,X'0C'	SET RETURN TO GO TO COMMAND 2 - PM	ESCR4960
0499	08A2 47F005E0		BC 15,SPM		ESCR4970
0500	08A6 95030510		CLI XI0F+5,3	IF C2 OR C3 IN ERROR, DO NOT SET	ESCR4980
0501	08AA 47208800		BC 2,0(,8)	OPT BIT 4 SWITCH	ESCR4990
0502	08AE 920C08B5	ERCY	MVI RIOM+3,X'0C'	SET RETURN TO GO TO COMMAND 2 - IO	ESCR5000
0503	08B2 47F08800	RIOM	BC 15,0(,8)		ESCR5010
0504	08B6 08AE	RIO	DC Y(ERCY)		ESCR5020
0505	08B8 08A6	RPM	DC Y(ERCY-8)		ESCR5030
0506	08BA 0000	PSC1	DC X'0000'		ESCR5040
0507	08BC 0556		DC Y(INT)		ESCR5050
0508	08BE 0205	LIM1	DC Y(C123+3)		ESCR5060
0509	08C0 0202		DC Y(C123)		ESCR5070
0510	08C2 0000	PSC2	DC X'0000'		ESCR5080
0511	08C4 054E		DC Y(LOOP)		ESCR5090
0512	08C6 E0000CE0	IS	DC X'E0000CE0'	INTERRUPT STATUS	ESCR5100
0513	08CA 0000	DS	DC X'0000'		ESCR5110
0514	08CC 0000	PSC3	DC X'0000'	SET PM AND JUMP TO WHATEVER IR 8	ESCR5120
0515	08CE 08B2		DC Y(RIOM)	INDICATES	ESCR5130
0516	08D0 0000	PSC4	DC X'0000'	SET UP FOR SENSE INFORMATION	ESCR5140
0517	08D2 079A		DC Y(GSW)		ESCR5150
0518	08D4 0000	PSC5	DC X'0000'		ESCR5160
0519	08D6 0390		DC Y(STRY-12)		ESCR5170
0520	08D8 0000	PSC6	DC X'0000'		ESCR5180
0521	08DA 05EE		DC Y(UINT)		ESCR5190
0522	08DC 47000692	IOC	BC 0,TIO1		ESCR5200
0523	08E0 029A	YCP	DC Y(SPSP)		ESCR5210
0524	08E2 02AA		DC Y(SPSP)		ESCR5220
0525	08E4 01F9	LDA	DC Y(TM1)		ESCR5230

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#561	0942	92800080	CPAR	MVI	X'80',0	CLEAR PRINTER AREA	ESCR5590
#562	0946	028200010080		MVC	X'81'(131),X'80'		ESCR5600
#563	094C	47F0C000		BC	15,0(12)		ESCR5610
#564	0950	47000962	P*PR	BC	0,#+18		ESCR5620
#565	0954	0283000000D2		MVC	X'80'(132),PHD1		ESCR5630
#566	095A	45C000E6		BAL	12,PRNT		ESCR5640
#567	095E	92F00951		MVI	*-13,X'F0'		ESCR5650
#568	0962	45C00942		BAL	12,CPAR		ESCR5660
#569	0966	48E00C70		LH	14,P*T	FORMAT 1	ESCR5670
#570	096A	95600AFF		CLI	EMX+5,X'60'	UNISERVO 6-C'S ARE BEING USED	ESCR5680
#571	096E	47800AE6		BC	8,E6CD		ESCR5690
#572	0972	91800205		TM	OPT,X'80'	EDIT RECORDING DENSITY	ESCR5700
#573	0976	47100AF0		BC	1,EDD		ESCR5710
#574	097A	0204000850C5D		MVC	X'85'(5),DEN+7	PHASE	ESCR5720
#575	0980	F3840008E053E	EDI	UNPK	X'8E'(9),X'10(5)	EDIT INSTRUCTION	ESCR5730
#576	0986	0C070008EE000		TR	X'8E'(8),0(14)		ESCR5740
#577	098C	92400096		MVI	X'96',X'40'		ESCR5750
#578	0990	45C000B6E		BAL	12,EDS	EDIT DEVICE STATUS	ESCR5760
#579	0994	9180053F		TM	X'10+1,X'80'	MX OR SEL	ESCR5770
#580	0998	47100AFA		BC	1,EMX		ESCR5780
#581	099C	9120053F		TM	X'10+1,X'20'		ESCR5790
#582	09A0	47800AFA		BC	8,EMX		ESCR5800
#583	09A4	F3E700A50070		UNPK	X'A5'(15),X'78'(8)	EDIT 78-7F	ESCR5810
#584	09AA	F3210003007F		UNPK	X'B3'(3),X'7F'(2)		ESCR5820
#585	09B0	0C0F00A5E000		TR	X'A5'(16),0(14)		ESCR5830
#586	09B6	92400005		MVI	X'B5',X'40'		ESCR5840
#587	09BA	0501051A0C62		CLC	X'10F+4(2),C1AD		ESCR5850
#588	09C0	47800046		BC	8,ESC1		ESCR5860
#589	09C4	0501051A0C64		CLC	X'10F+4(2),C2AD		ESCR5870
#590	09CA	47800056		BC	8,ESC2		ESCR5880
#591	09CE	F3E7000800220		UNPK	X'B6'(15),CW3(8)	EDIT SELECTOR COMMAND WORD 3	ESCR5890
#592	09D4	F321000C4022F		UNPK	X'C4'(3),CW3+7(2)		ESCR5900
#593	09DA	0C0F00080E000	ECC	TR	X'B6'(16),0(14)		ESCR5910
#594	09E0	9240000C6		MVI	X'C6',X'40'		ESCR5920
#595	09E4	91100205		TM	OPT,X'10'	EDIT SIMULATE	ESCR5930

0596 09E8 47100866
 0597 09EC 92D500F0
 0598 09F8 9503053F
 0599 09F4 47C00ADE
 0600 09F8 92F00831
 0601 09FC 91200205
 0602 0A00 4710079A
 0603 0A04 47F0078E
 0604 0A08 48E00C78
 0605 0A0C 92000831
 0606 0A10 F3A500D90268
 0607 0A16 F3A500E4026D
 0608 0A1C DC1400D9E008
 0609 0A22 924000E3
 0610 0A26 924000EE
 0611 0A2A 45C008E6
 0612 0A2E 47F00A82
 0613 0A32 48D00246
 0614 0A36 48E00956
 0615 0A3A 48F00E1E
 0616 0A3E 45C00942
 0617 0A42 D2000A490EC9
 0618 0A48 9180D000
 0619 0A4C 47100AA8
 0620 0A50 A6810A46
 0621 0A54 AAF00244
 0622 0A58 95010A49
 0623 0A5C 47800A64
 0624 0A60 47F00A42
 0625 0A64 AAD00272
 0626 0A68 49D00ED4
 0627 0A6C 47800A7A
 0628 0A70 D2010A460ED2
 0629 0A76 47F00A42
 0630 0A7A 92F00A2F

EGS

SSBE

TMI

BC 1,ESY
 MVI X'F0',X'D5'
 CLI XI0+1,3
 BC 12,SIDR
 MVI PRSW+1,X'F0'
 TM OPT,X'20'
 BC 1,GSW
 BC 15,GSW-12
 LH 14,P*T
 MVI PRSW+1,0
 UNPK X'D9'(11),NSNS(6)
 UNPK X'E4'(11),MSNS(6)
 TR X'D9'(21),0(14)
 MVI X'E3',X'40'
 MVI X'EE',X'40'
 BAL 12,PRNT
 BC 15,BSMD-38
 LH 13,BCW4+2
 LH 14,P*PR+6
 LH 15,YS0
 BAL 12,CPAR
 MVC TMI+1(1),TMT
 TM 0(13),X'80'
 BC 1,BSMD
 AI TMI-2,1
 AH 15,BCW4
 CLI TMI+1,X'01'
 BC 8,**8
 BC 15,TMI-6
 AH 13,01
 CH 13,LNS
 BC 8,**14
 MVC TMI-2(2),YTMT
 BC 15,TMI-6
 MVI SSBE+1,X'F0'

N - SIMULATION NOT SET
 GET SENSE INFORMATION?
 IO OR PM
 EDIT NORMAL SENSE
 EDIT MONITOR SENSE
 SENSE BYTE-BIT-EDIT SWITCH
 BIT N SET. STORE ASSOCIATED MESSAGE
 8 BITS OF THIS BYTE TESTED?
 TEST NEXT BIT
 10 BYTES OF SENSE TESTED?
 PRINT STORED MESSAGES
 RESET BIT TABLE
 TEST BIT 0 OF NEXT SENSE BYTE
 RESET SENSE BYTE-BIT-EDIT SWITCH

ESCR5940
 ESCR5950
 ESCR5960
 ESCR5970
 ESCR5980
 ESCR5990
 ESCR6000
 ESCR6010
 ESCR6020
 ESCR6030
 ESCR6040
 ESCR6050
 ESCR6060
 ESCR6070
 ESCR6080
 ESCR6090
 ESCR6100
 ESCR6110
 ESCR6120
 ESCR6130
 ESCR6140
 ESCR6150
 ESCR6160
 ESCR6170
 ESCR6180
 ESCR6190
 ESCR6200
 ESCR6210
 ESCR6220
 ESCR6230
 ESCR6240
 ESCR6250
 ESCR6260
 ESCR6270
 ESCR6280

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#631	0A7E 45C008E6
#632	0A82 45C00942
#633	0A86 45C008E6
#634	0A8A D2010A400ED2
#635	0A90 9200029B
#636	0A94 920002AB
#637	0A98 91000205
#638	0A9C 471000AE
#639	0AA0 470000ACE
#640	0AA4 47F00000
#641	0AA8 D204E000F000
#642	0AAE AAE00244
#643	0AB2 49E00ED6
#644	0AB6 470000ABE
#645	0ABA 47F00A50
#646	0ABE 45C008E6
#647	0AC2 45C00942
#648	0AC6 48E00956
#649	0ACA 47F00A50
#650	0ACE 91200205
#651	0AD2 92000AA1
#652	0AD6 47100000
#653	0ADA 47F005E0
#654	0ADE 92F00AA1
#655	0AE2 47F00A7E
#656	0AE6 D20300850C56
#657	0AEC 47F00900
#658	0AF0 D20600850C56
#659	0AF6 47F00900
#660	0AFA F38400C70070
#661	0B00 DC0700C7E000
#662	0B06 924000CF
#663	0B0A D501051A0C62
#664	0B10 47000032
#665	0B14 D501051A0C64

BSMD

IRCY

SIDR

E6CD

EDD

EMX

BAL	12,PRNT	PRINT MESSAGES
BAL	12,CPAR	
BAL	12,PRNT	
MVC	TMI-2(2),YTMT	
MVI	SPSP+1,0	
MVI	SPSI+1,0	
TM	OPT,X'00'	
BC	1,ERCY	
BC	0,IRCY	
BC	15,0(,0)	RESUME
MVC	0(5,14),0(15)	
AH	14,BCW4	INCR. PRINTER AREA
CH	14,LPA	ALL PRINTER AREA FILLED?
BC	0,++0	PRINT
BC	15,TMI+0	GET REMAINING MESSAGES
BAL	12,PRNT	
BAL	12,CPAR	
LH	14,P*PR+6	RESET IR14
BC	15,TMI+0	PM OR IO?
TM	OPT,X'20'	
MVI	BSMD-7,0	
BC	1,0(,0)	
BC	15,SPM	
MVI	BSMD-7,X'F0'	SET INTERNAL DEVICE RECOVERY
BC	15,BSMD-42	
MVC	X'85'(4),DEN	
BC	15,EDI	
MVC	X'85'(7),DEN	NRZI
BC	15,EDI	
UNPK	X'C7'(9),X'70'(5)	EDIT TERMINATION BCW
TR	X'C7'(8),0(14)	
MVI	X'CF',X'40'	
CLC	XIOF+4(2),C1AD	
BC	0,EMC1	
CLC	XIOF+4(2),C2AD	

ESCR6290
ESCR6300
ESCR6310
ESCR6320
ESCR6330
ESCR6340
ESCR6350
ESCR6360
ESCR6370
ESCR6380
ESCR6390
ESCR6400
ESCR6410
ESCR6420
ESCR6430
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ESCR6620
ESCR6630

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#666	081A 4780083C	BC	8,EMC2		ESCR6640
#667	081E F38400D0020E	UNPK	X'D0'(9),BCW3(5)		ESCR6650
#668	0824 DC0700D0E000	TR	X'D0'(8),0(14)		ESCR6660
#669	082A 924000D0	MVI	X'D0',X'40'		ESCR6670
#670	082E 47F009E4	BC	15,ECC+10		ESCR6680
#671	0832 F38400D0020E	EMC1	UNPK X'D0'(9),BCW1(5)		ESCR6690
#672	0838 47F00824	BC	15,EMC1-14		ESCR6700
#673	083C F38400D0020A	EMC2	UNPK X'D0'(9),BCW2(5)		ESCR6710
#674	0842 47F00824	BC	15,EMC1-14		ESCR6720
#675	0846 F3E700B00210	ESC1	UNPK X'B6'(15),CW1(8)	EDIT SELECTOR COMMAND WORD1	ESCR6730
#676	084C F32100C4021F	UNPK	X'C4'(3),CW1+7(2)		ESCR6740
#677	0852 47F009DA	BC	15,ECC		ESCR6750
#678	0856 F3E700B00220	ESC2	UNPK X'B6'(15),CW2(8)	EDIT SELECTOR COMMAND WORD 2	ESCR6760
#679	085C F32100C40227	UNPK	X'C4'(3),CW2+7(2)		ESCR6770
#680	0862 47F009DA	BC	15,ECC		ESCR6780
#681	0866 92E000F0	ESY	MVI X'F0',X'E0'	Y - SIMULATION IS SET	ESCR6790
#682	086A 47F009F0	BC	15,EGS		ESCR6800
#683	086E 48E00C78	EDS	LH 14,P+T		ESCR6810
#684	0872 F38400990040	UNPK	X'99'(9),X'40'(5)	EDIT 40-43	ESCR6820
#685	0878 DC070099E000	TR	X'99'(8),0(14)		ESCR6830
#686	087E 924000A1	MVI	X'A1',X'40'		ESCR6840
#687	0882 F32100A200CA	UNPK	X'A2'(3),DS(2)	EDIT DS	ESCR6850
#688	0888 DC0100A2E000	TR	X'A2'(2),0(14)		ESCR6860
#689	088E 924000A4	MVI	X'A4',X'40'		ESCR6870
#690	0892 47F0C000	BC	15,0(12)		ESCR6880
#691	0896 91800205	E46C	TM OPT,X'80'	NRZI?	ESCR6890
#692	089A 478007D4	BC	8,GMS		ESCR6900
#693	089E D2130D650E93	MVC	M0+15(20),N6CE		ESCR6910
#694	08A4 D2040DAB0EA7	MVC	M0+85(5),N6CE+20		ESCR6920
#695	08AA D2040DBF0DB5	MVC	M0+105(5),M0+95		ESCR6930
#696	08B0 D2040DB50EAC	MVC	M0+95(5),N6CE+25		ESCR6940
#697	08B6 D2270DC40E3E	MVC	M0+110(40),NESI+30		ESCR6950
#698	08BC D2040DEC0E39	MVC	M0+150(5),NESI+25		ESCR6960
#699	08C2 D2270DF10E6B	MVC	M0+155(40),NESI+75		ESCR6970
#700	08C8 D2040E190E66	MVC	YS0-5(5),NESI+70		ESCR6980

0701	#BCE 47F007D8		BC	15:GMS+4		ESCR6990
0702	#BU2 C5E2C3D940C4C5D5E2C9E3E840C9D5E2	PHD1	DC	C'ESCR DENSITY INS'	PRINT HEADER 1	ESCR7000
0703	#BE2 E3D9E4C3E3C9D6D540F4F0F4F1F4F2F4		DC	C'TRUCTION 4041424'		ESCR7010
0704	#BF2 F340C4E240F7F8F7F9F7C1F7C2F7C3F7		DC	C'3 DS 78797A7B7C7'		ESCR7020
0705	#C02 C4F7C5F7C640C3D6D4C4C2C1C4D9C6D3		DC	C'D7E7F COMDBADRFL'		ESCR7030
0706	#C12 C1C7C2C3D5E340E3C5D9D460C2C3E640		DC	C'AGBCNT TERM-BCW '		ESCR7040
0707	#C22 C9D5C9E360C2C3E640E2F0E2F1E2F2E2		DC	C'INIT-BCW S0S1S2S'		ESCR7050
0708	#C32 F3E2F440D4F0D4F1D4F2D4F3D4F440E2		DC	C'3S4 M0M1M2M3M4 S'		ESCR7060
0709	#C42 C9D44040404040404040404040404040		DC	C'IM		ESCR7070
0710	#C52 40404040		DC	C'		ESCR7080
0711	#C56 D5D9E9C940C3C2D7C8C1E2C5	DEN	DC	C'NRZI CBPHASE'		ESCR7090
0712	#C62 0203	C1AD	DC	Y(C123+1)		ESCR7100
0713	#C64 0204	C2AD	DC	Y(C123+2)		ESCR7110
0714	#C66 00000000	EBCW	DC	X'00000000'		ESCR7120
0715	#C6A F6C34040F74040F8F0F04040D5	SHDC	DC	C'6C 7 800 N'		ESCR7130
0716	#C78 088A	P+T	DC	Y(+2-240)		ESCR7140
0717	#C7A F0F1F2F3F4F5F6F7F8F9C1C2C3C4C5C6		DC	CL16'0123456789ABCDEF'		ESCR7150
0718	#C8A 0826	ARSM	DC	Y(RSIM+10)		ESCR7160
0719	#C8C 041A		DC	Y(SPC)		ESCR7170
0720	#C8E C3D4D9D140C9D5D9D840C2E2C3D240	S0	DC	C'CMRJ INRQ BSCK ' SENSE BYTE ZERO		ESCR7180
0721	#C9D C5D8C3D240C4C1C3D240D6E5D9D540		DC	C'EQCK DACK OVRN '		ESCR7190
0722	#CAC E6C4C3E940E2C2F0F740		DC	C'WDCZ SB07 '		ESCR7200
0723	#CB6 D5D6C9E240E3E4E2C140E3E4E2C240		DC	C'NOIS TUSA TUSB ' SENSE BYTE ONE		ESCR7210
0724	#CC5 F7E3D9D240C2D6E34040C5D6E34040		DC	C'7TRK BOT EOT '		ESCR7220
0725	#CD4 E3E4C6D740E3E4C9C340		DC	C'TUFP TUIC '		ESCR7230
0726	#CDE E3C9C5F040E3C9C5F140E3C9C5F240		DC	C'TIE0 TIE1 TIE2 ' SENSE BYTE TWO		ESCR7240
0727	#CED E3C9C5F340E3C9C5F440E3C9C5F540		DC	C'TIE3 TIE4 TIE5 '		ESCR7250
0728	#CFC E3C9C5F640E3C9C5F740		DC	C'TIE6 TIE7 '		ESCR7260
0729	#D06 E5D9C34040D4C4E34040E2D2C5E640		DC	C'VRC MDT SKEW ' SENSE BYTE THREE		ESCR7270
0730	#D15 D7E2E3C340E2C4E34040E3E4D7C840		DC	C'PSTC SDT TUPH '		ESCR7280
0731	#D24 C2D2E6C440E2C2F3F740		DC	C'BKWD SB37 '		ESCR7290
0732	#D2E D9E6C1E840E3D4C6E340E2C2F4F240		DC	C'RWAY TMFT SB42 ' SENSE BYTE FOUR		ESCR7300
0733	#D3D E2C2F4F340E2C2F4F440E2E3C1D340		DC	C'SB43 SB44 STAL '		ESCR7310
0734	#D4C E3D7C6E340E2C2F4F740		DC	C'TPFT SB47 '		ESCR7320
0735	#D56 D7C3F0F040D7C3F0F140D7C3F0F240	M0	DC	* C'PC00 PC01 PC02 ' MONITOR SENSE BYTE ZERO		ESCR7330

0736 0D65 F6C1E54040F7C1E54040F8C1E54040
 0737 0D74 D9C5E24040E2C9D44040
 0738 0D7E E6D9C9E340D9C5C1C440C2D2E6C440
 0739 0D8D E2D7C1C340C6C9D3C540D9C5E64040
 0740 0D9C E6E3D44040C5D9C1E240
 0741 0DA6 D7D9C5D940E2C5D5E340E3D4C44040
 0742 0DB5 D7E2E3C140C3E3D9D440D4D9D7C840
 0743 0DC4 C4E3D74040C4E3F04040
 0744 0DCE C4E3F14040C4E3F24040C4E3F34040
 0745 0DDD C4E3F44040C4E3F54040C4E3F64040
 0746 0DEC C4E3F74040D7E9C5D740
 0747 0DF6 D7E9C5F040D7E9C5F140D7E9C5F240
 0748 0E05 D7E9C5F340D7E9C5F440D7E9C5F540
 0749 0E14 D7E9C5F640D7E9C5F740
 0750 0E1E 0C8E
 0751 0E20 C4C3C3D240D9E5D9C340D3D9C34040
 0752 0E2F C3D9C34040E6E5D9C340C3D9C3D740
 0753 0E3E C3D9C3F040C3D9C3F140C3D9C3F240
 0754 0E4D C3D9C3F340C3D9C3F440C3D9C3F540
 0755 0E5C C3D9C3F640C3D9C3F740D3D9C3D740
 0756 0E6B D3D9C3F040D3D9C3F140D3D9C3F240
 0757 0E7A D3D9C3F340D3D9C3F440D3D9C3F540
 0758 0E89 D3D9C3F640D3D9C3F740
 0759 0E93 C4C5D5F040C4C5D5F140C5D7C1D940
 0760 0EA2 C4C3D6D540C5C7C1D740D3D6E6C740
 0761 0EB1 E4D5E2D6D3C9C3C9E3C5C440C9D5E3C5
 0762 0EC1 D9D9E4D7E3405C5C
 0763 0EC9 0040201000040201
 0764 0ED2 0EC9
 0765 0ED4 0272
 0766 0ED6 00F8
 0767 0ED8
 0768 0020
 0769 0020 FF
 0770 00003900034A

YS0
NESI

N6CE

EUI

TMT

YTMT

LNS

LPA

SPA

REV

DC C'6AV 7AV 8AV '
 DC C'RES SIM '
 DC C'WRIT READ BKWD ' MONITOR SENSE BYTE ONE
 DC C'SPAC FILE REW '
 DC C'WTM ERAS '
 DC C'PRER SENT TMD ' MONITOR SENSE BYTE TWO
 DC C'PSTA CTRM MRPH '
 DC C'DTP DT0 '
 DC C'DT1 DT2 DT3 ' MONITOR SENSE BYTE THREE
 DC C'DT4 DT5 DT6 '
 DC C'DT7 PZEP '
 DC C'PZE0 PZE1 PZE2 ' MONITOR SENSE BYTE FOUR
 DC C'PZE3 PZE4 PZE5 '
 DC C'PZE6 PZE7 '
 DC Y(S0)
 DC C'DCCK RVRC LRC ' NRZI EDITED SENSE INFORMATION
 DC C'CRC WVRC CRCP '
 DC C'CRC0 CRC1 CRC2 '
 DC C'CRC3 CRC4 CRC5 '
 DC C'CRC6 CRC7 LRCP '
 DC C'LRC0 LRC1 LRC2 '
 DC C'LRC3 LRC4 LRC5 '
 DC C'LRC6 LRC7 '
 DC C'DEN0 DEN1 EPAR ' NRZI 6C EDITED SENSE INFORMATION
 DC C'DCON EGAP LOWG '
 DC C'UNSOLICITED INTE'
 DC C'RRUPT **'
 DC X'0040201000040201' TEST MASK TABLE
 DC Y(TMT)
 DC Y(NSNS+10)
 DC X'00F8'
 DS ICL132
 ORG X'20' REVISION LEVEL TO 0020
 DC X'FF'
 END CKPC

ESCR7340
 ESCR7350
 ESCR7360
 ESCR7370
 ESCR7380
 ESCR7390
 ESCR7400
 ESCR7410
 ESCR7420
 ESCR7430
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 ESCR7670
 ESCR7680